

Physics 271 Electricity & Magnetism

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Review Notes

I) Electrostatics

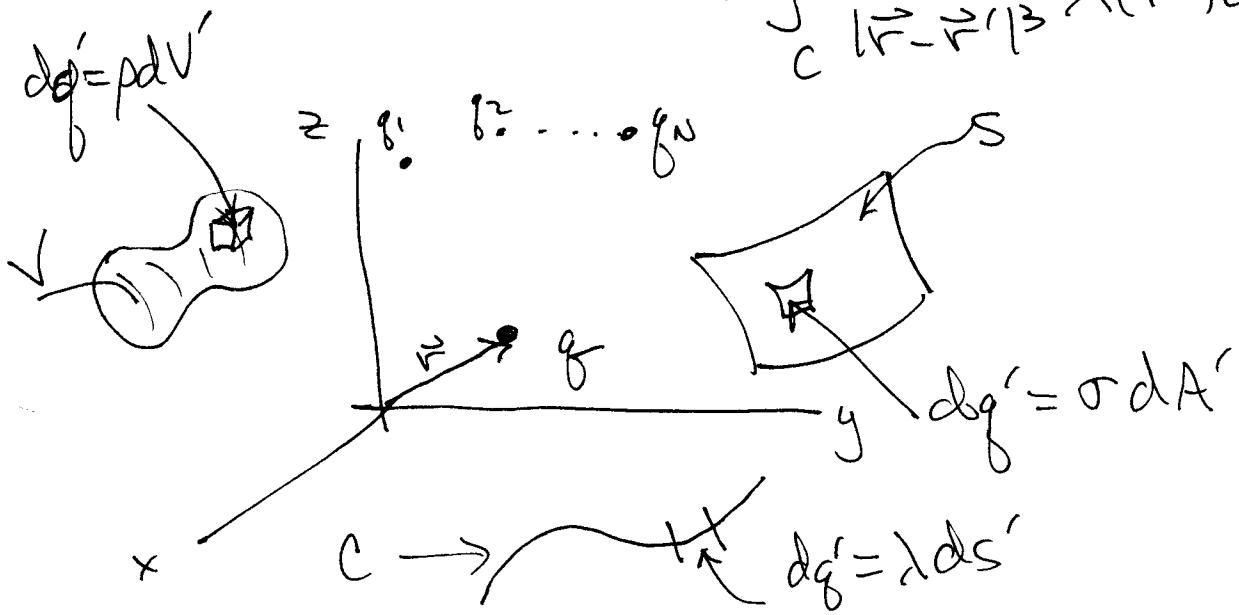
A) Coulomb's Law: Experimentally observed force between charges

$$\vec{F}_q = \frac{q}{4\pi\epsilon_0} \left\{ \sum_{i=1}^N \frac{q_i}{|\vec{r} - \vec{r}_i|^2} \frac{\vec{r} - \vec{r}_i}{|\vec{r} - \vec{r}_i|} \right\}$$

$$+ \int \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \rho(\vec{r}') dV'$$

$$+ \int_S \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \sigma(\vec{r}') dA'$$

$$+ \int_C \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \lambda(\vec{r}') ds' \}$$



$$(E_0 = 8.85 \times 10^{-12} \frac{C^2}{N \cdot m^2} = 8.85 \text{ pF/m})$$

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- IA) SI units $\frac{1}{4\pi E_0} = 8.99 \times 10^9 \frac{N \cdot m^2}{C^2}$

2) Principle of superposition: Total force is vector sum of pairwise individual forces on q .

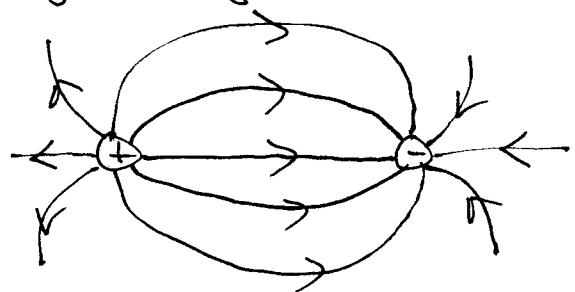
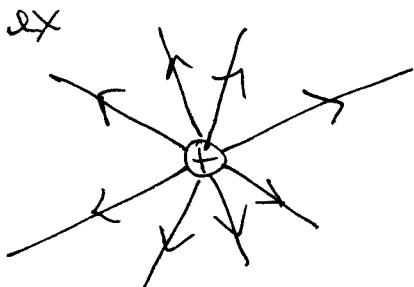
B) Electric Field: $\vec{E} = \lim_{q_0 \rightarrow 0} \frac{\vec{F}_{q_0}}{q_0}$

with q_0 a positive test charge

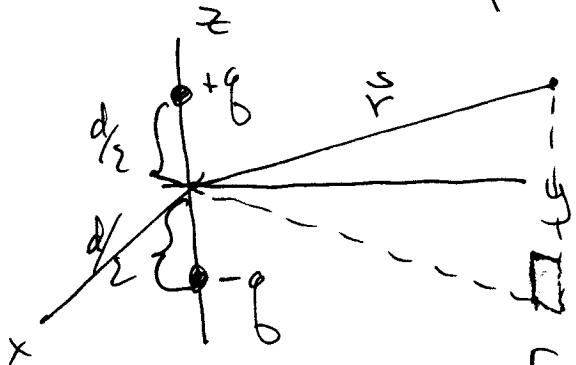
$$\begin{aligned} \vec{E}(\vec{r}) &= \frac{1}{4\pi E_0} \left\{ \sum_{i=1}^{N_1} q_i \frac{\vec{r} - \vec{r}_i}{|\vec{r} - \vec{r}_i|^3} \right. \\ &\quad + \int \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \rho(\vec{r}') dV' \\ &\quad + \int_S \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \sigma(\vec{r}') dA' \\ &\quad \left. + \int_C \frac{\vec{r} - \vec{s}'}{|\vec{r} - \vec{s}'|^3} \lambda(\vec{s}') ds' \right\} \end{aligned}$$

i) As did the force, \vec{E} obeys the principle of superposition, the total electric field is the vector sum of the individual charges' electric fields

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 IB2) Lines of Force (= field lines): a) end & start on charges, b) tangent to line is direction of \vec{E} (as a positive test charge would move), c) ~~the~~ of lines / unit cross-sectional area is proportional to magnitude of \vec{E} in that region, d) lines are continuous and do not cross in charge free regions of space



3) Electric Dipole:



$$\vec{P} = qd\hat{k}, \vec{E} \text{ given by } \vec{P}$$

$$\vec{E}(r) = \frac{q}{4\pi\epsilon_0} \times$$

$$x \left[\frac{\vec{r} - \frac{d}{2}\hat{k}}{(x^2 + y^2 + (z - \frac{d}{2})^2)^{3/2}} - \frac{\vec{r} + \frac{d}{2}\hat{k}}{(x^2 + y^2 + (z + \frac{d}{2})^2)^{3/2}} \right]$$

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$$IB3) \Rightarrow a) \vec{E}(x,y=0,z=0) = \frac{-\vec{P}}{4\pi\epsilon_0(x^2 + (\frac{d}{2})^2)^{3/2}}$$

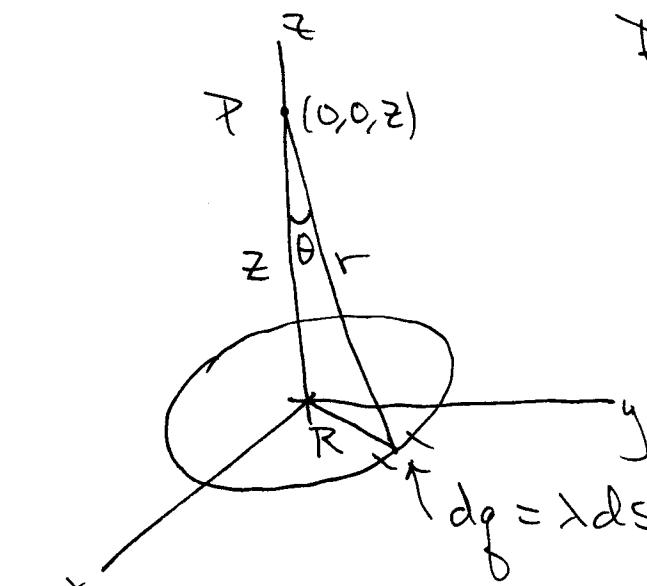
b) $x \gg d$: Taylor Expand: $\epsilon \ll 1$
 $f(\epsilon) = f(0) + \epsilon f'(0) + \frac{\epsilon^2}{2} f''(0) + \dots$

$$\vec{E}(x,y=0,z=0) \stackrel{x \gg d}{\approx} \frac{-\vec{P}}{4\pi\epsilon_0 x^3}$$

c) General Result for $r \gg d$

$$\vec{E}(r) \approx \frac{1}{4\pi\epsilon_0} \left[3 \frac{\vec{P} \circ \vec{r}}{r^5} \vec{r} - \frac{\vec{P}}{r^3} \right]$$

4) Ring of Charge:



where $\cos\theta = \frac{z}{r}$

By symmetry $E_x = E_y = 0$
at P!

$$E_z = \int_{\text{ring}} dE_z$$

$$= \frac{\lambda}{4\pi\epsilon_0} \int_{\varphi=0}^{2\pi} \frac{R d\varphi}{(z^2 + R^2)} \cos\theta$$

$$E_z = \frac{q}{4\pi\epsilon_0} \frac{z}{(z^2 + R^2)^{3/2}}$$

with $q = 2\pi R \lambda$

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- IB5) Disk of Charge :

$dq = \sigma dA$
 $= \sigma (2\pi r) dr$

Ring of Charge

$d\vec{E}(0,0,z) = \frac{dq z \hat{k}}{4\pi\epsilon_0 (z^2 + r^2)^{3/2}}$

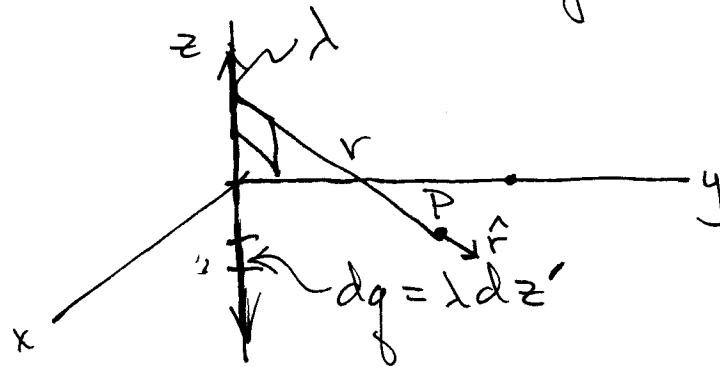
integrate $\rightarrow \vec{E}(0,0,z) = \frac{2\pi\sigma z \hat{k}}{4\pi\epsilon_0} \int_{r=0}^R \frac{r dr}{(z^2 + r^2)^{3/2}}$

$$\vec{E}(0,0,z) = \frac{\sigma}{2\epsilon_0} \left[1 - \frac{z}{\sqrt{z^2 + R^2}} \right] \hat{k} \quad (z > 0)$$

a) Close to disk $R \gg z$: $\frac{z}{\sqrt{z^2 + R^2}} = \frac{z/R}{\sqrt{1 + (\frac{z}{R})^2}} \approx 0$

$$\Rightarrow \vec{E} = \frac{\sigma}{2\epsilon_0} \hat{k}$$

b) Line of Charge : By symmetry \vec{E} is \perp to z -axis



$$\vec{E} = E \hat{r}$$

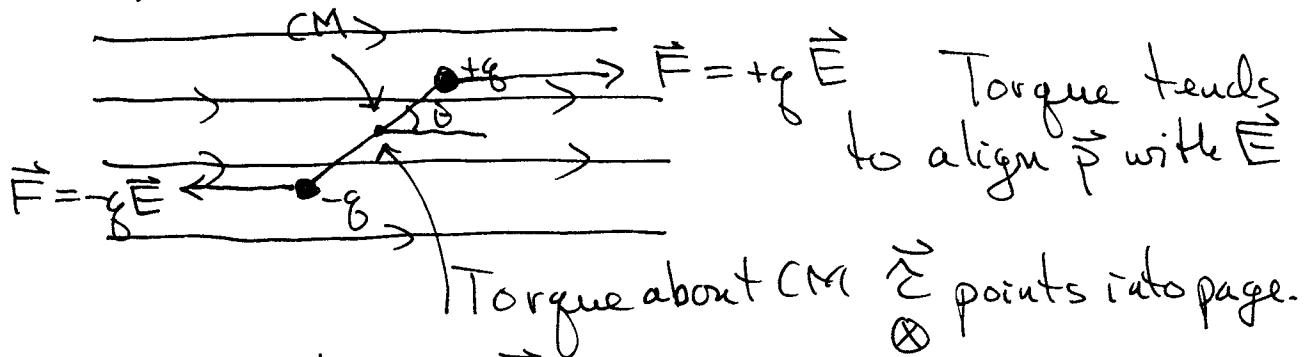
$$E = \frac{\lambda}{2\pi\epsilon_0 r}$$

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I C) Given the electric field \vec{E} at a point in space \vec{r} , The electric force of a point charge q located at \vec{r} is simply $\vec{F}_q = q \vec{E}$.

If classical, non-relativistic particle, it will then move according to Newton's 2nd Law $\vec{F}_q = m\vec{a}$.

i) Dipole in a uniform \vec{E} -field



$$\vec{\tau} = \sum_i \vec{r}_i \times \vec{F}_i$$

$$|\vec{\tau}| = \tau = F \frac{d}{2} \sin \theta + F \frac{d}{2} \sin \theta \\ = F d \sin \theta$$

$$F = q E \Rightarrow \tau = q d E \sin \theta \\ = p E \sin \theta$$

Which vectorially becomes

$$\boxed{\vec{\tau} = \vec{p} \times \vec{E}}$$

- IC 1) Work done by electric field = $W = \int_{\theta_0}^{\theta} \vec{E} \cdot d\vec{\theta} = \int_{\theta_0}^{\theta} -\vec{r} d\theta$

$W = -PE \int_{\theta_0}^{\theta} \sin\theta d\theta$

$$W = PE [\cos\theta - \cos\theta_0],$$

Change in potential energy of system

$$\Delta U = U(\theta) - U(\theta_0) = -W$$

$$= -PE [\cos\theta - \cos\theta_0]$$

Choose arbitrary reference point $\theta = \frac{\pi}{2}$ for zero of PE : $U(\frac{\pi}{2}) = 0$.

$$\Rightarrow U(\theta) = -PE \cos\theta = -\vec{p} \cdot \vec{E}$$

PE is a minimum when \vec{p} & \vec{E} align.

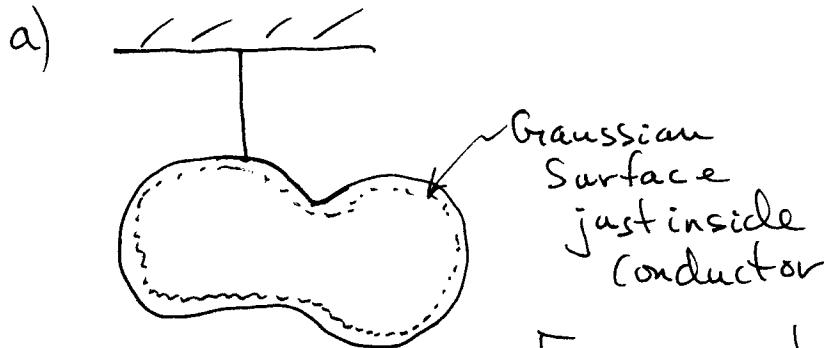
- I.D.) Gauss' Law:

$$\oint_S \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$

S = closed Gaussian surface bounding volume V
 $Q_{\text{enclosed}} = \text{all charge inside Gaussian surface}$
 i.e. in volume V .

$$\Phi_E = \oint_S \vec{E} \cdot d\vec{A} = \text{flux of } \vec{E} \text{ through } S$$

i) Isolated conductor with excess charge q



Experimental fact:

no currents in conductor $\Rightarrow \vec{E} = 0$
 inside conductor

Hence $\Phi_E = 0 = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$

\Rightarrow All q on outer surface of conductor

ID1b)

$\vec{E} \perp$ to surface
(no currents)

$$\oint_S \vec{E} \cdot d\vec{A} = \frac{Q_{\text{enclosed}}}{\epsilon_0}$$

$$E \Delta A = \frac{q}{\epsilon_0}$$

$$\Rightarrow \boxed{\vec{E} = \frac{q}{\epsilon_0} \hat{n}}$$

2) Infinite line of charge:

Cylindrical symmetry
 $\Rightarrow \vec{E} = E(r) \hat{r}$

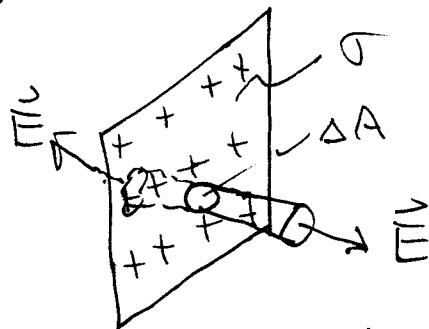
$$\oint_S \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$

$$0 + 0 + E(r) 2\pi r h = \frac{1}{\epsilon_0} \lambda h$$

$E \perp dA$ on end caps

$$\Rightarrow \boxed{E(r) = \frac{\lambda}{2\pi\epsilon_0 r}}$$

ID3) Infinite Sheet of Charge



Planar symmetry $\vec{E} \perp$ plane

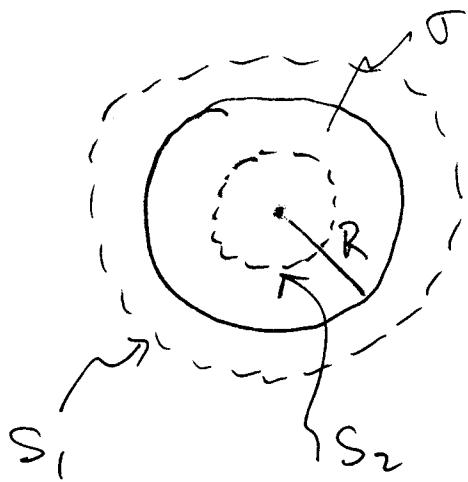
$$\oint_S \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$

$$0 + E_{\Delta A} + E_{\Delta A} = \frac{1}{\epsilon_0} \sigma \Delta A$$

↑ ↑
cylindrical side 2 end caps

$$\Rightarrow E = \frac{\sigma}{2\epsilon_0} \quad \{ \perp \text{ to sheet}$$

4) Spherical Shell of Charge



Spherical symmetry
 $\Rightarrow \vec{E} = E(r) \hat{r}$

$$i) S_1: r \geq R$$

$$\oint_{S_1} \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$

$$E(r) 4\pi r^2 = \frac{1}{\epsilon_0} 4\pi R^2 \sigma$$

$$\Rightarrow \boxed{\vec{E} = \frac{q}{4\pi\epsilon_0 r^2} \hat{r}}$$

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ID42) $S_2: r < R$ No charge is enclosed in S_2

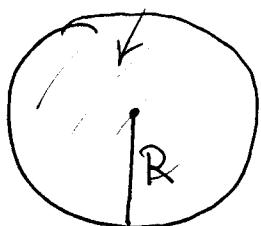
$$\oint \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} Q_{\text{enclosed}} = 0$$

$S_2 \parallel$

$$E(r) \oint_{S_2} dA = E(r) 4\pi r^2 = 0$$

$\Rightarrow \boxed{\vec{E} = 0 \text{ for } r < R}$
inside shell.

5) Spherically Symmetric Charge Distribution:



Spherical symmetry \Rightarrow

$$\vec{E} = E(r) \hat{r}$$

i) $r \geq R$ a) Add up shells $dq = 4\pi r'^2 dr' \rho$

$$E = \int_0^R \frac{1}{4\pi\epsilon_0} \frac{dq}{r^2} = \frac{\rho}{4\pi\epsilon_0 r^2} \int_0^R 4\pi r'^2 dr'$$

$$\boxed{E = \frac{q}{4\pi\epsilon_0 r^2}; r > R}$$

$q = \frac{4}{3}\pi R^3 \rho$

$= \frac{4}{3}\pi R^3 \rho$

Acts like pt. q at center
for $r \geq R$

b) Gauss' Law directly



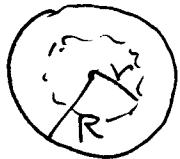
$$\oint \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$

$S \parallel$

$$= E(r) 4\pi r^2 = \frac{1}{\epsilon_0} q$$

$$\Rightarrow \boxed{E = \frac{q}{4\pi\epsilon_0 r^2}, r > R}$$

- IDS 2) $r \leq R$ Gauss's law:



$$\oint_S \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$

$$E(r) \oint_S dA = \frac{1}{\epsilon_0} \left(\frac{4}{3} \pi r^3 \rho \right)$$

$$E(r) 4\pi r^2 = \frac{1}{\epsilon_0} \left(\frac{4}{3} \pi R^3 \rho \right) \left(\frac{r^3}{R^3} \right)$$

$$\Rightarrow E(r) = \frac{q}{4\pi\epsilon_0 R^2} \left(\frac{r}{R} \right), r \leq R$$

Note: $r=R$ both expressions must be =,
and they are $E(R) = \frac{q}{4\pi\epsilon_0 R^2}$

E.) Potential Energy: Coulomb force is conservative

\Rightarrow
Work $= W_{ab} = \int_a^b \vec{F} \cdot d\vec{s}$ is path independent
to go $a \rightarrow b$

Potential Energy difference $\Delta U = U_b - U_a \equiv -W_{ab}$

$$\Delta U = U_b - U_a = - \int_a^b \vec{F} \cdot d\vec{s}$$

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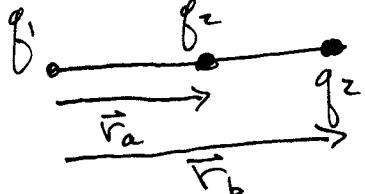
I.E) Potential Energy at a point = $U_b \equiv -W + U_a$

where U_a is an arbitrarily defined value at the reference point a. Usually choose $U_a \equiv 0$ at point a. For finite charges we choose $a = \infty$ i.e. all charges infinitely separated and $U_\infty \equiv 0$.

For $\vec{F} = q \vec{E}$ we have

$$\Delta U = U_b - U_a = -q \int_a^b \vec{E} \cdot d\vec{s}$$

i) Two point charges: q_1 fixed, q_2 moves from \vec{r}_a to \vec{r}_b



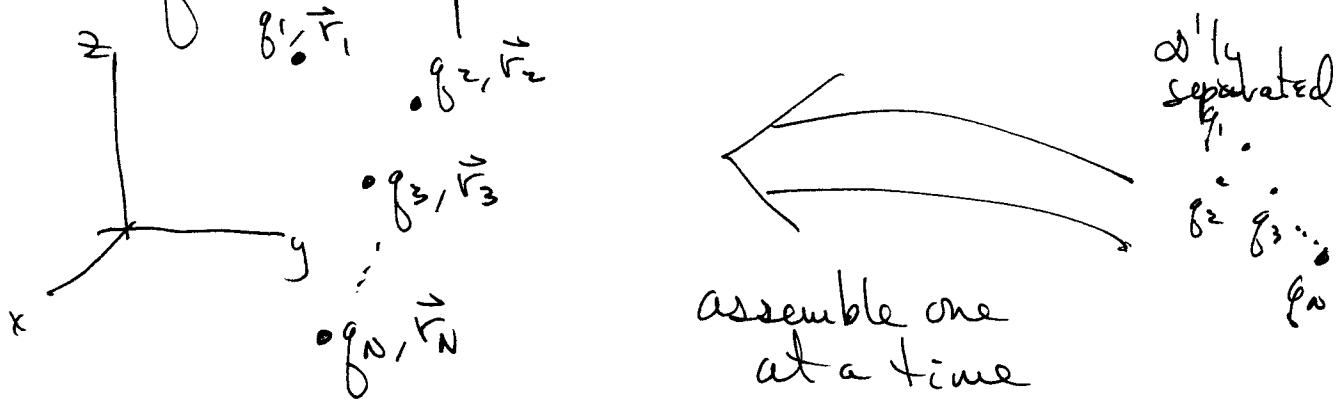
$$U_b - U_a = \frac{q_1 q_2}{4\pi\epsilon_0} \left(\frac{1}{r_b} - \frac{1}{r_a} \right)$$

let $r_a \rightarrow \infty$ and define $U_a = 0$ then

$$\Rightarrow U(r) = -\frac{q_1 q_2}{4\pi\epsilon_0 r}$$

(r = separation of q_1 & q_2)

I.E.2) System of point charges: Potential energy equals the work done by an external force to assemble the charge distribution from ∞ separation to final locations



$$U = U_1 + U_2 + \dots + U_N$$

$$= \sum_{i=1}^{N-1} U_i$$

work done to bring q_i in when q_1, \dots, q_{i-1} are already in place.

$$U = \sum_{i=1}^{N-1} \sum_{j=1}^{i-1} \frac{q_i q_j}{4\pi\epsilon_0 r_{ij}}$$

$$= \frac{1}{2} \sum_{i=1}^{N-1} q_i \left(\sum_{j=1}^{N-1} \frac{q_j}{4\pi\epsilon_0 |\vec{r}_i - \vec{r}_j|} \right)$$

$$\equiv V(\vec{r}_i)$$

= electric potential at \vec{r}_i due to other charges q_1, \dots, q_N excluding q_i

I.F.) Electric Potential: $V(\vec{r}) \equiv \lim_{q_0 \rightarrow 0} \frac{U(\vec{r})}{q_0}$ (5)

$V = PE/\text{unit charge}$

$$\boxed{\Delta V = V_b - V_a = - \int_a^b \vec{E} \cdot d\vec{s}}$$

1) SI units: 1 volt $\equiv \frac{1 \text{ Joule}}{1 \text{ Coulomb}} \Rightarrow E \text{ units} = \frac{\text{Volt}}{\text{m}} = \frac{\text{N}}{\text{C}}$

2) Move charge q between 2 points at fixed potential difference ΔV then the PE difference is

$$\Delta U = q \Delta V.$$

3) Point Charge q :

$$V_b - V_a = - \int_a^b \vec{E} \cdot d\vec{s}$$

$$= - \int_{r_a}^{r_b} \frac{q}{4\pi\epsilon_0} \frac{dr}{r^2}$$

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{\hat{r}}{r^3}$$

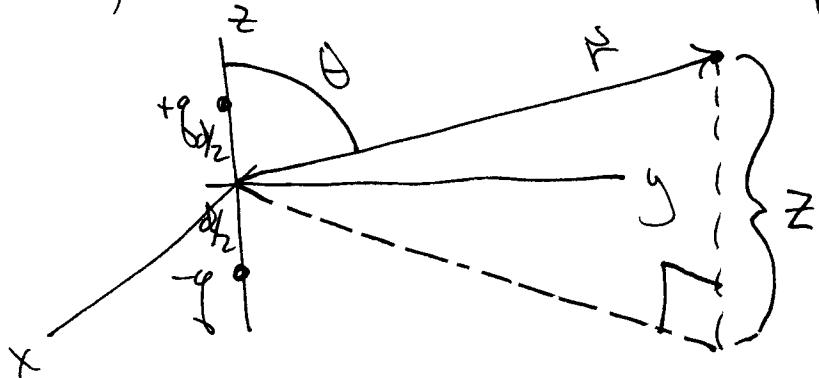
$$\boxed{V_b - V_a = \frac{q}{4\pi\epsilon_0} \left(\frac{1}{r_b} - \frac{1}{r_a} \right)}$$

Convention: $r_a = \infty$ $V_a \equiv 0$

$$\boxed{V(\vec{r}) = \frac{q}{4\pi\epsilon_0} \frac{1}{r}}$$

IF4) Principle of superposition: $V = \sum_{i=1}^N V_i = \frac{-16\pi}{4\pi\epsilon_0} \sum_{i=1}^N \frac{q_i}{r_i}$
Scalar addition of individual charge potentials.

5) Potential due to a dipole: use superposition of 2 pt. charges



$$\hat{r} \cdot \hat{k} = \cos\theta = \frac{z}{r}$$

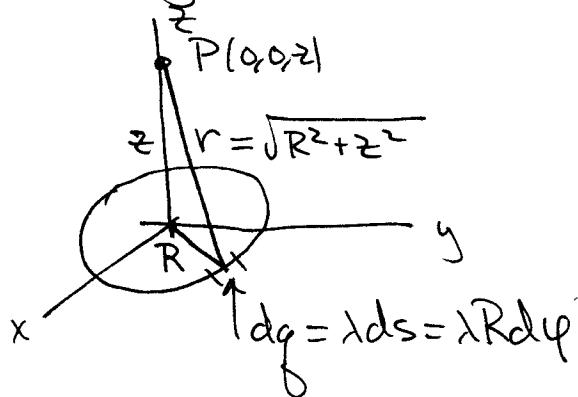
$$V = V_+ + V_- = \frac{q}{4\pi\epsilon_0} \left[\frac{1}{|\vec{r} - \frac{d}{2}\hat{k}|} - \frac{1}{|\vec{r} + \frac{d}{2}\hat{k}|} \right]$$

$$V(\vec{r}) = \frac{q}{4\pi\epsilon_0 r} \left[\frac{1}{\sqrt{1 - \frac{d}{r} \cos\theta + \frac{d^2}{4r^2}}} - \frac{1}{\sqrt{1 + \frac{d}{r} \cos\theta + \frac{d^2}{4r^2}}} \right]$$

a) $r \gg d$: $\frac{1}{\sqrt{1+\epsilon}} = 1 - \frac{1}{2}\epsilon + \dots$

$$V = \frac{\hat{p} \cdot \vec{r}}{4\pi\epsilon_0 r^3}$$

I.F.6) Ring of charge



$$\frac{q}{4\pi\epsilon_0\sqrt{R^2 + z^2}} =$$

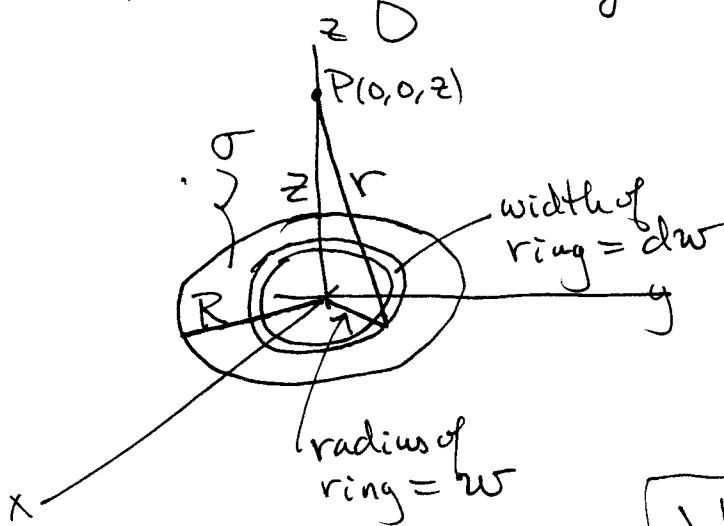
$$V(0,0,z) = \frac{1}{4\pi\epsilon_0} \int_{\text{ring}} \frac{dq}{r}$$

\uparrow
r is same around ring

$$= \frac{1}{4\pi\epsilon_0 R} \int_{\text{ring}} dq$$

$$V(0,0,z) = \frac{2\pi R \lambda}{4\pi\epsilon_0 \sqrt{R^2 + z^2}}$$

7) Disk of Charge



Ring of charge

$$dV(P) = \frac{dq}{4\pi\epsilon_0 r}$$

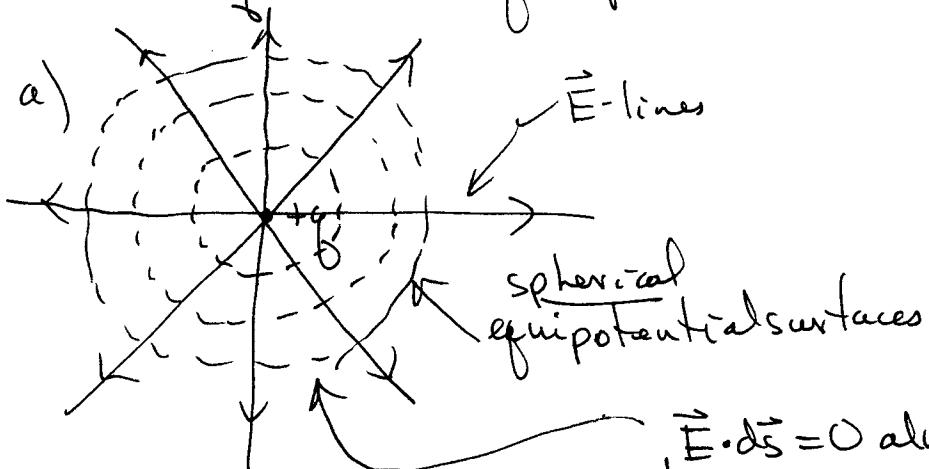
$r = \sqrt{w^2 + z^2}$

$$V(P) = \int_{w=0}^R dV(P)$$

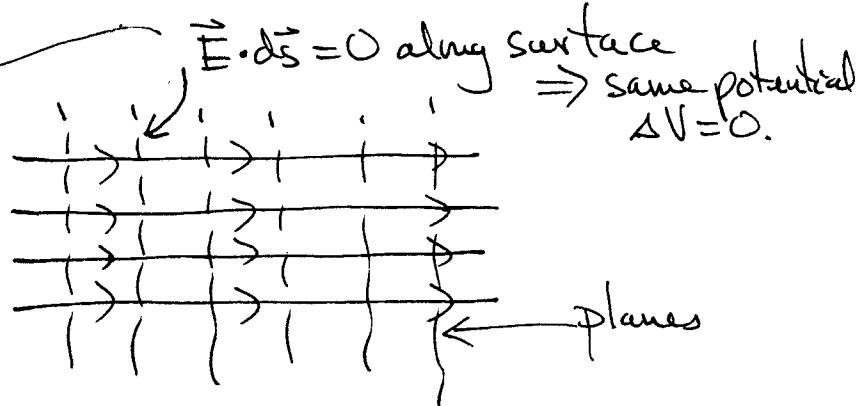
$$V(P) = \frac{\sigma}{2\epsilon_0} [\sqrt{R^2 + z^2} - z]$$

I.F. 8) Equipotential Surfaces: family of surfaces with each surface having the same electric potential.

lines of $\vec{E} \perp$ equipotential surfaces



b) Uniform \vec{E}



9) Gradient of electric potential.

$$dV = -\vec{E} \cdot d\vec{s}$$

$$\vec{\nabla} V \cdot d\vec{s}$$

$$\vec{\nabla} = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z}$$

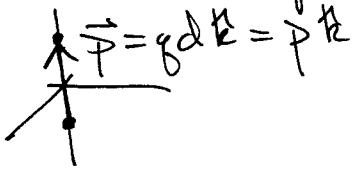
$$\vec{E} = -\vec{\nabla} V$$

$$E_x = -\frac{\partial V}{\partial x}$$

$$E_y = -\frac{\partial V}{\partial y}$$

$$E_z = -\frac{\partial V}{\partial z}$$

I.F.9a) Electric Dipole:

$$\vec{p} = qd\hat{k} = p\hat{k}$$


$$V = \frac{\vec{p} \cdot \vec{r}}{4\pi\epsilon_0 r^3}$$

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$$= \frac{p z}{4\pi\epsilon_0 (x^2 + y^2 + z^2)^{3/2}}$$

$$\vec{E} = -\vec{\nabla} V$$

$$E_x = -\frac{\partial V}{\partial x} = \frac{3pzx}{4\pi\epsilon_0 r^5}$$

$$E_y = -\frac{\partial V}{\partial y} = \frac{3pzy}{4\pi\epsilon_0 r^5}$$

$$E_z = -\frac{\partial V}{\partial z} = -\frac{p}{4\pi\epsilon_0 r^3} + \frac{3pz^2}{4\pi\epsilon_0 r^5}$$

\Rightarrow

$$\vec{E} = \frac{3(\vec{p} \cdot \vec{r}) \vec{r}}{4\pi\epsilon_0 r^5} - \frac{\vec{p}}{4\pi\epsilon_0 r^3}$$

10) All isolated conductor is an equipotential.

I G) Capacitors: two conducting plates carrying equal but opposite charge plates are equipotentials.

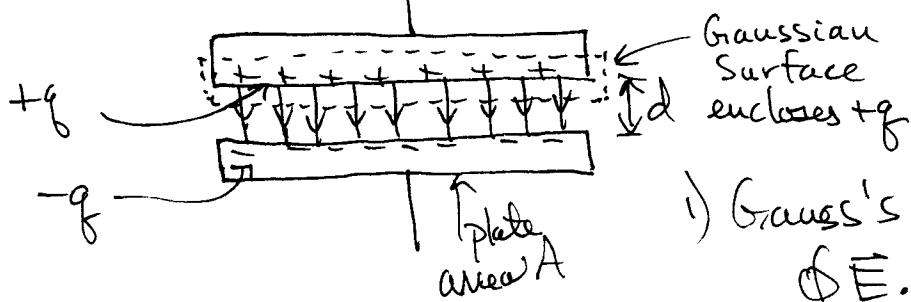
$$q = CV$$

C = capacitance of capacitor

q = magnitude of charge
 V = magnitude of Potential difference

1) SI units of capacitance 1 Farad = $\frac{1 \text{ Coulomb}}{1 \text{ Volt}}$

2) Parallel Plate Capacitor: Neglect fringing



1) Gauss's Law

$$\oint \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} q$$

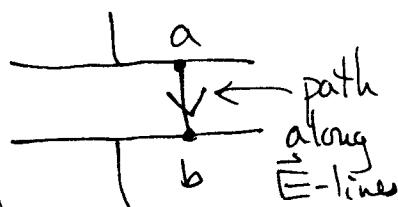
$$EA = \frac{q}{\epsilon_0}$$

$$E = \frac{q/A}{\epsilon_0} \left(\rightarrow \frac{\sigma}{\epsilon_0} \right)$$

2) Electric Potential Difference

$$-V = V_b - V_a = - \int_a^b \vec{E} \cdot d\vec{s}$$

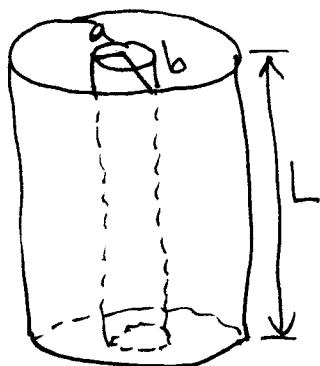
$$\Rightarrow +V = + \int_a^b \vec{E} \cdot d\vec{s} = E \int_0^d ds = Ed$$



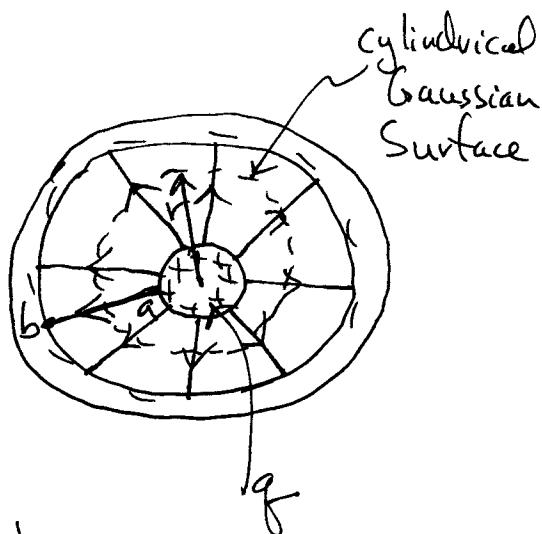
$$IG 2.2) \quad V = Ed = \left(\frac{q}{\epsilon_0 A}\right) d = \left(\frac{d}{\epsilon_0 A}\right) q = \frac{1}{C} q \quad -2-$$

$$\Rightarrow \boxed{C = \frac{\epsilon_0 A}{d}} \quad \text{II-plate Capacitor}$$

3) Cylindrical Capacitor:



$\gg b$ to ignore fringing



1) Gauss' Law $\oint_S \vec{E} \cdot d\vec{A} = \frac{q}{\epsilon_0}$

\uparrow $0+0+E(r)2\pi r L$
 end caps cylindrical
 $E \perp dA$ area at
 radius r

$$\Rightarrow E(r) = \frac{q}{2\pi\epsilon_0 r L}$$

2) Potential Difference

$$V = \int_a^b \vec{E} \cdot d\vec{s} = \frac{q}{2\pi\epsilon_0 L} \int_a^b \frac{dr}{r}$$

$$= \frac{q}{2\pi\epsilon_0 L} \ln\left(\frac{b}{a}\right)$$

IG3) \Rightarrow

$C = 2\pi \epsilon_0 \frac{L}{\ln(b/a)}$	22 (cylindrical capacitor)
--	-------------------------------

4) Spherical Capacitor: Cross-Section of sphere

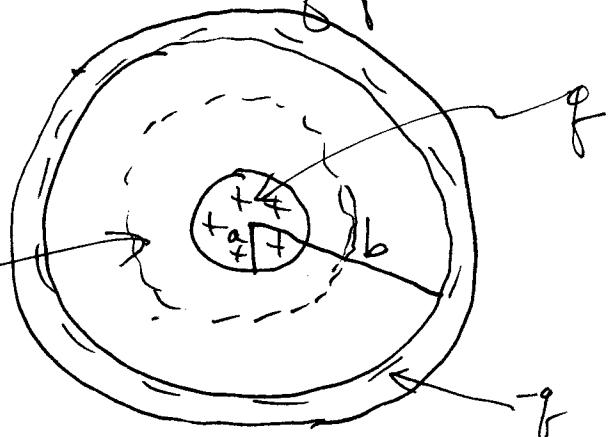
1) Gauss' Law

$$\oint \vec{E} \cdot d\vec{A} = \frac{q}{\epsilon_0}$$

$S \parallel$

$$E(r) 4\pi r^2$$

Spherical Gaussian Surface



$$\Rightarrow \vec{E}(r) = \frac{q}{4\pi\epsilon_0 r^2} \hat{r}$$

2) Potential difference:

$$V = \int_a^b \vec{E} \cdot d\vec{s} = \int_a^b E(r) dr = \frac{q}{4\pi\epsilon_0} \left(\frac{1}{a} - \frac{1}{b} \right)$$

3)

$C = \frac{q}{V} = 4\pi\epsilon_0 \left(\frac{ab}{b-a} \right)$	Spherical Capacitor
--	---------------------

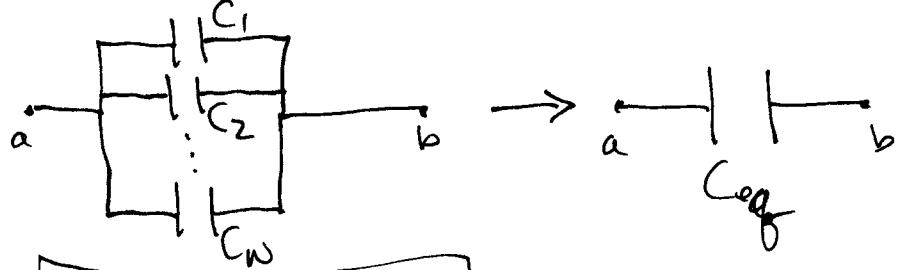
5) Isolated Sphere: let $b \rightarrow \infty$ above
and call $a = R$

$C = 4\pi\epsilon_0 R$	isolated sphere
------------------------	-----------------



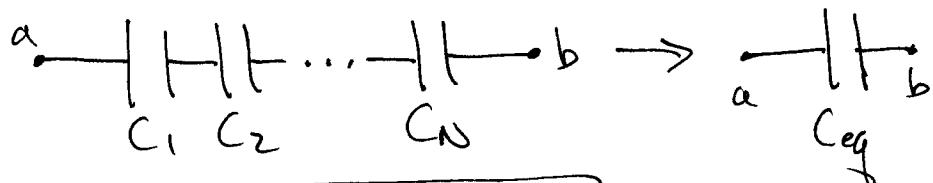
- I.G.6) Equivalent Capacitance:

a) Capacitors in Parallel



$$C_{eq} = \sum_{i=1}^N C_i$$

b) Capacitors in Series



$$\frac{1}{C_{eq}} = \sum_{i=1}^N \frac{1}{C_i}$$

H.) Energy Storage in an Electric Field

Charge capacitor, at time t' , q' charge is on plates with potential difference V' across them, so add dq' more charge. The increase in PE is

$$dU = dq' V' \quad \text{but } V' = q'/C$$

-24-

I.H) $dU = \frac{q' dq'}{C}$; Continue until
totally charged \Rightarrow

$$U = \int_0^U dU = \int_0^q \frac{q'}{C} dq' = \frac{1}{2} \frac{q^2}{C}$$

$$U = \frac{1}{2} \frac{q^2}{C} = \frac{1}{2} CV^2$$

since $q = CV$

i) II-plate:



Energy density $\equiv u = \text{const.}$ between plates
since \vec{E} is uniform

$$u = \frac{U}{Ad} = \frac{\frac{1}{2} CV^2}{Ad} = \boxed{\frac{1}{2} \epsilon_0 E^2 = u}$$

since $C = \frac{\epsilon_0 A}{d}$ and $E = \frac{V}{d}$

II If \vec{E} exists at a point in space, then
the energy density stored at that point
is

$$u = \frac{1}{2} \epsilon_0 |\vec{E}|^2$$

general result

I H 2) Isolated Conducting sphere with charge q



$$1) U = \frac{q^2}{2C} = \frac{1}{2} \frac{q^2}{4\pi\epsilon_0 R}$$

Total energy stored in \vec{E} -field

2) Energy density at point r from center

$$u = \frac{1}{2} \epsilon_0 E(r)^2 = \frac{q^2}{32\pi^2 \epsilon_0 r^4}$$

3) One Half energy stored within radius R_0

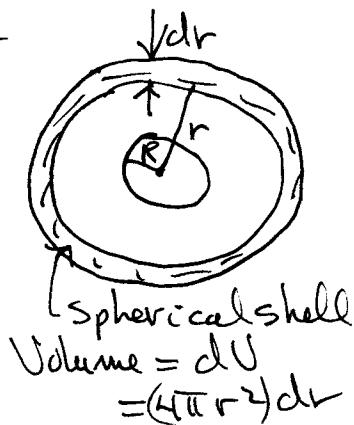
$$dU = u dV = u(r) 4\pi r^2 dr$$

$$= \frac{q}{8\pi\epsilon_0} \frac{dr}{r^2}$$

Require

$$\int_R^{R_0} dU = \frac{1}{2} \int_R^\infty dU$$

$$\Rightarrow \boxed{R_0 = 2R}$$

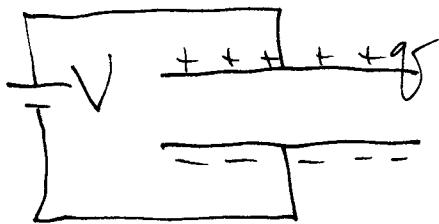


I.I.) Dielectrics: Intermediate materials between conductors and insulators: The charged particles in dielectrics displace their positions slightly in response to an \vec{E} -field.

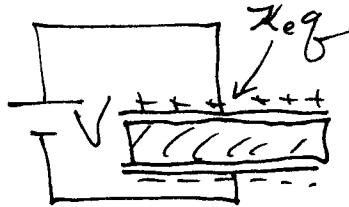
1) Faraday: Experimental results

a)

V_{fixed}



insert
dielectric
slab
with battery
attached
 $V_{\text{maintained}}$



For same V , stored charge q increases

\Rightarrow Capacitance $C = q/V$ increases

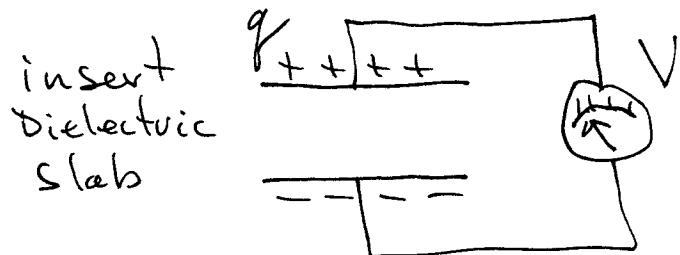
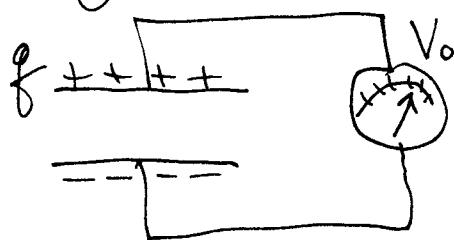
Define
dielectric
constant

$$\kappa_e \equiv \frac{C}{C_0} \xrightarrow{\substack{\text{with} \\ \text{dielectric}}} \begin{array}{l} C \\ C_0 \end{array} \xrightarrow{\substack{\text{vacuum} \\ \text{between} \\ \text{plates}}}$$

($\epsilon \equiv \kappa_e \epsilon_0$ = permittivity of material)

So $q = CV = \kappa_e C_0 V = \kappa_e \epsilon_0$.

- II 1b) q - fixed



$$q = C_0 V_0$$

$$\begin{aligned} q &= CV \\ \text{but } \delta C &= \kappa_e C_0 \\ q &= \kappa_e C_0 V \end{aligned}$$

\Rightarrow

$$q = C_0 V_0 = \kappa_e C_0 V \Rightarrow$$

$$V = \frac{1}{\kappa_e} V_0$$

For fixed charge q , the voltage decreases as the slab is inserted.

2) Fill Capacitors with dielectric $\kappa_e \Rightarrow$
 $C = \kappa_e C_0$

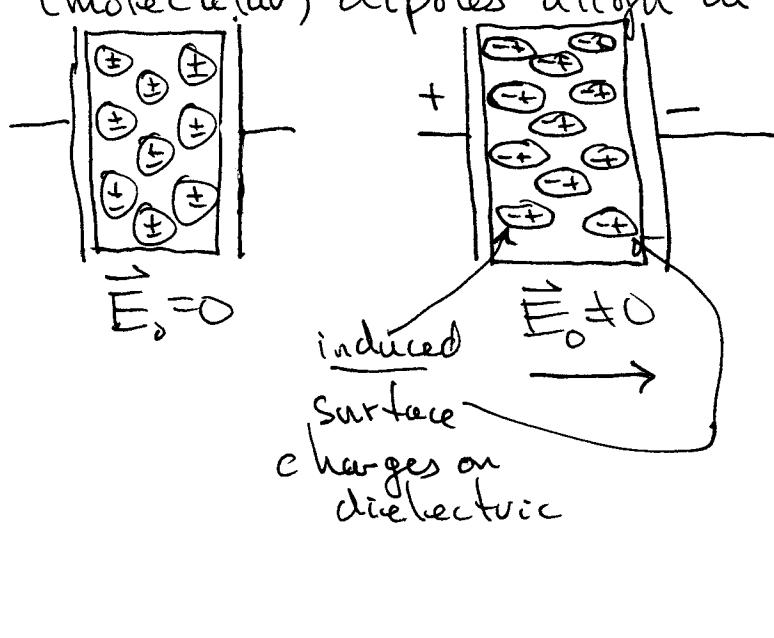
a) II-plate : $C = \frac{\kappa_e C_0 A}{d}$

b) Cylindrical : $C = 2\pi \kappa_e \epsilon_0 \frac{L}{\ln(b/a)}$

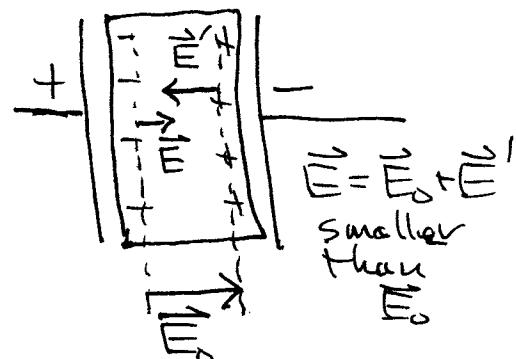
c) Spherical : $C = 4\pi \kappa_e \epsilon_0 \frac{ab}{b-a}$

d) Isolated Sphere : $C = 4\pi \kappa_e \epsilon_0 R$.

- I.I.3) Microscopic View of Dielectrics: Atomic (molecular) dipoles align in \vec{E} -field.



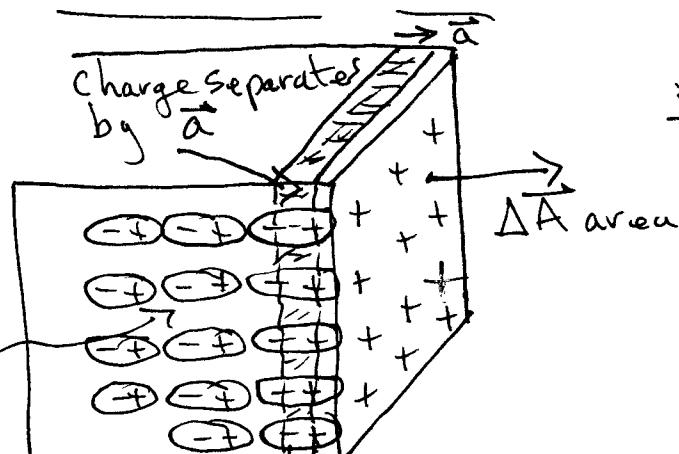
Alignment tends to lower \vec{E} -field in dielectric



a) Molecular dipole moment \vec{p} & Polarization Charge



$$\text{Polarization Vector} = \vec{P} \equiv N \vec{p} = \frac{\text{dipole moment}}{\text{Volume}}$$



$$\frac{\# \text{ of atoms}}{\text{Volume}} \left(= \frac{1}{\Delta V} \sum_{\text{molecules}} \vec{p} \right)$$

sum molecular

dipole moments in macro
small but micro large
volume ΔV
This depends on size ΔV , so
divide by ΔV

\vec{E}_0 uniform

- II.3a) Negative charges shift away from surface, no new negative charge enters surface since it is the external surface of the dielectric.
- Hence the box at the surface gains positive charge equal to the amount of negative charge that left the surface.

$$\text{surface box} = \underbrace{N Ze}_{\substack{\text{atoms} \\ \text{Vol.}}} (\underbrace{a \Delta A}_{\substack{\text{charge} \\ \text{atom}}}) \underbrace{\text{Vol. of box}}_{\text{Vol.}}$$

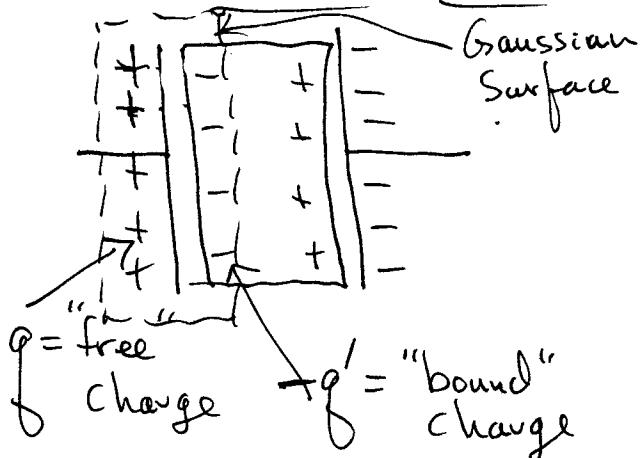
Hence the surface acquires a Polarization surface charge density

$$\sigma_p = \frac{N Ze a \Delta A}{\Delta A} = N Ze a = N |\vec{p}| = |\vec{P}|$$

or in terms of vectors and in general

$$\boxed{\sigma_p \Delta A = \vec{P} \cdot \vec{\Delta A}}$$

I.I.4) Gauss' Law Re-Visited



$$\oint_S \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} [q - q']$$

$\parallel A$

$$\Rightarrow \boxed{E = \frac{q}{\epsilon_0 A} - \frac{q'}{\epsilon_0 A}}$$

(Vacuum: $E_0 = \frac{q}{\epsilon_0 A}$)

a) Charges

$$E = \frac{1}{\chi_e} E_0 \quad (\text{Faraday's Exp linear dielectric materials})$$

$$\frac{q}{\epsilon_0 A} - \frac{q'}{\epsilon_0 A} = \frac{1}{\chi_e} \frac{q}{\epsilon_0 A}$$

$$\Rightarrow \boxed{q' = q \left(1 - \frac{1}{\chi_e}\right) < q}$$

likewise $\sigma_p = \sigma \left(1 - \frac{1}{\chi_e}\right)$
 $(\sigma_p = q'/A)$ $\sigma = q/A$

induced
Polarization
surface
charge < free
charge

b) Gauss' Law $\epsilon_0 \oint_S \vec{E} \cdot d\vec{A} = q - q' = q/\chi_e$

$$\Rightarrow \boxed{\epsilon_0 \oint_S \chi_e \vec{E} \cdot d\vec{A} = q}$$

free
charge
only.

- II.4.c) Electric Displacement Vector \vec{D} -31-

$$1) E = \frac{q}{\epsilon_0 A} - \frac{q'}{\epsilon_0 A} = \frac{\sigma}{\epsilon_0} - \frac{\sigma_p}{\epsilon_0}$$

$$= \frac{\sigma}{\epsilon_0} - \frac{P}{\epsilon_0} \Rightarrow \sigma = \epsilon_0 E + P$$

free charge density $\frac{\sigma}{A}$
 \parallel

Define:
$$\boxed{\vec{D} = \epsilon_0 \vec{E} + \vec{P}}$$

So $\frac{q}{A} = \sigma = D$; D is given by free charge only.

Now $\sigma = \kappa_e \epsilon_0 E$ hence

$$\boxed{\vec{D} = \kappa_e \epsilon_0 \vec{E}}$$

2) Gauss' Law for \vec{D}

$$\boxed{\oint_S \vec{D} \cdot d\vec{A} = q}$$

d.) Constitutive Equation: Linear, isotropic dielectrics (Faraday's exp.)

$$\vec{P} = \chi_E \vec{E}$$

\uparrow electric susceptibility

I.I.4.d) Now $\vec{D} = \epsilon_0 \vec{E} + \vec{P}$

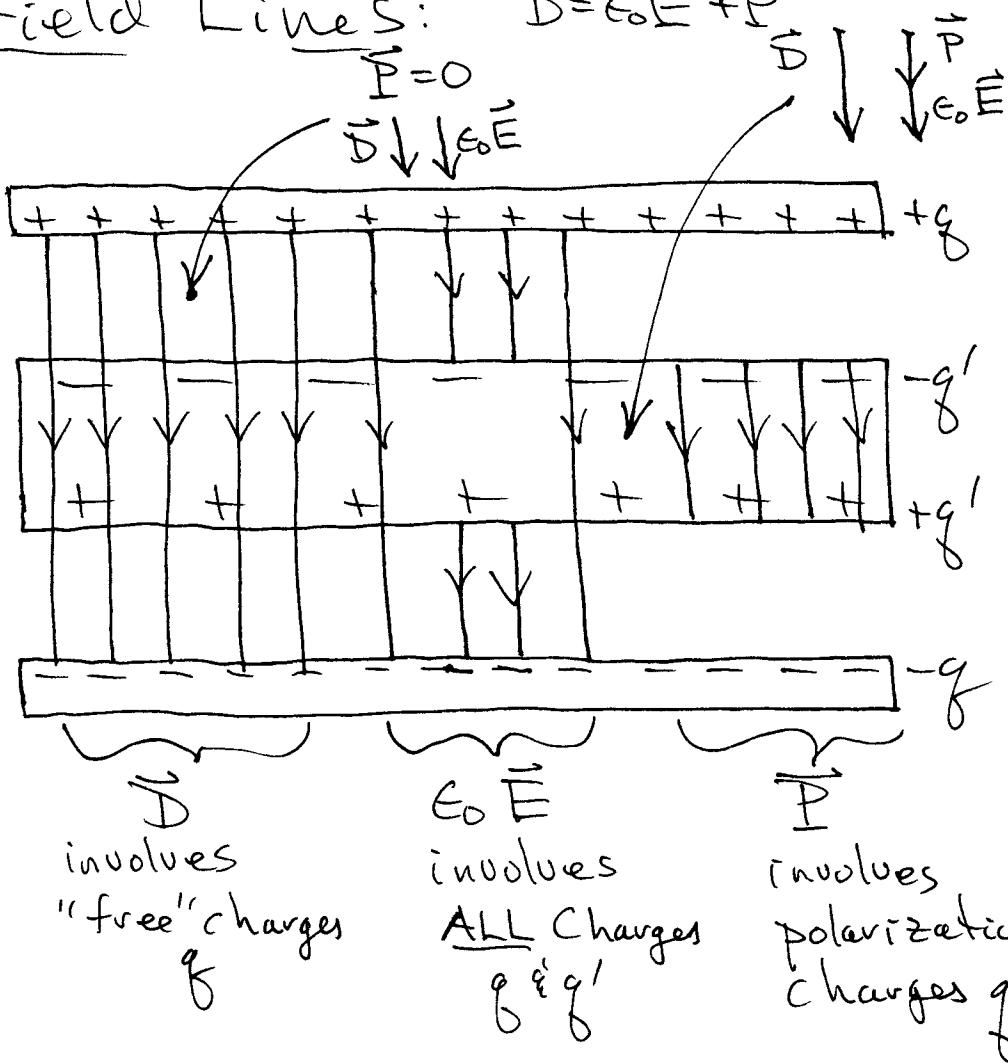
$$= \underbrace{\epsilon_0(1+\chi_E)}_{\equiv \epsilon = \epsilon_0 \chi_e} \vec{E}$$

$\equiv \epsilon = \epsilon_0 \chi_e$ = permittivity

thus $\boxed{\chi_e = \epsilon/\epsilon_0 = 1 + \chi_E}$ = dielectric constant

hence $\boxed{\vec{P} = \epsilon_0(\chi_e - 1) \vec{E}}$.

e) Field Lines: $\vec{D} = \epsilon_0 \vec{E} + \vec{P}$



I.I.5) Energy stored in field - Re-Visited

Dielectric filled capacitor $q = CV$, $C = \kappa_e C_0$

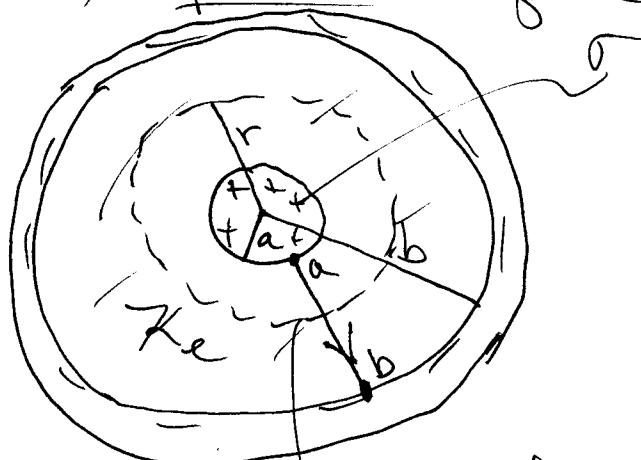
$$\Rightarrow U = \frac{1}{2} \frac{q^2}{C} = \frac{1}{2} CV^2 \text{ as previously}$$

energy density stored in fields $\Rightarrow U = \frac{1}{2} \vec{D} \cdot \vec{E}$

Hence energy stored in fields

$$U = \frac{1}{2} \int \vec{D} \cdot \vec{E} dV$$

6) Capacitance of Coaxial Cable



Cylindrical Gaussian Surface

1) Gauss' Law

$$\oint \vec{D} \cdot d\vec{A} = Q_{\text{free}}$$

$$\int_S D(r) 2\pi r dl = 2\pi a l \sigma$$

$$\Rightarrow D(r) = \frac{\sigma r}{r}$$

$$2) E(r) = \frac{1}{\epsilon_0 \kappa_e} D(r)$$

$$= \frac{\sigma r}{\kappa_e \epsilon_0 r}$$

- II(6) 3) Potential Difference:

$$V = \int_a^b \vec{E} \cdot d\vec{s} = \int_a^b E(r) dr \\ = \frac{\alpha \sigma}{\kappa_e \epsilon_0} \ln(b/a)$$

4) Capacitance $C = q/V$; $q = 2\pi a \lambda \sigma$

$$C = \frac{2\pi \kappa_e \epsilon_0}{\ln(b/a)} l = \kappa_e C_0$$

$$\boxed{C/l = \frac{2\pi \kappa_e \epsilon_0}{\ln(b/a)}} = \text{Capacitance per unit length.}$$

7) Forces on Charges

a) Isolated System: $Q = \text{fixed}$

$$dW = \vec{F} \cdot d\vec{s} = -dU = -\vec{\nabla}U \cdot d\vec{s}$$

↑ Work performed by \vec{E} -field ↑ Loss in P.E.

$$\Rightarrow \boxed{\vec{F} = -\vec{\nabla}U \quad |_{Q=\text{fixed}}}$$

-35-

- I.I. > b) Energy source attached to system:
fix. potential difference: V-fixed

$$\vec{F} \cdot d\vec{s} = dW = dW_{\text{battery}} - dU$$

↑
work performed
by battery & \vec{E} -field ↑
work performed
by battery PE gain

$$\left. \begin{array}{l} dW_{\text{battery}} = dgV \\ dU = \frac{1}{2} dgV \end{array} \right\} \Rightarrow dW = \frac{1}{2} dgV$$
$$= dU$$

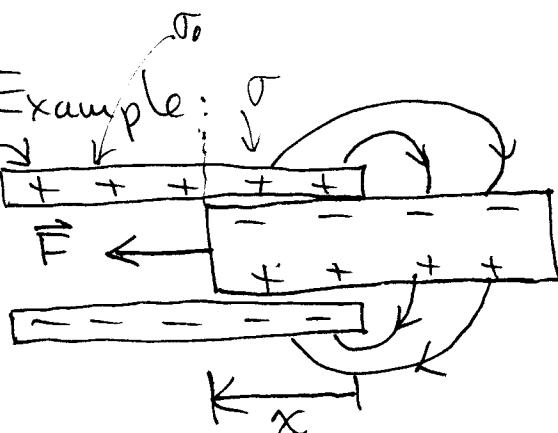
So

$$\vec{F} \cdot d\vec{s} = +dU = +\vec{\nabla}U \cdot d\vec{s}$$

$$\Rightarrow \boxed{\vec{F} = +\vec{\nabla}U \quad |_{V=\text{fixed}}}$$

I.I.7c) Example:

fixed edge



q - fixed

dielectric

slab pulled in
by \vec{E} -field

$$U = \frac{1}{2} \int \mathcal{D} \cdot \vec{E} dV = \frac{1}{2} \epsilon_0 \chi_e E^2 (x b d) \\ \text{capacitor volume} \quad + \frac{1}{2} \epsilon_0 E^2 [(l-x) b d] \\ = \frac{1}{2} \epsilon_0 E^2 b d [\chi_e x + (l-x)]$$

q is fixed, but V changes with x

$$\left\{ \begin{array}{l} q = \sigma x b + \sigma_0 (l-x) b \\ E = \frac{\sigma}{\epsilon_0 \epsilon_0} = \frac{\sigma_0}{\epsilon_0} = V/d \Rightarrow \sigma = \chi_e \sigma_0 \end{array} \right.$$

$$\Rightarrow \sigma_0 = \frac{q}{\chi_e x b + (l-x) b}$$

Hence

$$U = \frac{1}{2} \frac{q^2}{C} \quad \text{with}$$

$$C = \frac{\epsilon_0 b}{d} [(l-x) + \chi_e x]$$

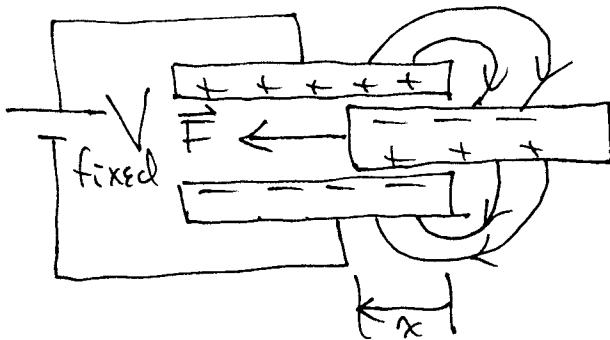
So

$$F = - \frac{dU}{dx} \quad \text{since } q \text{ is fixed}$$

$$F = + \frac{q^2}{2 C^2} \frac{dC}{dx} > 0$$

(x -dependent
force in q fixed case)

IITd) Example: V-fixed



dielectric slab is pulled in.

$$E = V/d = \text{constant}$$

$$U = \frac{1}{2} \int_{\text{Capacitor Volume}} \vec{D} \cdot \vec{E} dV = \frac{1}{2} \epsilon_0 \chi_e E^2 (x b d) + \frac{1}{2} \epsilon_0 E^2 [(l-x) b d]$$

$$\boxed{U = \frac{1}{2} \epsilon_0 \left(\frac{V}{d}\right)^2 b d [\chi_e x + (l-x)]}$$

$$= \frac{1}{2} C V^2$$

$$F = + \frac{dU}{dx} = \frac{1}{2} V^2 \frac{dC}{dx}$$

$$= \frac{1}{2} V^2 \frac{\epsilon_0 (\chi_e - 1/b)}{d} > 0$$

F is a constant indep. of x

in fixed V case

Note:

$$F \Big|_{q \text{fixed}} = \frac{q^2}{2C^2} \frac{dC}{dx}$$

but $q = CV$

$$= \frac{1}{2} V^2 \frac{dC}{dx}$$

but $V = V(x)$ in

similar form
but different
 x -dependence

$$F \Big|_{V \text{fixed}} = \pm V^2 \frac{dC}{dx}$$

but $V = \text{constant}$
in fixed V case

II.) Currents

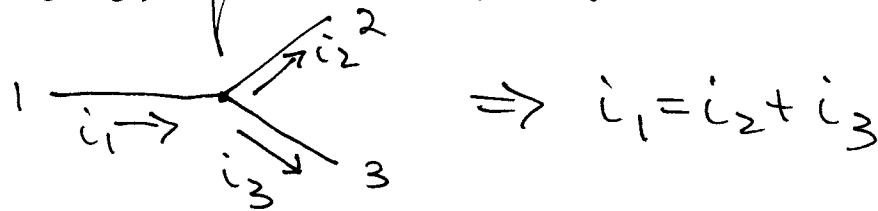
A) Electric current, i , is the rate at which charge is transported through a given surface

$$i = \frac{dq}{dt}$$

1) SI units: $[i] = 1 \text{ Ampere} = 1 \frac{\text{Coulomb}}{\text{Second}}$

2) Convention: Current is in the direction of positive charge flow.

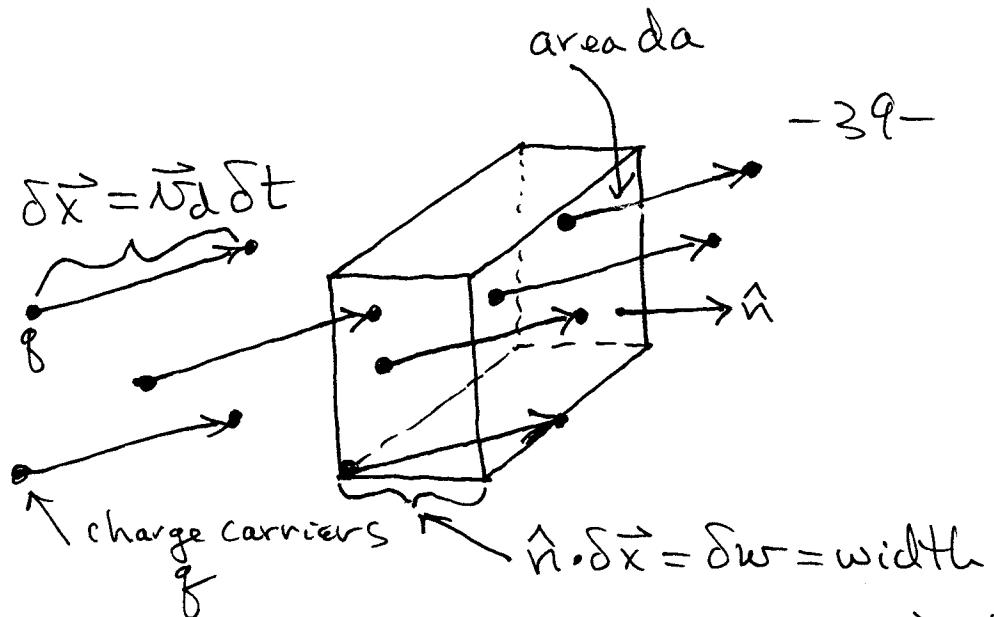
3) Current obeys scalar addition



B) Conducting medium: free electron gas model electrons move at constant drift velocity \vec{v}_d when an \vec{E} -field is established in conducting wire

1) Suppose conducting medium has one type of charge carrier σ with $N = \frac{\# \text{ of charge carriers}}{\text{Volume}}$ each has drift velocity \vec{v}_d in an \vec{E} -field

- II(B))



In time δt , each charge carrier moves $\delta \vec{x} = \vec{v}_d \delta t$. Charge δQ passes through area da in time δt

$$\delta Q = (q N) (\delta \vec{x} \cdot \hat{n} da)$$

$$= q N \vec{v}_d \cdot d\vec{A} \delta t \quad \text{where } d\vec{A} = da \hat{n}$$

Hence, $i_i = \text{current transported through } da$

$$i_i = \frac{\delta Q}{\delta t} = N q \vec{v}_d \cdot d\vec{A}$$

$$i_i = \vec{j} \cdot d\vec{A}$$

With the current density $\vec{j} = N q \vec{v}_d$

2) Current flowing through an arbitrarily shaped surface S of macroscopic size

$$i = \int_S \vec{j} \cdot d\vec{A}$$

II B3) Charge Conservation = Continuity Equation

$$\int_V \frac{\partial \rho}{\partial t} dV + \oint_S \vec{j} \cdot d\vec{A} = 0$$

$S = \text{boundary of } V$
= closed surface

c) Ohm's Law: Linear, isotropic conducting medium

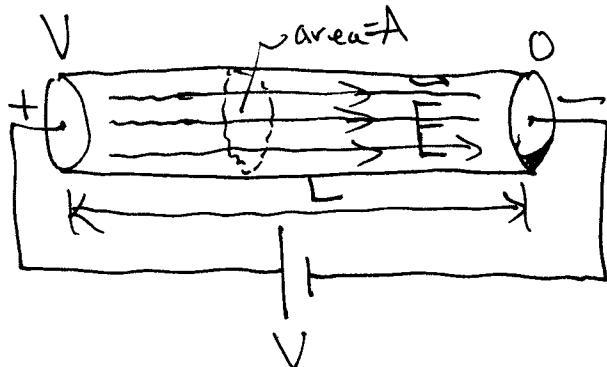
$$\vec{j} = \sigma \vec{E}$$

σ = conductivity of material

1) SI units: $1 \text{ ohm} (\Omega) \equiv 1 \frac{\text{ Volt}}{\text{ Ampere}}$

$$[\sigma] = \Omega^{-1} m^{-1}$$

2) Wire of conductivity σ , length L , cross sectional area A



$$V = + \int_0^L \vec{E} \cdot d\vec{s}$$

$$= E L$$

$$\Rightarrow E = \frac{V}{L}$$

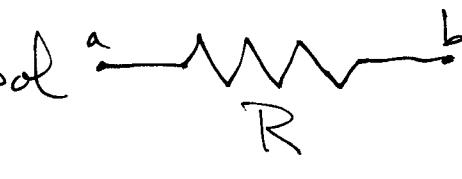
$$\text{II.C.)2) } i = \int_A \vec{j} \cdot d\vec{A} = j A = \sigma E A = \left(\sigma \frac{A}{L} \right) V \stackrel{-41-}{=} R^{-1}$$

\Rightarrow

$V = i R$ Macroscopic
Ohm's Law

a) SI units of R : $[R] = \Omega$

b) $\rho = \frac{V}{I} = \text{resistivity of material}$
 $R = \frac{\rho L}{A}$ $[\rho] = \Omega \cdot m$

c) Circuit Symbol
 for Resistor 

D) Work done by E -field in moving dQ through potential difference V

$$dW = dQ V = i dt V$$

Rate of energy transfer = Power P

$$P = \frac{dW}{dt} = i V$$

(Units:
 $1 \text{ Amp} \cdot \text{Volt} = 1 \text{ watt}$)

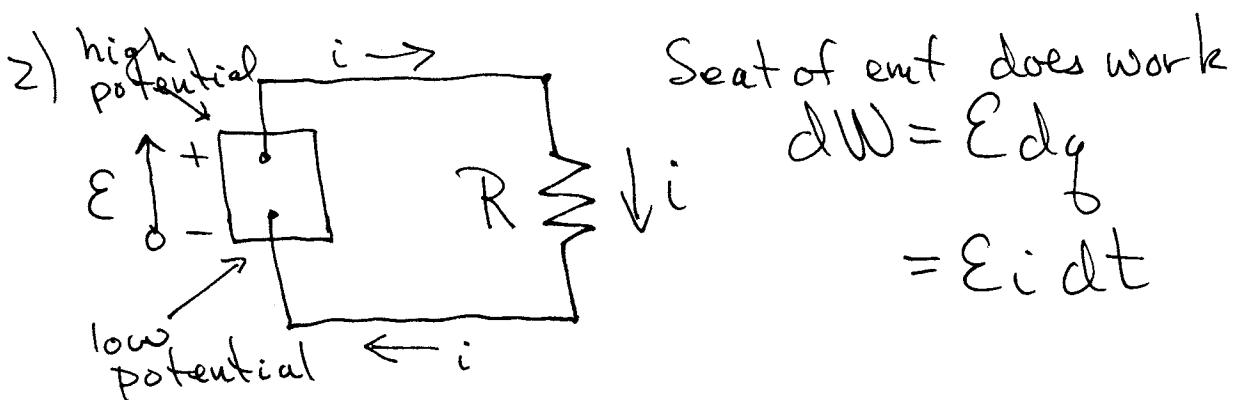
i) For Ohmic Device $V = i R$

$$\Rightarrow P = i V = i^2 R = \frac{V^2}{R}$$

I.E.) Electromotive Force (emf) \mathcal{E}

$$\mathcal{E} = \frac{dW}{dq}$$

1) SI units: $[\mathcal{E}] = 1 \frac{\text{Joule}}{\text{Coulomb}} = 1 \text{ volt.}$

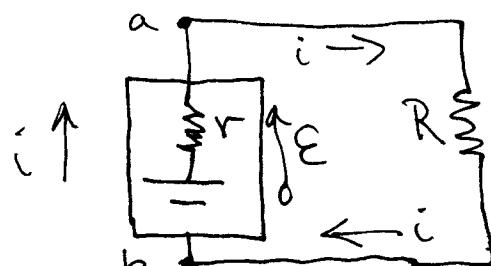


Conservation of energy: $\mathcal{E} i dt = i^2 R dt$
 $\Rightarrow i = \mathcal{E}/R$

3) Kirchhoff's Second Rule (Loop Rule):
 (Conservation of energy)

The algebraic sum of the changes in potential encountered in a complete traversal of any closed circuit is zero.

4) Internal resistance of seat of emf



Loop Rule:

$$V_b + \mathcal{E} - ir - iR = V_b$$

$$\Rightarrow i = \frac{\mathcal{E}}{R+r}$$

II E.4.) Potential Difference V_{ab} : traverse part of circuit by any path that includes the two points a & b

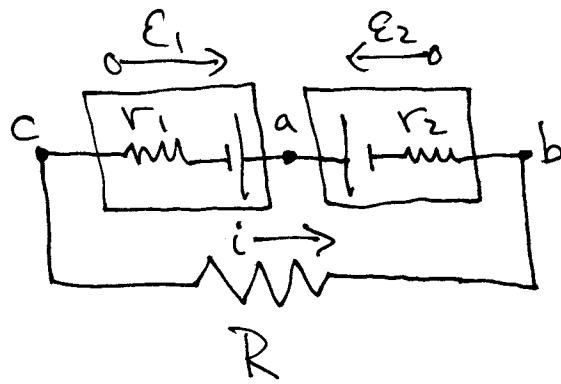
a) Start at b } $V_b + iR = V_a$
 and go CCW } $\Rightarrow V_a - V_b = V_{ab} = iR$
 to a }

$$= \mathcal{E} \frac{R}{R+r}$$

b) Start at a } $V_a + ir - \mathcal{E} = V_b$
 and go CCW } $\Rightarrow V_{ab} = \mathcal{E} - ir = \mathcal{E} \frac{R}{R+r}$
 to b }

The same as above.

5.) Example



a) $i = ?$ Loop Rule: Start at "a" go CW back to "a"

$$-\mathcal{E}_2 + ir_2 + iR + ir_1 + \mathcal{E}_1 = 0$$

$$\Rightarrow i = \frac{\mathcal{E}_2 - \mathcal{E}_1}{R + r_1 + r_2}$$

II Es) a) The sign of i tells its direction of flow

b) $V_{ab} = ?$ Start at "b" go CCW to "a"

$$V_b - ir_2 + \epsilon_2 = V_a$$

$$\Rightarrow V_{ab} = -ir_2 + \epsilon_2 \\ = \frac{\epsilon_1 r_2 + \epsilon_2 (R + r_1)}{R + r_1 + r_2}$$

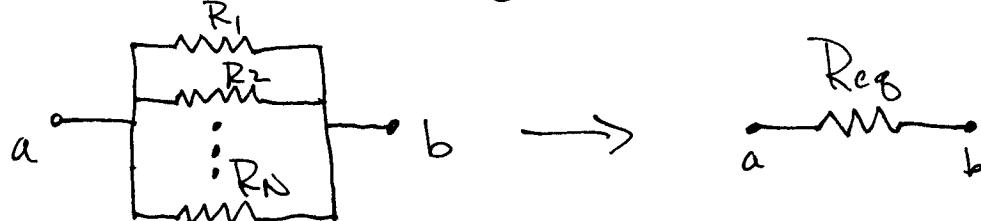
c) $V_{ac} = ?$ Start at "c" go CW to "a"

$$V_c + ir_1 + \epsilon_1 = V_a$$

$$\Rightarrow V_{ac} = \epsilon_1 + ir_1 \\ = \frac{\epsilon_1 (R + r_2) + \epsilon_2 r_1}{R + r_1 + r_2}$$

F) Equivalent Resistance

i) Resistors in Parallel



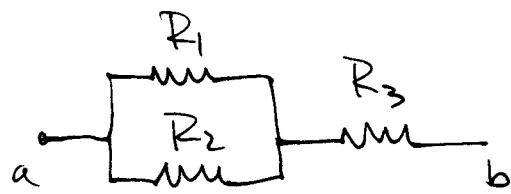
II F 1) $\frac{1}{R_{\text{eq}}} = \sum_{i=1}^{N_f} \frac{1}{R_i} = \frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_N}$

2) Resistors in Series

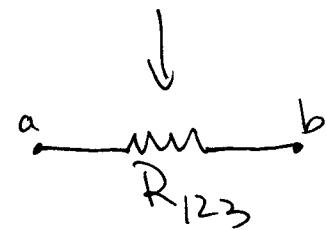


$$R_{\text{eq}} = \sum_{i=1}^{N_f} R_i = R_1 + R_2 + \dots + R_N$$

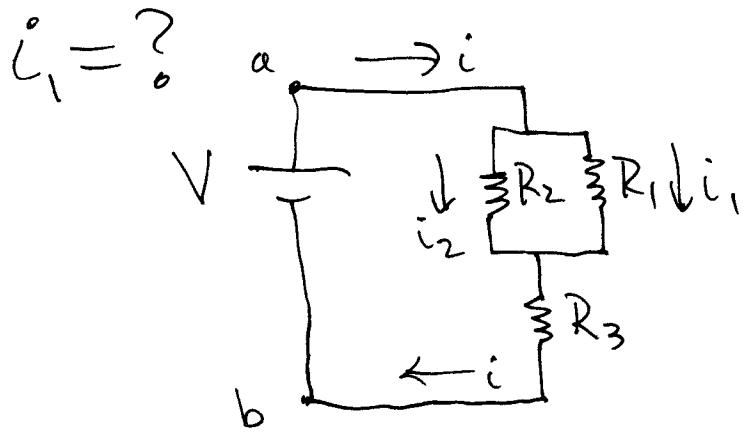
3) Example



$$R_{12} = \frac{R_1 R_2}{R_1 + R_2}$$

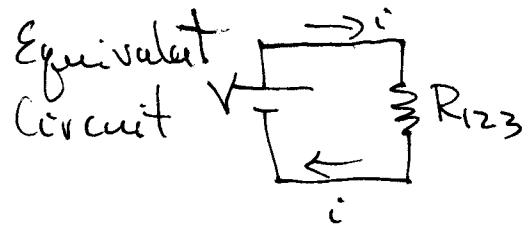


$$\begin{aligned} R_{123} &= R_{12} + R_3 \\ &= \frac{R_1 R_2}{R_1 + R_2} + R_3 \end{aligned}$$

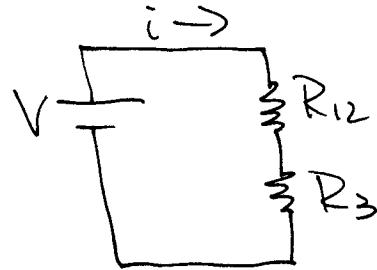


Steps:

a) $i = \frac{V}{R_{123}}$



II F3) b) Equivalent Circuit



$$V_{12} = i R_{12}$$

c) Since R_1 & R_2 are in II, V_{12} is the voltage that appears across both — so

$$i_1 = \frac{V_{12}}{R_1} \quad (V_1 = V_2 = V_{12})$$

$$= \frac{V R_{12}}{R_1 R_{123}}$$

G) Multiloop Circuits: Made up of junctions and branches

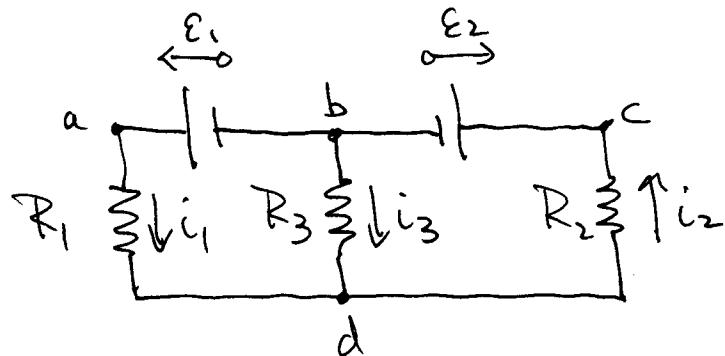
Junction = 3 or more wire segments meet

Branch = Circuit path that starts at one junction and ends at another.

i) Kirchhoff's First Rule (Junction Rule)
(Conservation of Charge)

At any junction, the sum of the currents leaving the junction equals the sum of the currents entering the junction.

- II G2) Example:



a) 2 Junctions b & d

b) 3 Branches:
Left Branch bad
Central Branch bd
Right Branch bcd

Find i_1, i_2, i_3 :

1) Apply Junction Rule to d \Rightarrow

$$i_1 + i_3 = i_2$$

2) Apply Loop Rule: CCW b-a-d-b

$$\varepsilon_1 - i_1 R_1 + i_3 R_3 = 0$$

3) Apply Loop Rule: CCW b-d-c-b

$$-i_3 R_3 - i_2 R_2 - \varepsilon_2 = 0$$

\Rightarrow 3 equations for 3 unknowns i_1, i_2, i_3
(Use either junction to apply junction rule, get same equation, Use any 2 independent loops, get same information)

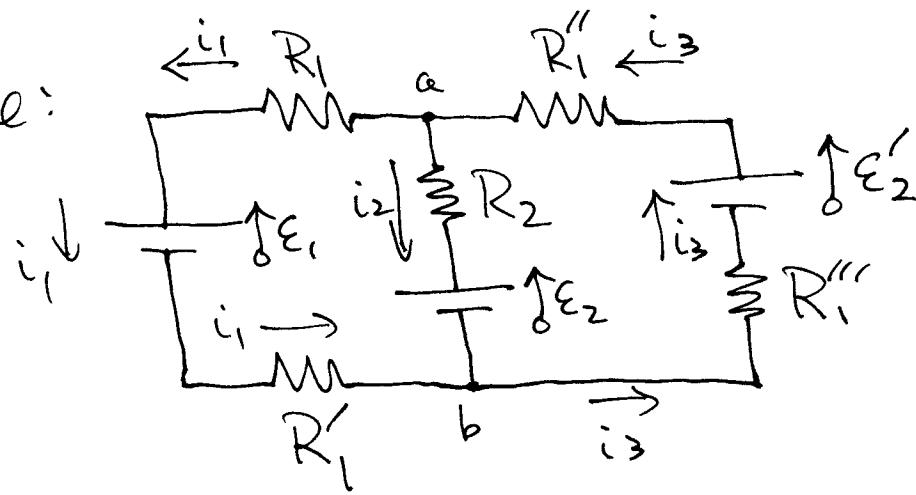
- II G2) Solve 3 simultaneous equations

$$i_3 = - \frac{R_2 \varepsilon_1 + R_1 \varepsilon_2}{R_1 R_2 + R_2 R_3 + R_1 R_3} \quad \begin{aligned} & \text{(negative result)} \\ & \Rightarrow i_3 \text{ flows from } d \rightarrow b \text{ opposite how we drew} \end{aligned}$$

$$i_2 = \frac{\varepsilon_1 R_3 - \varepsilon_2 (R_1 + R_3)}{R_1 R_2 + R_2 R_3 + R_1 R_3}$$

$$i_1 = \frac{\varepsilon_1 (R_2 + R_3) - \varepsilon_2 R_3}{R_1 R_2 + R_2 R_3 + R_1 R_3}$$

3) Example:



i) Apply Junction Rule at b

$$i_1 + i_2 = i_3$$

ii) Apply Loop Rule: CCW a-b-a (Left Loop)

$$-i_1 R_1 - \varepsilon_1 - i_1 R_1' + \varepsilon_2 + i_2 R_2 = 0$$

$$(if R_1' = R_1 \Rightarrow 2i_1 R_1 - i_2 R_2 = \varepsilon_2 - \varepsilon_1)$$

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II G3) 3) Apply Loop Rule: CW a-b-a (Right Loop)

$$i_3 R'' - \epsilon'_2 + i_3 R''' + \epsilon_2 + i_2 R_2 = 0$$

$$(if R'' = R''' = R_1 \text{ and } \epsilon'_2 = \epsilon_2 \Rightarrow i_2 R_2 + 2 i_3 R_1 = 0)$$

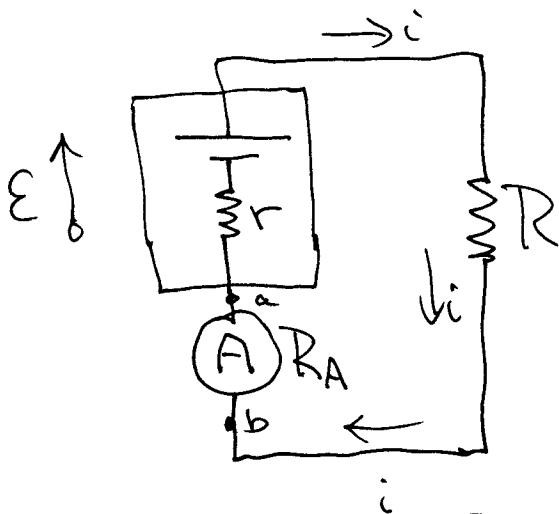
Hence we have 3 equations for the
3 unknowns i_1, i_2, i_3 — solve

simultaneously:

(See class notes for solution and
 $V_a - i_2 R_2 - \epsilon_2 = V_b \Rightarrow V_{ab} = \epsilon_2 + i_2 R_2$)

H) Measuring Instruments:

1) Ammeter measures current

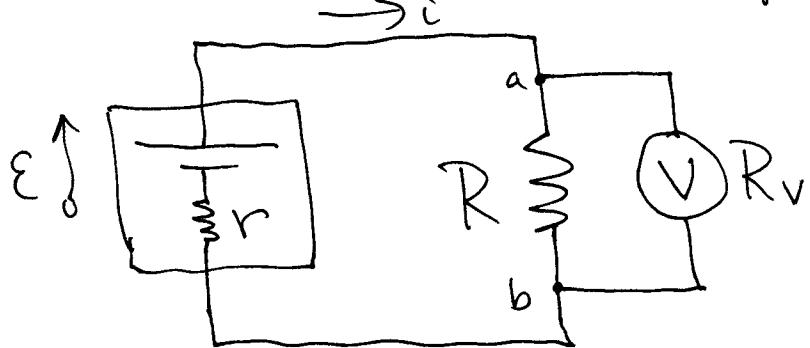


Loop Rule

$$\begin{aligned} 0 &= \epsilon - iR - iR_A - ir \\ \Rightarrow i &= \frac{\epsilon}{r+R+R_A} \end{aligned}$$

Ideal Ammeter $R_A = 0$
Realistic Ammeter $R_A \ll r+R$
to give small error

- II H 2) Voltmeter measures potential difference



Loop Rule

$$E - iR_{\text{eq}} - ir = 0$$

$$i = \frac{E}{r + R_{\text{eq}}}$$

$$R_{\text{eq}} = \frac{RR_V}{R+R_V}$$

Potential Difference
measured

$$V_a - iR_{\text{eq}} = V_b$$

$$\Rightarrow V_{ab} = iR_{\text{eq}} = E \frac{R_{\text{eq}}}{R_{\text{eq}} + r}$$

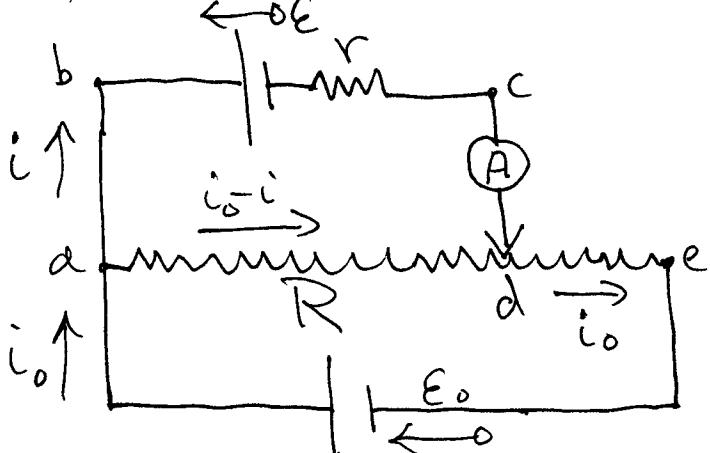
Without Voltmeter this would be $V_{ab}^0 = E \frac{R}{R+r}$

So ideal Voltmeter $R_V = \infty$ (then $R_{\text{eq}} = R$)

Realistic Voltmeter $R_V \gg R$

to give small error

3) Potentiometer: Measures unknown emf E_x
by comparing to standard
emf E_S



R = resistance between
a-d

-> 1 -

- II(3) Step 1: Place E_s where E is and adjust R until $i = 0$ — potentiometer is "balanced" call this value of $R = R_s$ at balance

Loop Rule (W a-b-c-d-a)

$$-E_s - ir + (i_0 - i)R_s = 0$$

But $i = 0$ in balance \Rightarrow

$$E_s = i_0 R_s .$$

- Step 2: Substitute E_x for E_s and adjust R to R_x for balance $i = 0$ again

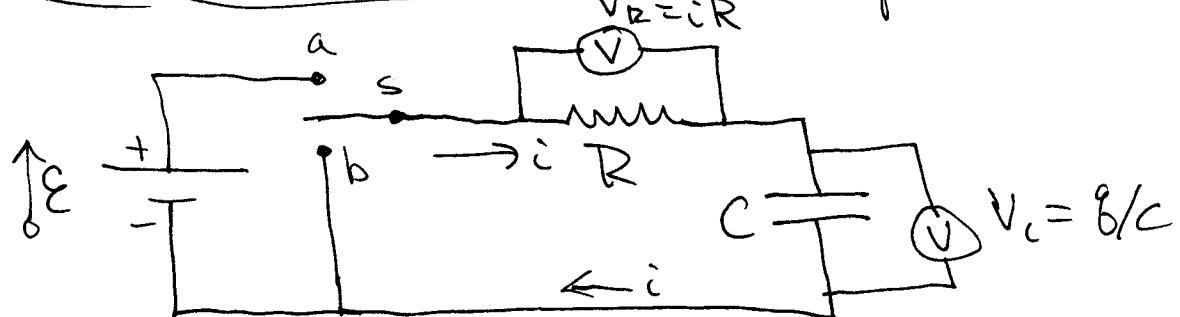
Now loop Rule gives $E_x = i_0 R_x$

(same i_0)

$$\Rightarrow E_x = E_s \frac{R_x}{R_s}$$

(independent
of $E_s - i = 0$
"null instrument")

- II.) I) RC-circuits: Current will depend on time



- a) Throw switch to a - charge capacitor
Loop Rule: CW start at a end at a
with $V_R = iR$ and $V_C = \frac{q}{C}$

$$\epsilon = iR + \frac{q}{C}$$

$$= R \frac{dq}{dt} + \frac{q}{C}$$

This is DE for $q = q(t)$:

$$\int_0^{q(t)} \frac{dq}{\epsilon C - q} = \frac{1}{RC} \int_0^t dt$$

$$-\ln [\epsilon C - q] \Big|_0^{q(t)} = \frac{1}{RC} t$$

$$\Rightarrow \ln \left[\frac{\epsilon C - q(t)}{\epsilon C} \right] = -\frac{t}{RC}$$

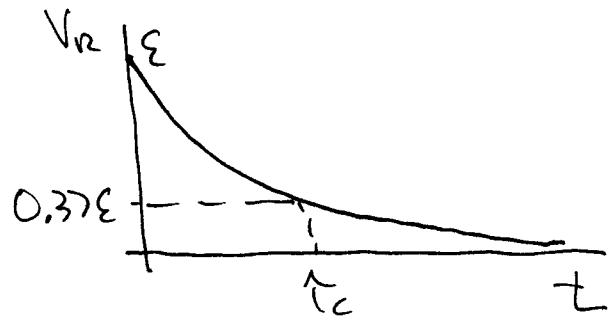
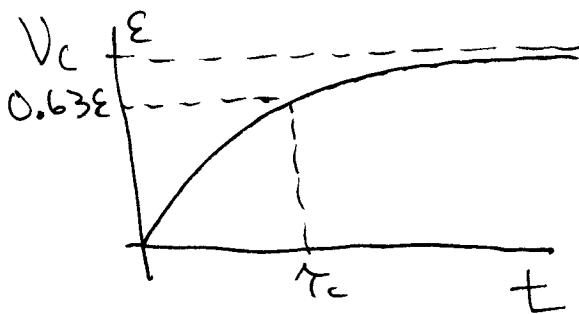
$$\Rightarrow \frac{\epsilon C - q(t)}{\epsilon C} = e^{-t/RC}$$

- IIIa) \Rightarrow

$$q(t) = \epsilon C [1 - e^{-t/\tau_c}]$$

with $\tau_c \equiv RC$ = Capacitive Time Constant

Hence $i = i(t) = \frac{dq(t)}{dt} = \frac{\epsilon}{R} e^{-t/\tau_c}$



b) Throw switch from a to b: Discharge Capacitor

Loop Rule:

$$iR + \frac{q}{C} = 0$$

$$\Rightarrow R \frac{dq}{dt} + \frac{1}{C} q = 0$$

$$\Rightarrow \int_{q_0}^{q(t)} \frac{dq}{q} = -\frac{1}{RC} \int_0^t dt$$

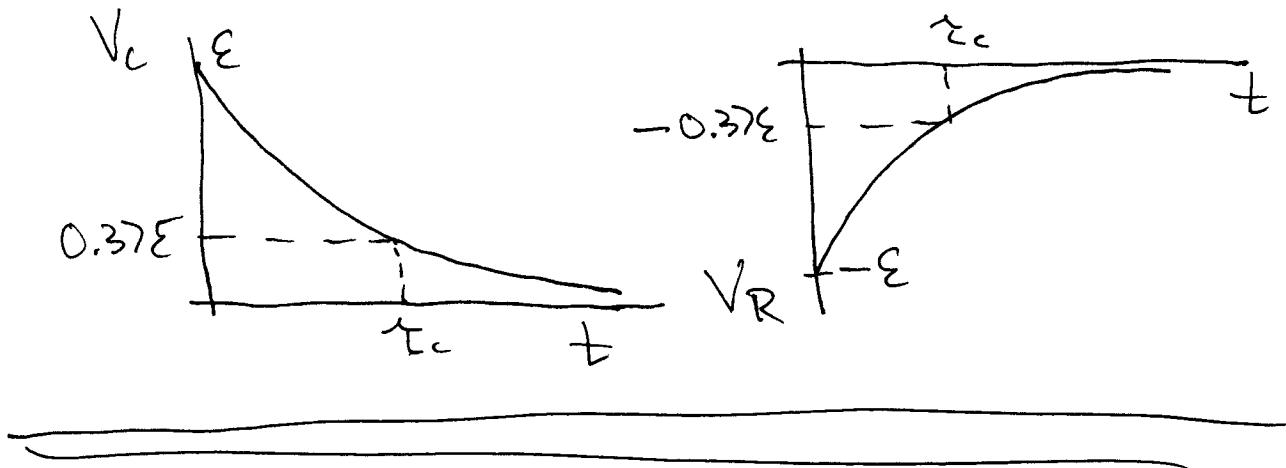
$$\Rightarrow q(t) = q_0 e^{-t/\tau_c}$$

- II.I.b) q_0 = initial charge on capacitor
for $t \gg \tau_c$ in part a) $q_0 \approx \epsilon C$.

$$q(t) = \epsilon C e^{-t/\tau_c}$$

and

$$i(t) = \frac{dq(t)}{dt} = -\frac{\epsilon}{\tau_c} e^{-t/\tau_c}$$



III) Magnetic Field:

A) The magnetic field \vec{B} is defined by the force law

$$\vec{F} = q \vec{v} \times \vec{B}$$

1) SI units: $[\vec{B}] = \text{tesla (T)}$

$$= 1 \frac{\text{Newton}}{\text{Ampere-meter}}$$

(non-SI units: gauss(G) = 10^{-4}T)

2) $\vec{F} \perp \vec{v}$: magnetic force does no work
only change direction of \vec{v} ,
not magnitude.

3) Lorentz Force Law: total
force on charge q in \vec{E} - and \vec{B} -
fields

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

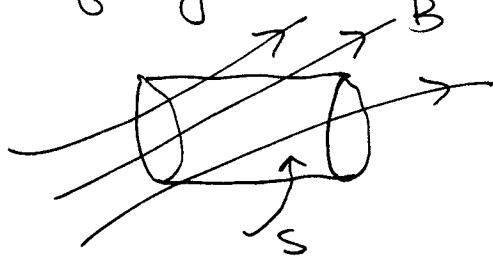
(This defines \vec{B} and \vec{E})

4) No Magnetic Charges: experimental
result

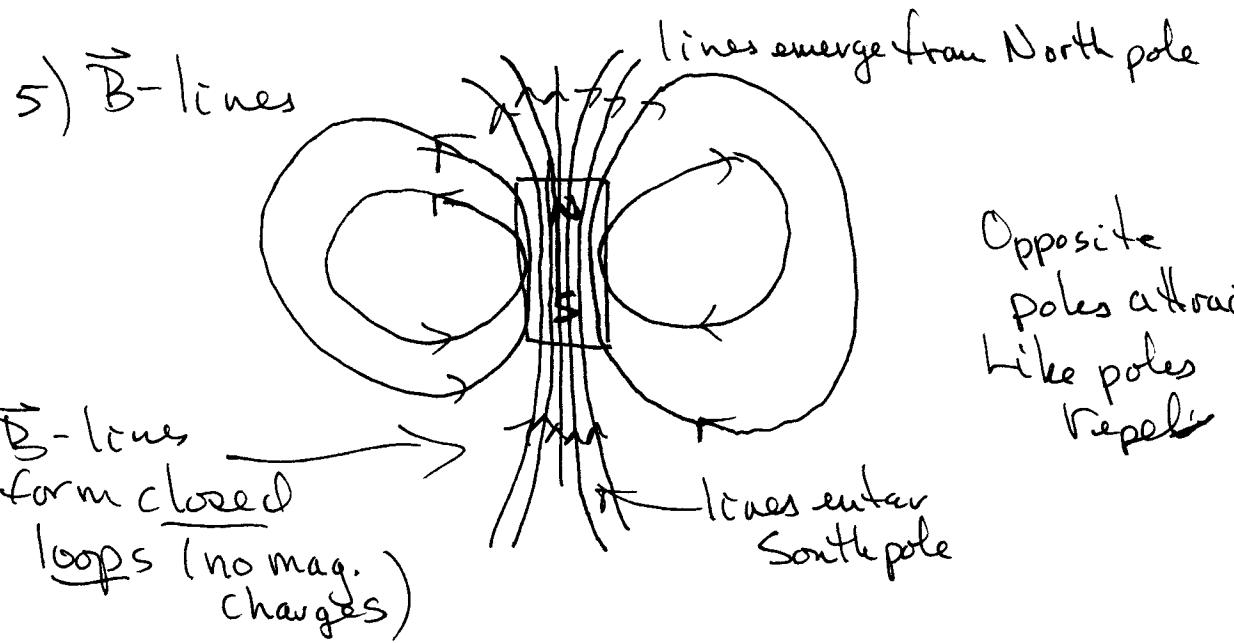
Lines of \vec{B} are continuous

- III A4) Hence Flux of \vec{B} through any closed surface is zero

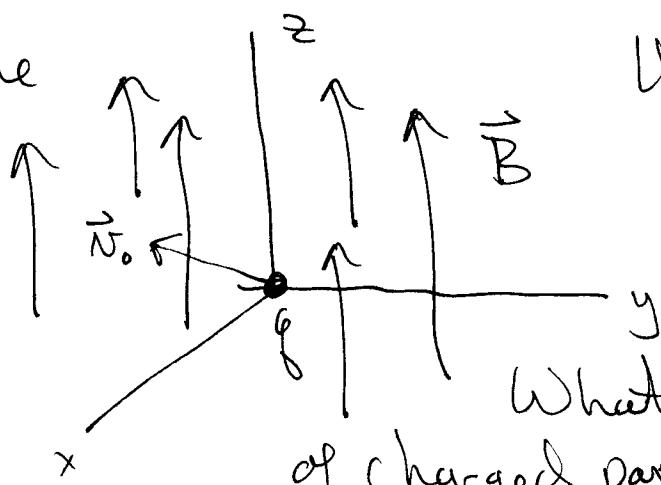
Fundamental Law
of Magnetism



$$\oint_S \vec{B} \cdot d\vec{A} = 0$$



b) Example



Uniform \vec{B} -field
in z -direction
 $\vec{B} = B \hat{k}$

What is trajectory
of charged particle?

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III B) Particle has charge q , mass m and at $t=0$ passes through origin with velocity \vec{v}_0

$$\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$$

So initial conditions are $\begin{cases} \vec{r}(0) = 0 \\ \frac{d\vec{r}}{dt}|_{t=0} = \vec{v}_0 \end{cases}$ six conditions

$$\Rightarrow \begin{aligned} x(0) &= 0 \\ y(0) &= 0 \\ z(0) &= 0 \end{aligned}$$

$$\begin{aligned} \frac{dx}{dt}|_{t=0} &= v_{0x} \\ \frac{dy}{dt}|_{t=0} &= v_{0y} \\ \frac{dz}{dt}|_{t=0} &= v_{0z} \end{aligned}$$

Newton's 2nd Law: $\vec{F} = m\vec{a}$

$$\vec{a} = \frac{d^2\vec{r}}{dt^2} = \frac{d^2x(t)}{dt^2}\hat{i} + \frac{d^2y(t)}{dt^2}\hat{j} + \frac{d^2z(t)}{dt^2}\hat{k}$$

and

$$\begin{aligned} \vec{F} &= q\vec{v} \times \vec{B} = q \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{dx}{dt} & \frac{dy}{dt} & \frac{dz}{dt} \\ 0 & 0 & B \end{vmatrix} \\ &= qB \left(\frac{dy}{dt}\hat{i} - \frac{dx}{dt}\hat{j} \right) \end{aligned}$$

- III B) Newton's Law \Rightarrow

$$\boxed{\begin{aligned} m \frac{d^2x(t)}{dt^2} &= g \vec{B} \frac{dy(t)}{dt} & -58- \\ m \frac{d^2y(t)}{dt^2} &= -g \vec{B} \frac{dx(t)}{dt} \\ m \frac{d^2z(t)}{dt^2} &= 0 \end{aligned}}$$

(see class notes)

Solve \Rightarrow

$$x(t) = \frac{N_0 y}{\omega} + \frac{N_0 x}{\omega} \sin \omega t - \frac{N_0 y}{\omega} \cos \omega t$$

$$y(t) = -\frac{N_0 x}{\omega} + \frac{N_0 y}{\omega} \sin \omega t + \frac{N_0 x}{\omega} \cos \omega t$$

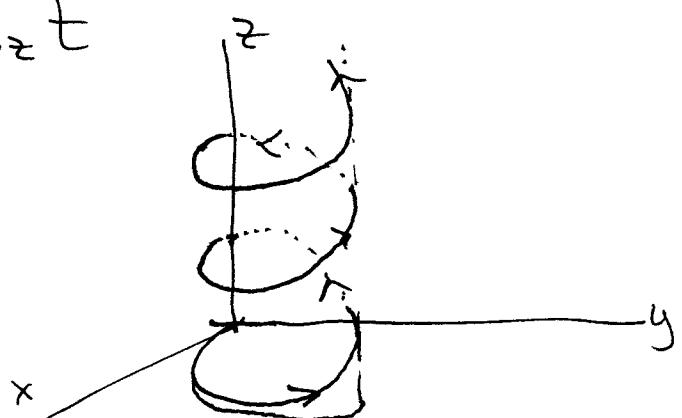
$$z(t) = N_0 z t$$

where $\omega \equiv \frac{g B}{m}$

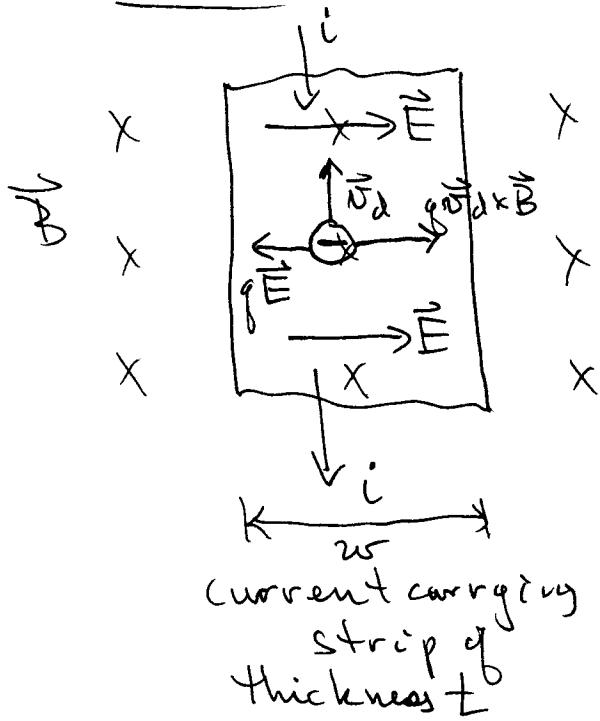
Trajectory is a helix:

$$(x(t) - \frac{N_0 y}{\omega})^2 + (y(t) + \frac{N_0 x}{\omega})^2 = \left[\frac{N_0^2 x^2 + N_0^2 y^2}{\omega^2} \right]$$

$$z(t) = N_0 z t$$



- III C) Hall Effect:



Potential difference across strip =
Hall Voltage $= V = E_w$

$$\begin{aligned} \text{At equilibrium} \\ 0 &= q \vec{E} + q \vec{v}_d \times \vec{B} \\ \Rightarrow E &= v_d B \end{aligned}$$

$$\begin{aligned} \text{Recall } j &= nev_d = \frac{i}{A} \\ &= \frac{i}{wt} \end{aligned}$$

So

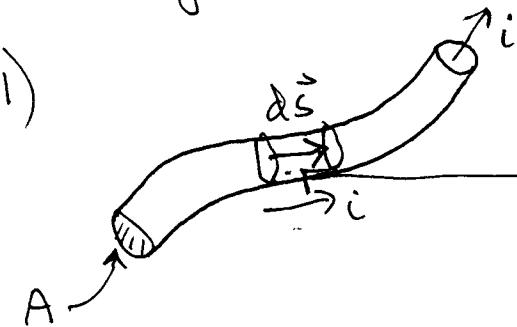
$$\begin{aligned} E &= \frac{V}{w} = v_d B = \frac{1}{ne} B = \frac{iB}{newt} \\ \Rightarrow n &= \frac{iB}{etV} \end{aligned}$$

density of charge carriers

Measure Hall Voltage \rightarrow if positive charge carriers are +ve
if negative charge carriers are -ve.

III) Magnetic Force on a Current

1)



$$\text{charge } dq = nA \, ds \, lg$$

$$d\vec{F} = dq \, \vec{l} \times \vec{B}$$

$$= nAq \, l \, ds \, \vec{l} \times \vec{B}$$

$$\text{But } ds \parallel \vec{l} \Rightarrow$$

$$d\vec{F} = nA \, l \, \vec{l} \, lg \, ds \times \vec{B}$$

$$\text{Recall } i = nq \, l \, \vec{l} \, l \, A \Rightarrow$$

$$\boxed{d\vec{F} = i \, ds \times \vec{B}}$$

the

magnetic force exerted on wire segment ds

2) Straight wire segment of length L



$$\vec{F} = \int d\vec{F} = i \left(\int_0^L ds \right) \times \vec{B}$$

$$= iL \times \vec{B} \quad \text{a sideways force.}$$

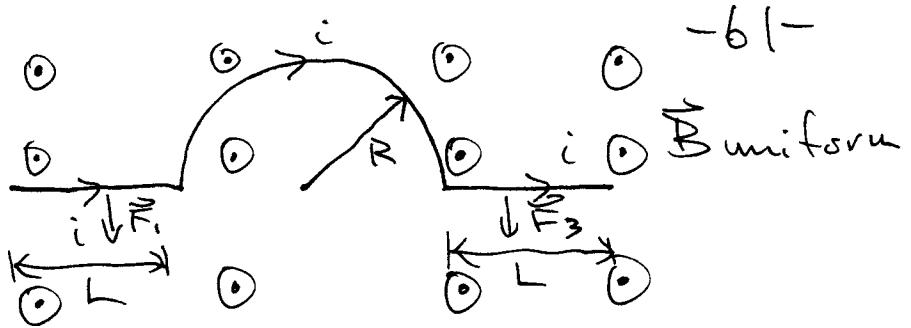
3) Closed Loop in a constant \vec{B} -field



$$\vec{F} = \oint_C d\vec{F} = i \left(\oint_C ds \right) \times \vec{B} = 0.$$

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- III D) 4.) Example:



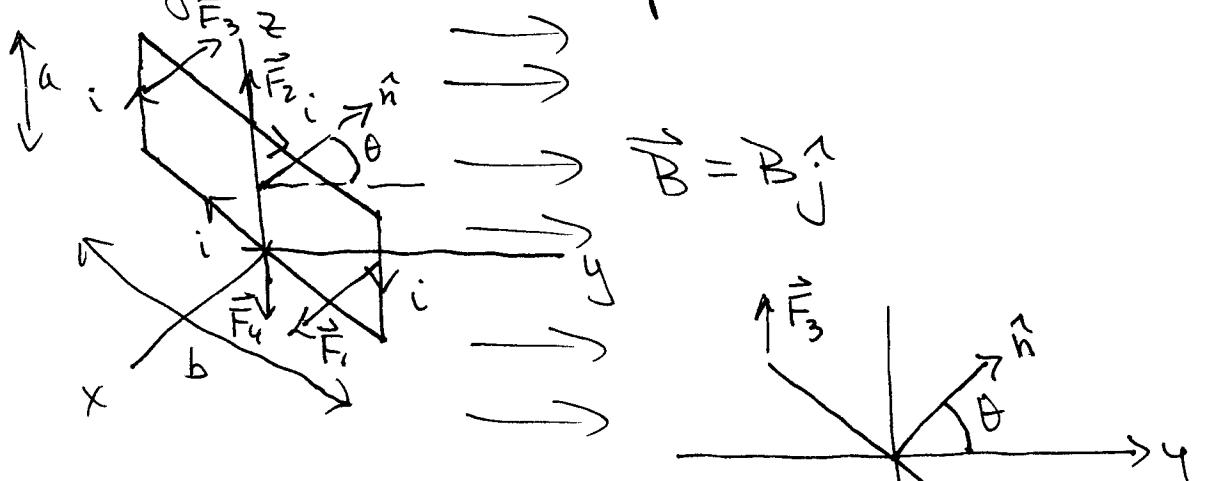
$$F_1 = F_3 = iL\vec{B} \text{ pointing down}$$

$$\begin{aligned} F_2 &= \int_{\theta=0}^{\pi} dF \sin \theta = iBR \int_{\theta=0}^{\pi} \sin \theta d\theta \\ &= 2iBR \text{ pointing down} \end{aligned}$$

Total force $\vec{F} = (2L + 2R)\vec{i}\vec{B}$ pointing down

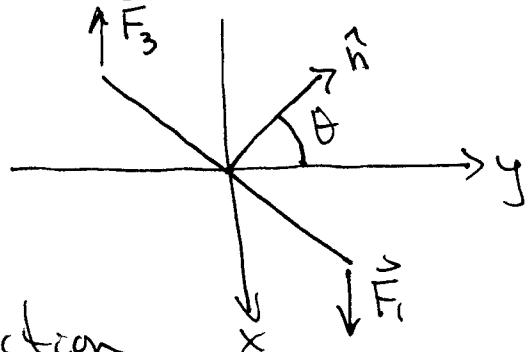
E) Torque Due to Magnetic Field

1) Rectangular Current loop in uniform \vec{B} -field



$$\vec{F}_2 = i b B \cos \theta \hat{k} = -\vec{F}_4$$

No torque since same line of action



- III.E.1) $\vec{F}_1 = iab\hat{i} = -\vec{F}_3$ produce torque since they act as a couple.

$$\vec{\tau} = \frac{b}{2} F_1 \sin\theta (-\hat{k}) + \frac{b}{2} F_3 \sin\theta (-\hat{k})$$

$$\vec{\tau} = iabB \sin\theta (-\hat{k})$$

$$\vec{\tau} = iA B \sin\theta (-\hat{k}) \quad A = ab = \text{area of loop}$$

For N-turns of wire

$$\vec{\tau} = NiA B \sin\theta (-\hat{k}) \quad \text{this result is true for any shaped planar area } A.$$

The normal \hat{n} to loop points in direction determined by right hand rule applied to direction of current flow about perimeter

Define Magnetic Dipole Moment

$$\boxed{\vec{\mu} = NiA \hat{n}}$$

Then

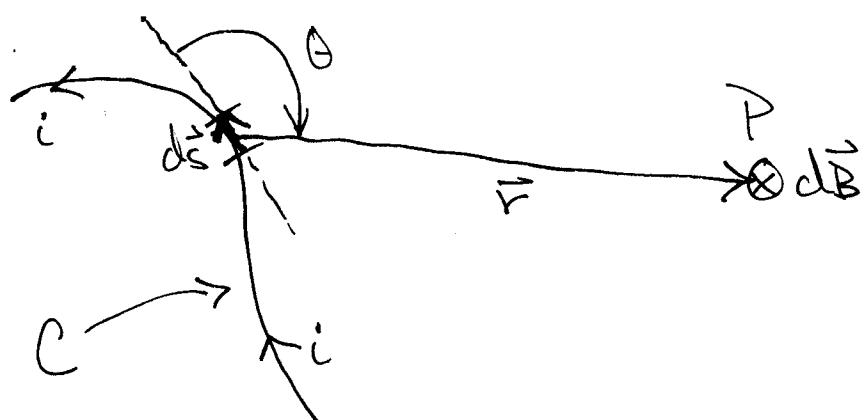
$$\boxed{\vec{\tau} = \vec{\mu} \times \vec{B}}$$

- III. E.2.) Potential energy of magnetic dipole in magnetic field \vec{B}

$$U(\theta) = -\vec{\mu} \cdot \vec{B}$$

IV) Magnetostatics: (Steady currents)

A) Biot-Savart Law



$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{i d\vec{s} \times \vec{r}}{r^3}$$

(SI: $\mu_0 = 4\pi \times 10^{-7} \frac{\text{T} \cdot \text{m}}{\text{A}}$
 μ_0 = permeability of free space)

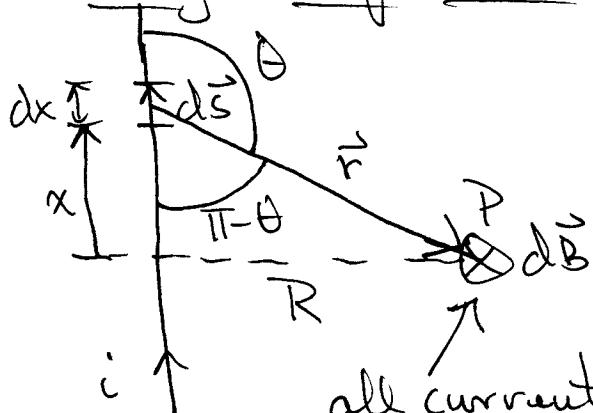
Magnetic Field at point P due to $i d\vec{s}$ current element

$$\vec{B} = \int_C d\vec{B} = \frac{\mu_0}{4\pi} \int_C \frac{i d\vec{s} \times \vec{r}}{r^3}$$

Magnetic Field at point P due to current carrying wire C.

IV B) Examples:

i) Long Straight Wire



Magnitude of $d\vec{B}$ at P

$$dB = \frac{\mu_0 i}{4\pi} \frac{ds \sin \theta}{r^2}$$

$$= \frac{\mu_0 i}{4\pi} \frac{dx \sin \theta}{r^2}$$

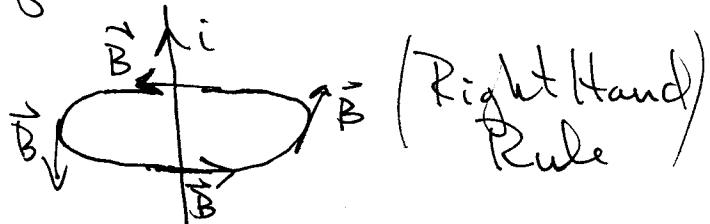
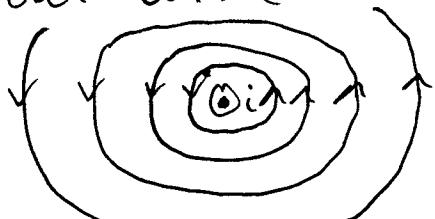
all current elements $i ds$ produce $d\vec{B}$'s in the same direction - into page — So just add up magnitudes — scalar integral

$$B = \int_{x=-\infty}^{+\infty} dB = \frac{\mu_0 i}{4\pi} \int_{x=-\infty}^{+\infty} \frac{\sin \theta}{r^2} dx$$

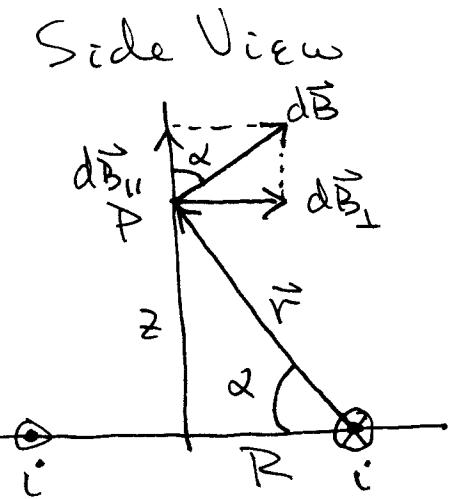
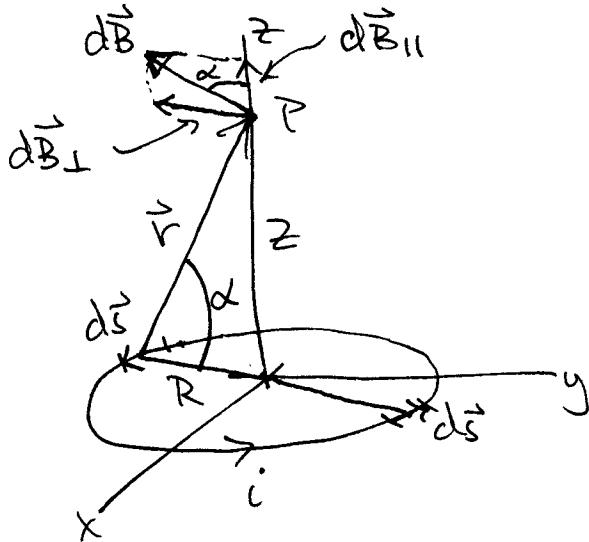
where $r = \sqrt{R^2 + x^2}$, $\sin \theta = \sin(\pi - \theta)$
 $= \frac{R}{\sqrt{R^2 + x^2}}$

$\Rightarrow B = \frac{\mu_0 i}{2\pi R}$ and points into page

By symmetry, lines of \vec{B} form circles about wire



- IV B2) Circular Current Loop



By symmetry only $d\vec{B}_{||}$ will contribute to the total \vec{B} at P the $d\vec{B}_{\perp}$ contributions cancell out.

$$\vec{B} = B \hat{k}$$

$$B = \int_C d\vec{B}_{||} = \frac{\mu_0 i}{4\pi} \int_C \frac{\sin\theta ds}{r^2} \frac{\cos\alpha}{r}$$

$$\theta = 90^\circ ! \text{ so } \sin\theta = 1$$

for $d\vec{B}_{||}$

$$\text{and } r = \sqrt{R^2 + z^2} ; \cos\alpha = \frac{R}{r} = \frac{R}{\sqrt{R^2 + z^2}}$$

Hence

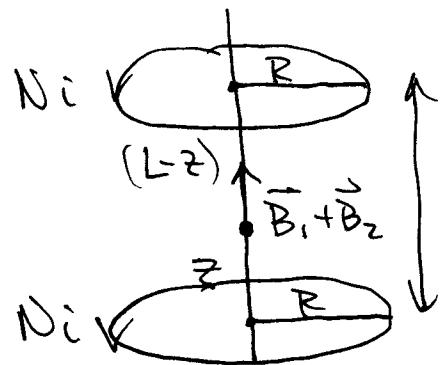
$$B = \frac{\mu_0 i}{4\pi} \left(\frac{1}{R^2 + z^2} \right) \left(\frac{R}{\sqrt{R^2 + z^2}} \right) \int_C ds$$

$$\Rightarrow \boxed{\vec{B} = \frac{\mu_0 i R^2}{2(R^2 + z^2)^{3/2}} \hat{k}}$$

$$= 2\pi R$$

- IV B2a) Far from loop, $z \gg R$, $B \approx \frac{\mu_0 i R^2}{2z^3}$ - 66-
- For N-turns of wire, $B = \frac{\mu_0 N i R^2}{2z^3}$
- Dipole moment of coil $\mu = NiA = Ni\pi R^2$
 $\Rightarrow B = \frac{\mu_0}{2\pi} \frac{\mu}{z^3}$ dipole moment.

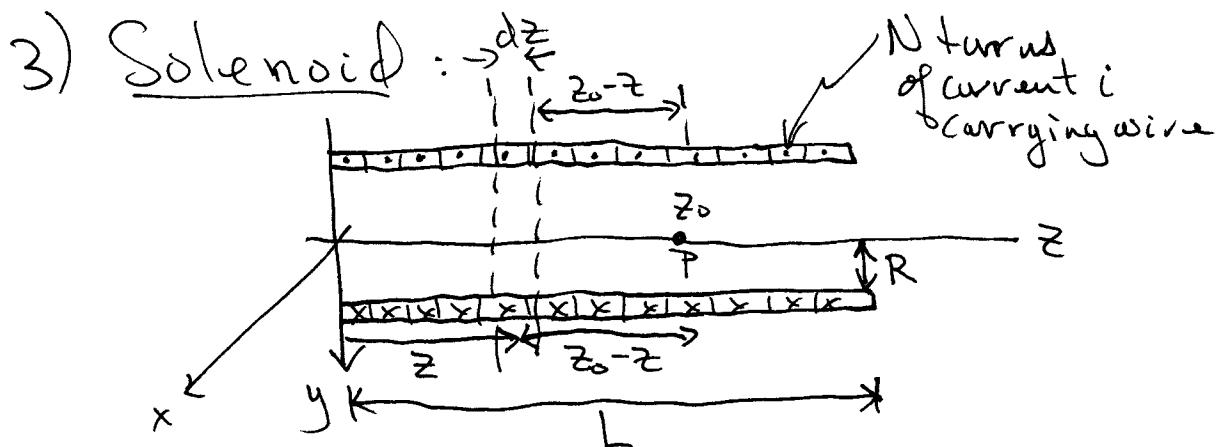
b) Helmholtz Coils:



$$B = B_1 + B_2$$

$$\vec{B} = \frac{\mu_0 NiA}{2\pi} \frac{1}{R} \times$$

$$\times \left[\frac{1}{(R^2+z^2)^{3/2}} + \frac{1}{(R^2+(L-z)^2)^{3/2}} \right]$$



Infinitesimal slice of solenoid acts like current loop $di = Ni \frac{dz}{L}$

-67

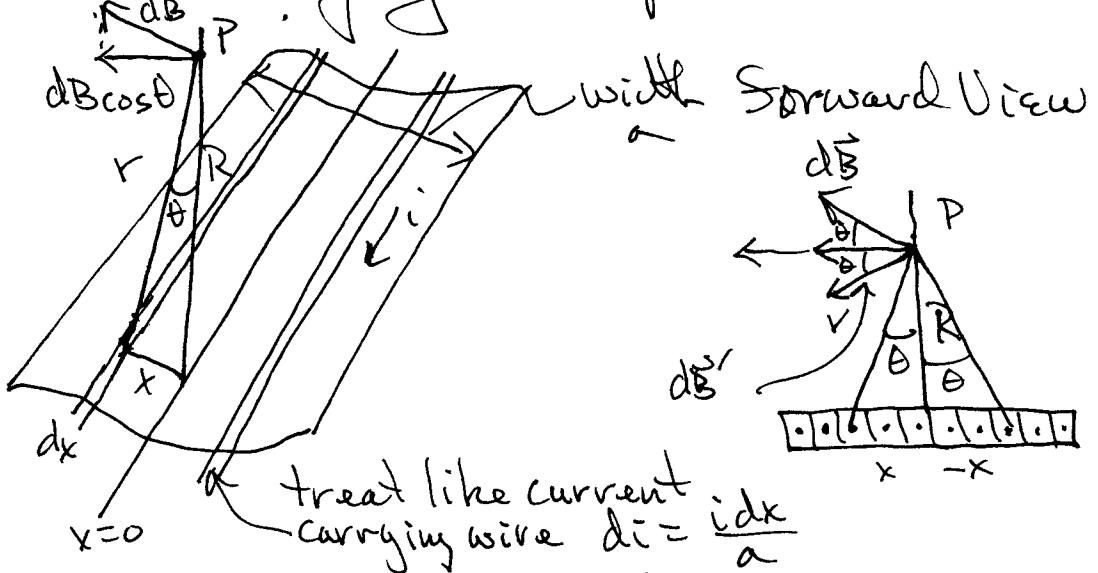
- IVB3) \vec{B} is in the z -direction with magnitude

$$\begin{aligned} B(z_0) &= \frac{\mu_0 Ni R^2}{2L} \int_{z=0}^L \frac{dz}{[R^2 + (z_0 - z)^2]^{3/2}} \\ &= \frac{\mu_0 Ni}{L} \cdot \frac{1}{2} \left[\frac{1}{\sqrt{1 + \left(\frac{R}{L-z_0}\right)^2}} + \frac{1}{\sqrt{1 + \left(\frac{R}{z_0}\right)^2}} \right] \end{aligned}$$

a) For $R \ll L$ and $z_0 = \frac{L}{2}$

$$B(z_0 = \frac{L}{2}) \approx \frac{\mu_0 Ni}{L} \cdot \left[1 - \frac{2R^2}{L^2} \right]$$

4) Current Carrying Strip



By symmetry only horizontal component of $d\vec{B}$ contributes to total \vec{B} at P , vertical components cancel

- II B4) So again the horizontal magnitude is

$$B = \int dB \cos\theta$$

$$= \frac{\mu_0}{2\pi} \int \frac{di}{r} \cos\theta$$



But $r \cos\theta = R$
and $x = R \tan\theta$

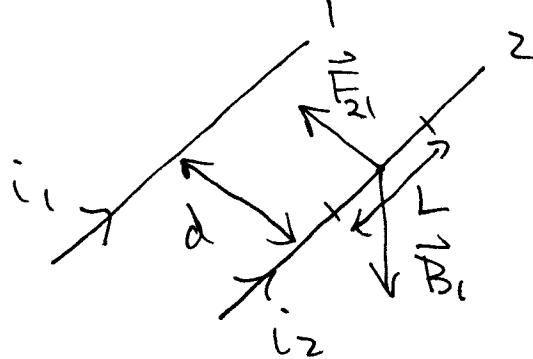
$$B = \frac{\mu_0}{2\pi R a} \frac{i}{a} \int_{-a/2}^{+a/2} \frac{dx}{\sec^2\theta} = \frac{\mu_0 i}{2\pi a} 2a$$

where $\tan\theta = \frac{a}{2R}$

So

$$\boxed{B = \frac{\mu_0 i}{\pi a} \tan^{-1} \frac{a}{2R}}$$

5) 2-Parallel Conductors:



$$B_1 = \frac{\mu_0 i_1}{2\pi d}$$

$$\begin{aligned} \Rightarrow F_{21} &= i_2 L B_1 \\ &= \frac{\mu_0 L i_1 i_2}{2\pi d} \end{aligned}$$

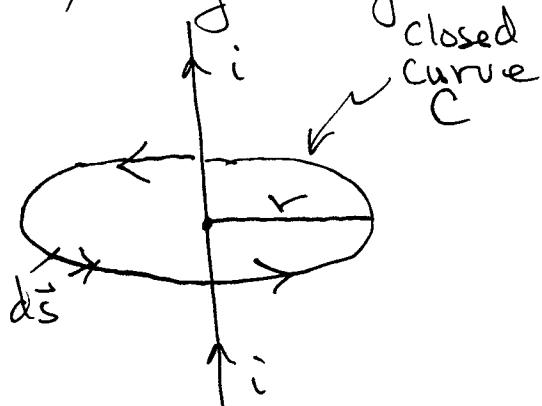
Likewise $F_{12} = \frac{\mu_0 L i_1 i_2}{d}$ pointing towards
wire 2.
Attraction

IVB5) This force law is used to define the unit of current - ampere

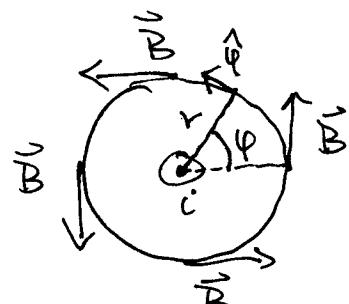
"Given 2 long parallel wires of negligible circular cross section separated in vacuum by a distance of 1 meter, the ampere is defined as the current in each wire that would produce a force of 2×10^{-7} newtons/meter of length."

c) Amperes Law

i) Long Straight Wire



$$\vec{B} = \frac{\mu_0 i}{2\pi r} \hat{\phi} \text{ at points on circle}$$



$$\begin{aligned} d\vec{s} &= \text{element of path along circle} \\ &= r d\phi \hat{\phi} \end{aligned}$$

$$\Rightarrow \oint_C \vec{B} \cdot d\vec{s} = \oint_C \left(\frac{\mu_0 i}{2\pi r} \hat{\phi} \right) \cdot (r d\phi \hat{\phi})$$

- $\text{II C. 1) } \oint_C \vec{B} \cdot d\vec{s} = \int_{\varphi=0}^{2\pi} \frac{\mu_0 i}{2\pi} d\varphi = \mu_0 i$

$$= \mu_0 i$$

2) Ampere found this is generally true

Ampere's Law

$$\oint_C \vec{B} \cdot d\vec{s} = \mu_0 i_{\text{enclosed}}$$

a) C is closed curve called "Amprian loop"

b) $i_{\text{enclosed}} =$ net current that flows through surface bounded by C.

c)



i_{enclosed}

$$= i_1 + i_3 - i_2 - i_4$$

Right Hand Rule: fingers in direction of C, thumb points in "positive" current direction.

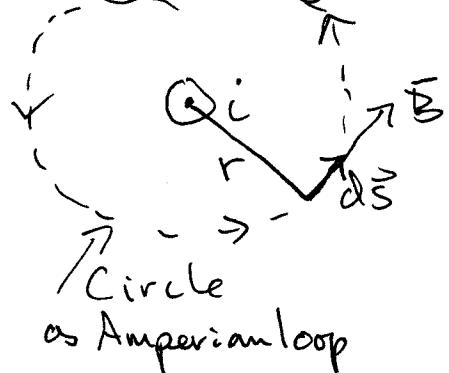
d) Ampere's Law replaces Biot-Savart law as one of the fundamental laws

->1-

IV C.2d) of magnetostatics.

3) Examples:

a) Long Straight Wire: By symmetry: $\vec{B} = B(r)\hat{\phi}$



Amper's Law

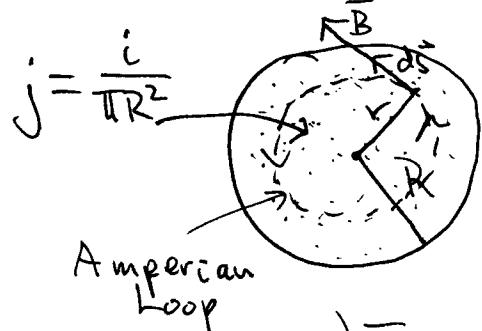
$$\oint_C \vec{B} \cdot d\vec{s} = \mu_0 i_{\text{enclosed}}$$

$$= \mu_0 i$$

$$B(r) \int r dr \phi = B(r) 2\pi r$$

$$\Rightarrow \boxed{\vec{B} = \frac{\mu_0 i}{2\pi r} \hat{\phi}}$$

b) Long cylindrical wire of radius R with i uniformly spread over cross section



By symmetry $\vec{B} = B(r)\hat{\phi}$

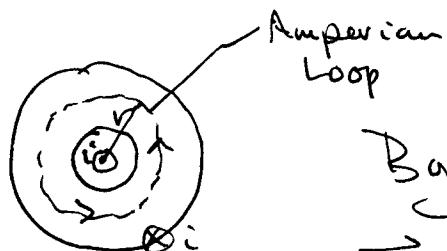
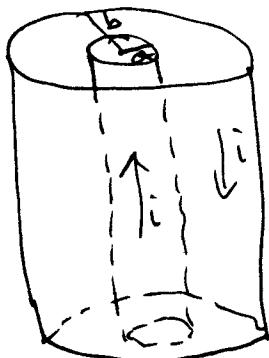
$$\text{Amper's Law } \oint_C \vec{B} \cdot d\vec{s} = \mu_0 i_{\text{enclosed}}$$

$$\text{a) For } r \leq R: B(r)(2\pi r) = \mu_0 \left(\frac{i}{\pi R^2}\right) (\pi r^2)$$

$$\Rightarrow \boxed{\vec{B} = \frac{\mu_0 i}{2\pi} \frac{r}{R^2} \hat{\phi}}$$

- IV.C3b) b) For $r \geq R$: $\vec{B} = \frac{\mu_0 i}{2\pi r} \hat{\phi}$.

c) Coaxial Cable



By symmetry
 $\vec{B} = B(r) \hat{\phi}$

Ampere's Law:

$$\oint_C \vec{B} \cdot d\vec{s} = 2\pi r B(r) = \mu_0 i_{\text{enclosed}}$$

$$= \mu_0 \begin{cases} i & a < r < b \\ 0 & r > b \end{cases}$$

\Rightarrow

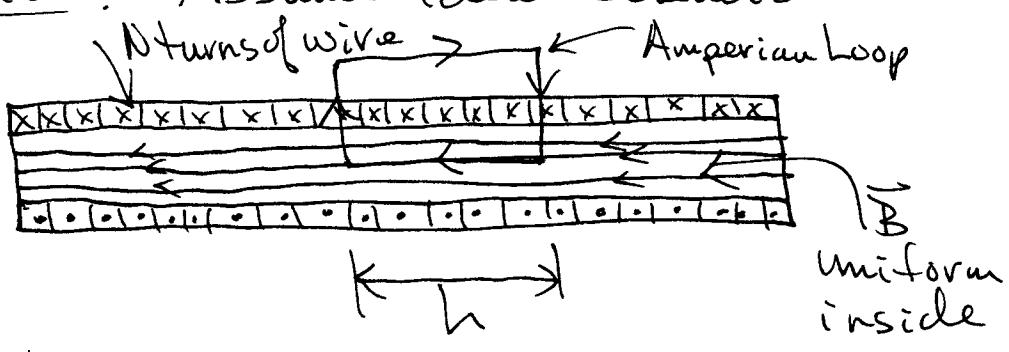
$$B(r) = \begin{cases} \frac{\mu_0 i}{2\pi r} & a < r < b \\ 0 & r > b \end{cases}$$

D) Solenoid : Assume ideal solenoid

Assume $B = 0$ outside

to a good approximation

(true for infinitely long solenoid)



Uniform inside

->3-

- III C.3.D) Ampere's Law:

$$\oint_C \vec{B} \cdot d\vec{s} = B h + 0 + 0 + 0$$

$\Rightarrow \vec{B} \cdot d\vec{s} = 0$ outside here
 $\Rightarrow \vec{B} \cdot d\vec{s} = 0$ here

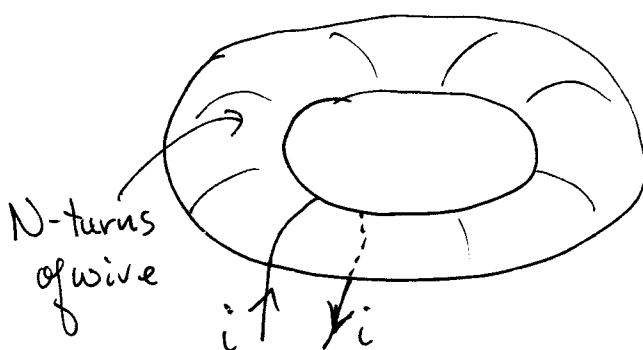
$$= \mu_0 i_{\text{enclosed}} = \mu_0 i \frac{N}{L} \cdot h$$

\Rightarrow

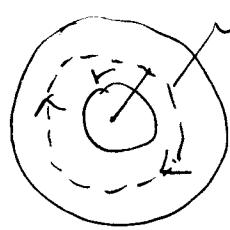
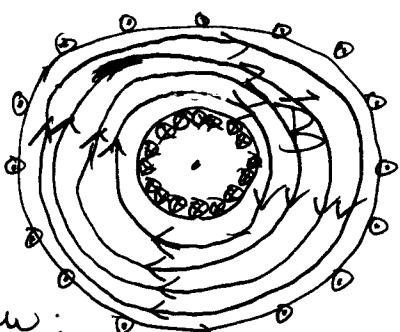
$$\boxed{\vec{B} = \mu_0 i \frac{N}{L} = \mu_0 i n}$$

$n = \frac{\# \text{ of turns}}{\text{unit length}}$

E.) Toroid:



\vec{B} -lines form concentric circles inside toroid



Amperian loop

$$\oint_C \vec{B} \cdot d\vec{s} = B(r) 2\pi r$$

$$= \mu_0 i_{\text{enclosed}}$$
$$= \mu_0 i N$$

-24-

- III C3 E) Toroid:

$$\boxed{B(r) = \frac{\mu_0 i N}{2\pi r}}$$

V.) Electromagnetic Induction

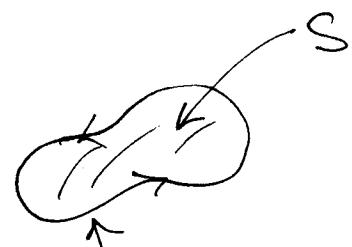
A) Faraday's Law: (emf form)

The induced emf in a circuit is equal to the negative of the rate at which the magnetic flux through the circuit is changing with time.

$$E = - \frac{d\Phi_B}{dt}$$

i) Magnetic flux through open surface S bounded by

$$\Phi_B = \int_S \vec{B} \cdot d\vec{A}$$



a) SI unit: $[\Phi_B] = 1 \text{ T} \cdot \text{m}^2 \equiv 1 \text{ weber (Wb)}$

I. A) 2) Lenz' Law: The induced current in a closed conducting loop appears in such a direction that it opposes the change that produced it. (This is the minus sign in Faraday's Law)

3) emf $\mathcal{E} = \oint_C \vec{f} \cdot d\vec{s}$ where \vec{f} is the total force per unit charge acting on the charges in a circuit. In general $\vec{f} = \vec{f}_s + \vec{E}$ where \vec{f}_s is the force per unit charge the localized sources of emf (i.e. battery, solar cell, generator etc.) exert on charges in the circuit.

In electrostatics the \vec{E} -field is conservative, hence $\oint_C \vec{E} \cdot d\vec{s} = 0$, so for DC circuits:

$$\mathcal{E} = \oint_C \vec{f}_s \cdot d\vec{s} = \int_{\text{source}} \vec{f}_s \cdot d\vec{s} = \frac{dW}{dq}$$

Faraday discovered that time varying magnetic flux produced a non-conservative electric field in a closed circuit

$$\mathcal{E} = \oint_C \vec{E} \cdot d\vec{s} = - \frac{d}{dt} \phi_B$$

->6-

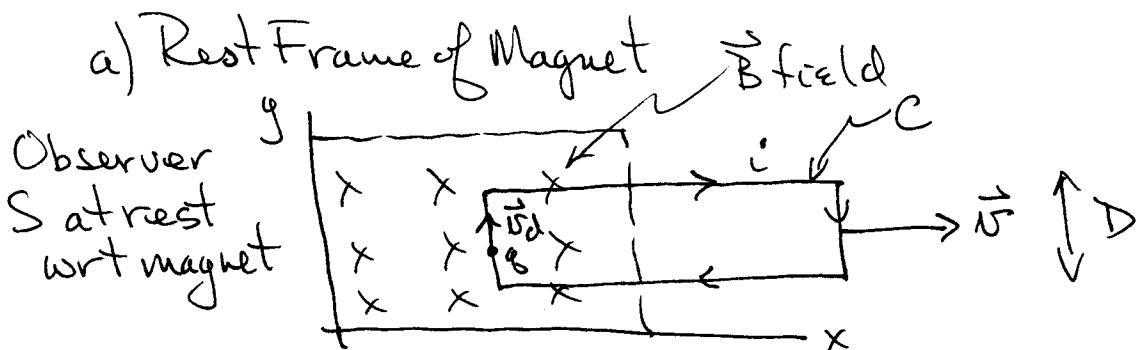
II. B) Faraday's Law: (induced electric field form)

$$\oint_C \vec{E} \cdot d\vec{s} = - \frac{d}{dt} \int_S \vec{B} \cdot d\vec{A}$$

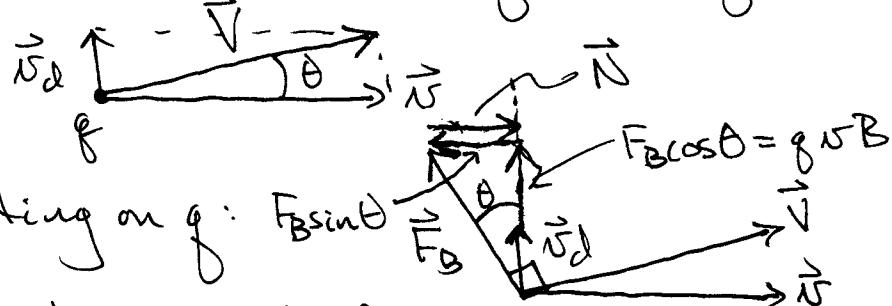
- 1) Lenz' Law (Revisited): The induced electric field has direction so as to oppose the change that produces it.
- 2) The closed curve C is any arbitrary closed curve, not just physical circuits, S is any open surface with C as its boundary.
- 3) Time varying magnetic fields produce electric fields!
- 4) The induced electric field is not conservative $\oint_C \vec{E} \cdot d\vec{s} \neq 0$
- 5) Induced electric field lines form closed loops
- 6) Faraday's law of electromagnetic induction, $\oint_C \vec{E} \cdot d\vec{s} = - \frac{d}{dt} \int_S \vec{B} \cdot d\vec{A}$, is one of the fundamental laws of electromagnetism (it is one of the 4 Maxwell equations)

I. C) Examples:

1) Motional emf: Relative motion of \vec{B} -field and circuit produce emf



Lorentz force $\vec{F}_B = q \vec{v} \times \vec{B} = q \vec{v} \times \vec{B} + q \vec{v}_d \times \vec{B}$



Forces acting on q: $F_B \sin \theta \hat{i}$

Wire exerts normal force
on charges to keep them inside wire

$$\vec{N} = -q \vec{v}_d \times \vec{B} = F_B \sin \theta \hat{i} = q v_d B \hat{i}$$

Only $F_B \cos \theta$ is component of force along wire
So

$$E = \oint_C \vec{f} \cdot d\vec{s} = \oint_C \vec{N} \times \vec{B} \cdot d\vec{s}$$

$$= N B D \quad (\text{top \& bottom paths give 0 and right side } B=0)$$

only from left side of C

IV.C. 1) Now the work done on the charges in the circuit is supplied by the external agent pulling the loop with force \vec{N} . In time Δt the charge moves

$$d\vec{s} = \vec{V} dt = (\vec{v} + \vec{v}_d) dt$$

So the work done by the force \vec{N} is

$$dW = \vec{N} \cdot d\vec{s} = N v dt$$

$$\text{But } N = F_B \sin \theta = qVB \sin \theta = qVB \left(\frac{v_d}{V} \right)$$

$$= qv dB$$

So

$$dW = qv dB v dt = qvB (v dt)$$

*This is just
the distance
the charge moves up the left
side of the wire.*

Hence

$$W = \oint_C dW = qvB D$$

(again top &
bottom paths
give 0, and
 $B=0$ for Right
hand side)

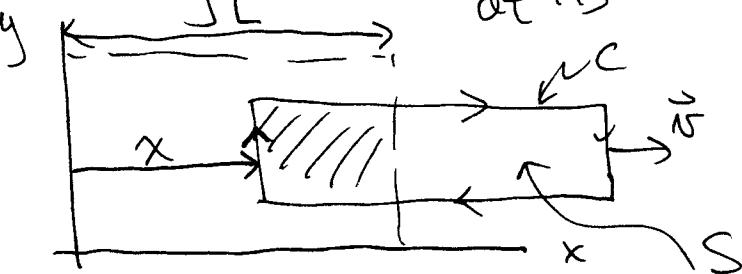
The work done per unit charge
is just equal to the sum above

$$E = \frac{dW}{dq} = vBD \quad \text{as we found above.}$$

The emf E is produced by the magnetic force of $v \times B$,
the Work W performed is done by the pulling force, N ,
yet $E = \frac{dW}{dq}$.

II C.1a) This is the same result we obtain by applying the ent form of Faraday's Law directly

$$\mathcal{E} = - \frac{d}{dt} \phi_B$$



$$\phi_B = \int_S \vec{B} \cdot d\vec{A} = BD(L-x) \quad (\text{shaded portion has } B \neq 0 \text{ only})$$

So

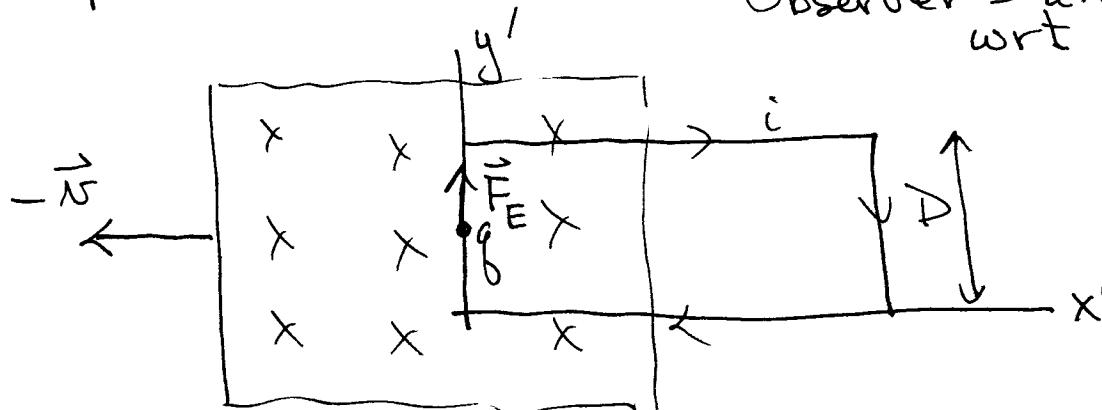
$$\frac{d\phi_B}{dt} = BD \left(-\frac{dx}{dt} \right) = -BDv$$

Faraday's Law: $\mathcal{E} = - \frac{d\phi_B}{dt} = +BDv \quad \checkmark$

agrees with our force analysis.

b.) Rest frame of wire loop: magnet moves past with $-\vec{v}$

Observer S' at rest wrt loop



Current i still flows in loop, the same emf will occur in circuit (for $v < c$) since the relative motion in the 2 cases

- $\vec{J}C(b)$ is the same. But there is no magnetic force in this frame $\vec{N}' \times \vec{B} = 0$ since $\vec{v}' = 0$, the wire is at rest. Can only conclude the current flows due to an induced \vec{E} -field, \vec{E}' , in the wire

$$\mathcal{E}' = \oint_C \vec{E}' \cdot d\vec{s} = E' D$$

(same current so $E' = E$)

$$= E = NBD \quad (N \ll c)$$

$$\Rightarrow E' = N B \quad \text{or in terms of vectors}$$

see, $\vec{E}' = \vec{v} \times \vec{B}$: Observer S' related to Observer S's \vec{B} -field.

- c.) Observer S: stationary wrt magnet
Says the force on the charges arises from magnetic field with

$$E = \oint_C (\vec{v} \times \vec{B}) \cdot d\vec{s}$$

Observer S': stationary wrt loop
attributes current to electric field \vec{E}' with

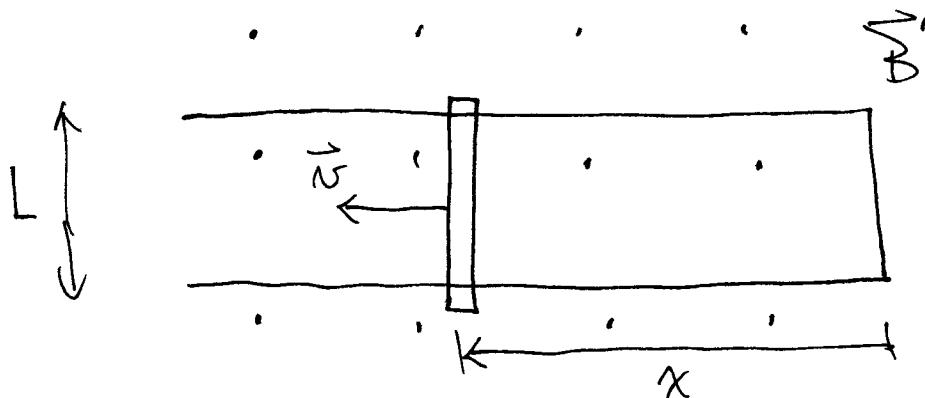
$$\mathcal{E}' = \oint_C \vec{E}' \cdot d\vec{s}$$

IV(c) "Third observer S": Magnet and loop moving
 Force on charges both electric and magnetic
 $\vec{F}_q = \vec{E}'' + \vec{v}'' \times \vec{B}''$

Conclusion: 1) \vec{E} and \vec{B} are not independent of each other and have no separate unique existence, they depend on the inertial frame.

- 2) Still we find Faraday's Law holds in all inertial frames - it is covariant - that is form invariant

- 2) A conducting rod of length L is pulled along conducting rails at velocity \vec{v} with a uniform \vec{B} field \perp to it.



a) Induced emf in the rod : $\phi_B = BLx$

(magnitude) $E = \frac{d\phi_B}{dt} = BL \frac{dx}{dt}$

$= BLv$ (minus sign: Lenz law)
 current flows CW

- II C.2)b) Resistance of rod is R and rails negligible
What is current?

$$i = \frac{\epsilon}{R} \quad (\text{Lenz' Law: flows CW})$$

- c) What rate is internal energy being
created in rod?

$$P = i^2 R$$

- d) What is the force that must be applied by
an external agent to the rod to
maintain its motion?

Current in rod feels force

$$\vec{F} = i \vec{L} \times \vec{B}$$

$$\Rightarrow F = iLB \quad \text{to the right.}$$

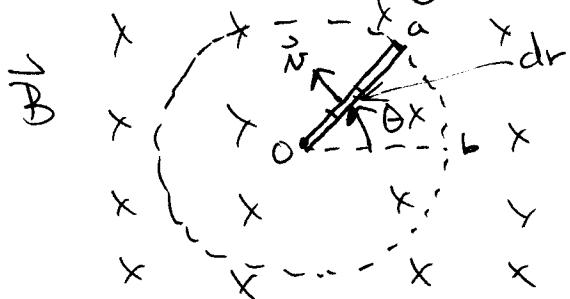
So agent must pull to the left with
force $F = iLB$.

- e) At what rate does this force do work
on the rod?

$$P = FN = iLBN = i\epsilon$$

$= i^2 R$. External agent's
work eventually appears as Joule heating.

- IC.3) A copper rod of length R rotates at angular frequency ω in a uniform \vec{B} -field. Find the emf E developed between the 2 ends of the rod.



A motional emf dE develops across element dr of the rod as it moves with velocity v .

Charge separation produces an \vec{E} -field across dr at steady state $v \times \vec{B} = -\vec{E} \Rightarrow E = vB = \omega r B$

The potential across dr is $E dr$ - these add up like batteries in series

$$E = \int_0^R E dr = \omega B \int_0^R r dr = \frac{1}{2} \omega B R^2$$

$E = \frac{1}{2} \omega B R^2$

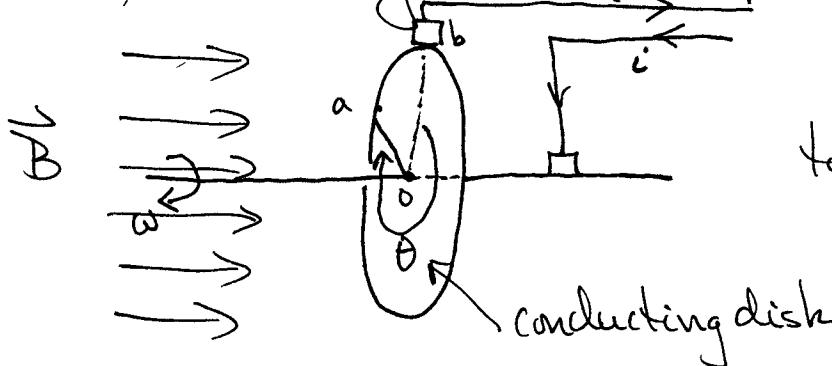
As well, directly from Faraday's Law we find the flux through a loop

$$\Phi_B = \int_S \vec{B} \cdot d\vec{A} = B \left(\frac{1}{2} R^2 \theta \right)$$

$$\frac{d\Phi_B}{dt} = \frac{1}{2} B R^2 \frac{d\theta}{dt} = \frac{1}{2} B R^2 \omega$$

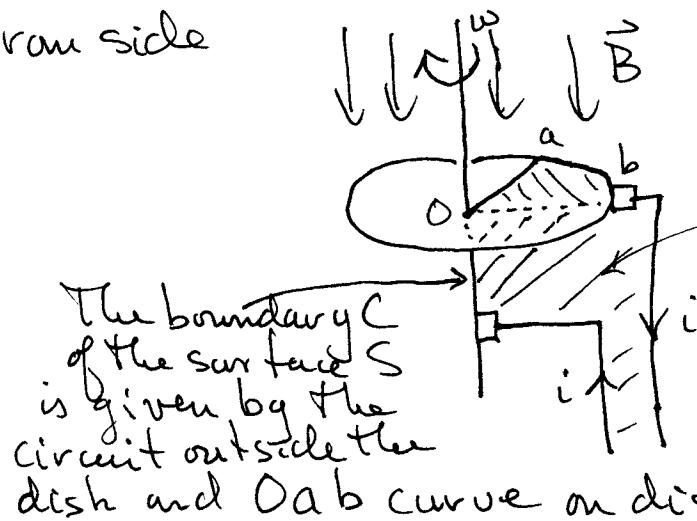
So the magnitude of $E = \frac{d\Phi_B}{dt} = \frac{1}{2} B R^2 \omega$ ✓

- I.C.4.) Faraday Disk (Homopolar Generator)



Use Faraday's law
to find the emf
produced by the
spinning rotor

View from side



The boundary C
of the surface S
is given by the
circuit outside the
disk and Oab curve on disk

Open
Surface S is
formed by these
2 planar surfaces
meeting at
right angles

$$\text{The flux } \Phi_B = \int_S \vec{B} \cdot d\vec{A} = \frac{1}{2} BR^2(2\pi - \theta) + Q$$

↑
 B Through area
 Oab Q on
 disk

for rest of
 circuit
 for which
 either $\vec{B} = 0$
 or $\vec{B} \cdot d\vec{A} = 0$

Hence the emf by Faraday's Law
is

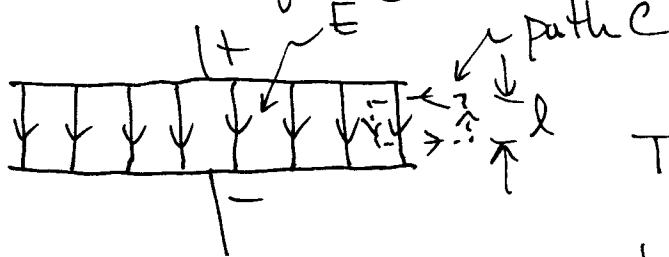
$$\mathcal{E} = -\frac{d\Phi_B}{dt} = \frac{1}{2} \omega BR^2 = \pi BR^2 V$$

(where $V = \frac{\omega}{2\pi}$)

V C.4) The torque that must be provided to keep the rotor spinning when current i is produced is found from

$$\text{Power} = \dot{E}_i \quad \text{also} \quad \text{Power} = \gamma \omega$$
$$\Rightarrow \gamma = \frac{\dot{E}_i}{\omega} = \frac{1}{2} B R^2 i$$

5) \vec{E} -must fringe for a II-plate capacitor



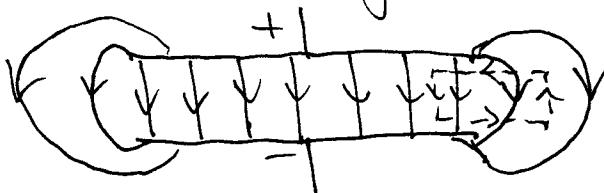
Assume no fringing
There is no \vec{B} -field
in this problem so
 $\phi_B = 0$; $\frac{d\phi_B}{dt} = 0$

$$\Rightarrow E = 0 \quad \text{by Faraday's law}$$

but $E = \oint_C \vec{E} \cdot d\vec{s} = El = 0$

$$\Rightarrow E = 0 \quad \underline{\text{contradiction!}}$$

\vec{E} must fringe so that $E = \oint_C \vec{E} \cdot d\vec{s} = 0$



VI) Magnetic Properties of Matter

A) Material placed in a magnetic field is either

1) Diamagnetic: when placed in an external magnetic field \vec{B}_0 , it tends to lessen the resultant field \vec{B} . It is repelled from a region of greater magnetic field to lesser magnetic field.

2) Paramagnetic: when placed in an external magnetic field \vec{B}_0 , it tends to increase the resultant \vec{B} -field. It is attracted toward a region of greater magnetic field from lesser magnetic field.

a) Ferromagnetic: when placed in an external magnetic field \vec{B}_0 , it greatly increases ($\approx 10^2$) the resultant magnetic field \vec{B} .

B) Magnetic properties are due to atomic motion of electron clouds swirling about nucleus and electrons having intrinsic spin. This spin and orbital motion of the electrons results in atomic magnetic moments ("atomic currents")

1) No net magnetic moment results in diamagnetic properties — in an external \vec{B} -field a magnetic moment is induced in the opposite direction to \vec{B}_0 .

VI) B₂) Net magnetic moment results in paramagnetic material - in an external \vec{B} -field the magnetic moments tend to align along the direction of \vec{B}_0 .

C) Magnetization, \vec{M} , is the dipole moment per unit volume at each macroscopic point of the material → characterizes all macroscopic magnetic properties of the material.

$$\vec{M} = \lim_{\Delta V \rightarrow 0} \frac{\langle \vec{\mu} \rangle}{\Delta V}$$

where $\langle \vec{\mu} \rangle$ is the average over the magnetic dipole moments of all the many atoms in the macroscopically small, but microscopically large, volume element ΔV of material

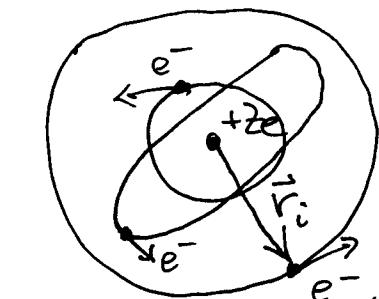
$$\langle \vec{\mu} \rangle = \sum_a^{\text{atoms in } \Delta V} \vec{\mu}_a .$$

If each $\vec{\mu}_a \approx \vec{\mu}$, then $\vec{M} = N \vec{\mu}$ where
 $N = \frac{\# \text{ of atoms}}{\text{Volume}}$

i) SI units of \vec{M} are $\frac{\text{Amperes}}{\text{meter}}$

- VI D) Microscopic View of Magnetic Materials:
 Use simplified planetary model of atom

1)



circular orbits
 $\vec{v}_i = \vec{\omega}_i \times \vec{r}_i$

i^{th} electron at radius \vec{r}_i with velocity $\vec{v}_i \Rightarrow$ atomic current

$$i = \frac{e v_i}{2\pi r_i} = \frac{e \omega_i}{2\pi} = \frac{dq}{dt}$$

and $\tau = \frac{2\pi}{\omega} = \text{time to make one orbit.}$

This current has an associated magnetic dipole moment

$$\text{magnitude : } \mu_i = iA = i\pi r_i^2$$

$$= \frac{e \omega_i}{2\pi} \pi r_i^2$$

$$= \frac{1}{2} \left(\frac{e}{m} \right) \underbrace{(m \omega_i r_i^2)}_{= L_i}$$

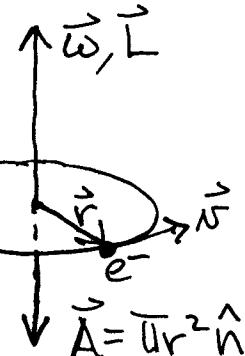
$$\mu_i = \frac{1}{2} \frac{e}{m} L_i$$

\vec{L}_i = orbital \vec{p} momentum of i^{th} electron

$$(\vec{L} = \vec{F} \times \vec{p} = m\vec{r} \times \vec{v} = m\vec{r} \times (\vec{\omega} \times \vec{r}) = mr^2 \vec{\omega})$$

direction of \vec{p}
 opposite \vec{L}

direction
 of positive
 charge flow!



$$\vec{\mu}_i = i \vec{A}$$

$$\boxed{\vec{\mu}_i = -\frac{e}{2m} \vec{L}_i}$$

VI.D1) Total magnetic moment due to orbital motion of electrons

$$\vec{\mu}_L = -\frac{e}{2m} \sum_i \vec{L}_i$$

$$\boxed{\vec{\mu}_L = -\frac{e}{2m} \vec{L}}$$

a) Bohr magneton: $\mu_B \equiv \frac{e\hbar}{2m} \left(= 9.27 \times 10^{-2} \frac{J}{T} \right)$

2) Electrons have intrinsic spin angular momentum, also which gives rise a spin magnetic dipole moment

$$\vec{\mu}_{S_i} = -\frac{eg}{2m} \vec{S}_i \quad g \approx 2 \text{ for } e^-$$

g "g-factor"

Total magnetic moment due to spin of electrons

$$\vec{\mu}_S = -\frac{eg}{2m} \sum_i \vec{S}_i$$

$$\boxed{\vec{\mu}_S = -\frac{eg}{2m} \vec{S}}$$

- VI.) D2) Hence the total atomic magnetic moment is the vector sum of the orbital and spin moments

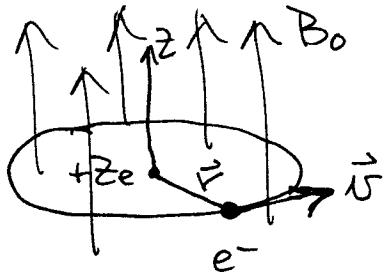
$$\vec{\mu} = -\frac{e}{2m} (\underbrace{\vec{L} + g\vec{S}}_{\neq \vec{J}})$$

\vec{J} = total \vec{x}
 momentum
 of atom
 $= \vec{L} + \vec{S}$

3) So if $\vec{L} = 0 = \vec{S} \Rightarrow \vec{\mu} = 0 \Rightarrow \vec{M} = 0$
 hence there is no net magnetization of the material. This is necessary for a diamagnetic material → we must still show opposite to \vec{B}_0 direction for the induced $\vec{\mu}$.

a) Lenz's Law: place atom in \vec{B} field \Rightarrow flux through atomic orbits increases, Lenz's law implies atomic motion will change to oppose this increase in flux (i.e. e^- speed up or slowdown), the atomic dipole moment will change (induced) to oppose the external \vec{B} -field \Rightarrow repulsion \Rightarrow diamagnetic material

- VII D 3.b) Quantitative argument: Place atom in an external \vec{B} -field along the z -direction



Total force on electron

$$\vec{F} = \underbrace{-e\vec{v} \times \vec{B}_0}_{\text{magnetic force due to } \vec{B}_0} - \underbrace{\frac{Ze^2}{4\pi\epsilon_0 r^2} \vec{r}}_{\text{Coulomb force attraction of nucleus}}$$

(circular motion ($\vec{v} = \vec{\omega} \times \vec{r}$))

\Rightarrow attractive force

$$\vec{F} = -[e\omega r B_0 + \frac{Ze^2}{4\pi\epsilon_0 r^2}] \vec{r}$$

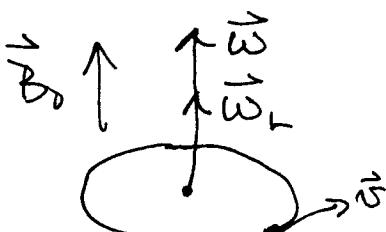
- Newton's 2nd law $\Rightarrow -mr\omega^2 = F$

$$= -[e\omega r B_0 + \frac{Ze^2}{4\pi\epsilon_0 r^2}]$$

\Rightarrow quadratic equation for ω

$$\omega \approx \frac{e}{2m} B_0 \pm \frac{e}{2m} \sqrt{\frac{Zm}{\pi\epsilon_0 r^3}} \equiv \omega_0$$

\pm Cases: i) Positive Root:



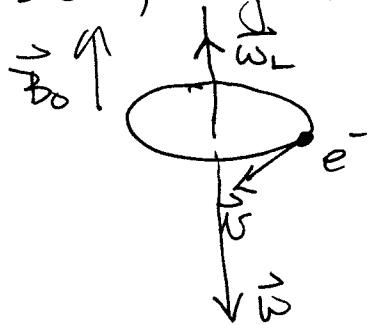
$$\omega = \omega_0 + \frac{e}{2m} B_0 \equiv \omega_L = \frac{\text{Larmor frequency}}{4}$$

If $\vec{B}_0 \parallel \vec{\omega}_0$ then ω increases

to $\vec{\omega} = (\omega_0 + \omega_L) \hat{k} \Rightarrow \vec{L}$ increases

Since $\vec{L} = mr^2 \vec{\omega}$ BUT $\vec{\mu}_i = -\frac{e}{2m} \vec{L}_i \propto S_i$
 $\vec{\mu}_i$ decreases \Rightarrow $\vec{\mu}_{\text{induced opposite}} \vec{B}_0$

-VII D3b2) Negative Root: $\vec{\omega} = -\omega_0 \hat{k} + \omega_L \hat{k}$



$$\omega = |\vec{\omega}| = |\omega_0 - \omega_L| \text{ decreases}$$

$$\text{Since } \vec{\omega}_{\text{induced}} = \omega_L \hat{k}$$

$$\Rightarrow \text{induced } \vec{L}_{\text{induced}} = mr^2 \vec{\omega}_{\text{induced}}$$

is along \vec{B}_0

$\Rightarrow \text{induced magnetic moment opposite } \vec{B}_0$

Both cases \Rightarrow

$$\begin{aligned} \vec{\mu}_{\text{induced}} &= -\frac{e}{2m} \vec{L}_{\text{induced}} \\ &= -\frac{e^2 r^2}{4m} \vec{B}_0 \end{aligned}$$

Now Z electrons with different orbits - we must average for total induced moment —
Need QM results is

$$\begin{aligned} \vec{\mu} &= \langle \vec{\mu}_{\text{induced}} \rangle_{QM} \\ &= -\frac{Ze^2}{6m} r_0^2 \vec{B}_0 \end{aligned}$$

with r_0^2 = mean square radius of atom

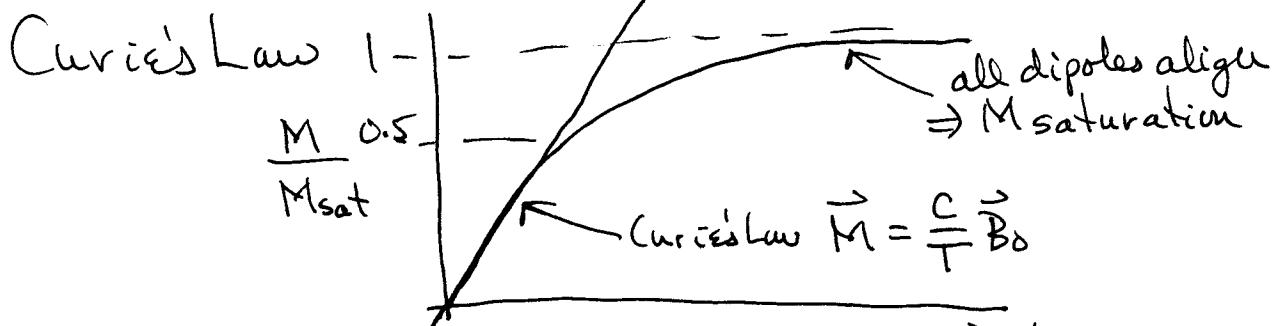
Hence

$$\vec{M} = -\left[\frac{NZ e^2 r_0^2}{6m} \right] \vec{B}_0$$

\vec{M} is opposite direction of $\vec{B}_0 \Rightarrow \text{decreases resultant field}$

- VII D 3b) So this is diamagnetic material.

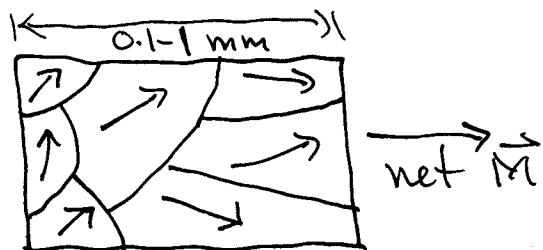
4) Paramagnetic material: atomic magnetic moments do not sum to zero \Rightarrow molecules have a permanent magnetic dipole moment — these tend to align in external \vec{B} -field



Paramagnetic materials

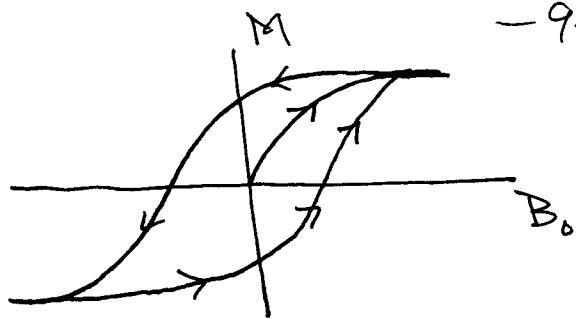
$$\vec{M} = \left\{ \frac{C}{T} - \frac{N^2 e^2 r_0^2}{6m} \right\} \vec{B}_0 \approx \frac{C}{T} \vec{B}_0$$

5) Ferromagnetic material: Large paramagnetic effects — electron spin magnetic moment and strong interactions between neighboring atoms \Rightarrow alignment of dipoles even after external \vec{B} -field is removed



Macroscopic regions of aligned moments called domains

- VII D5) Hysteresis Curve

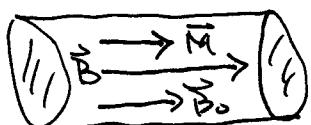


E) Macroscopic Fields & the Magnetization Current

$$\vec{B} = \vec{B}_o + \vec{B}_M$$

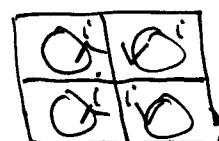
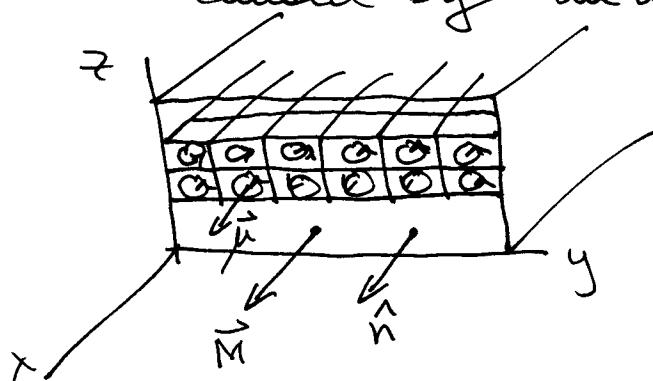
↑ ↑ ↑ due to Magnetization \vec{M}
Total external of material

i) Consider solenoid containing magnetic material



$$MsV = \mu$$

each magnetic moment μ is viewed as caused by an atomic current loop



adjacent current loops flow in opposite direction —

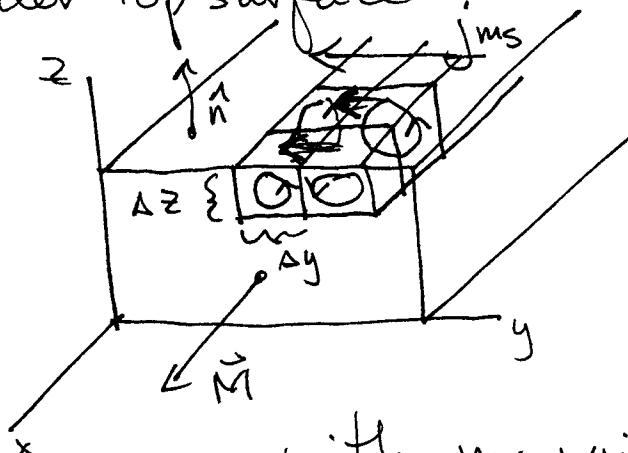
no net flow

So the current density flowing in a macroscopically thin layer of this surface will be zero

$$j_{Ms} \rightarrow 0 \text{ when } \vec{M} \parallel \hat{n}$$

But

- VII E) Consider top surface \rightarrow



A current density appears to flow across top surface in the direction $\vec{M} \times \hat{n}$

with magnitude

$$j_{MS} = \frac{i}{\Delta x}$$

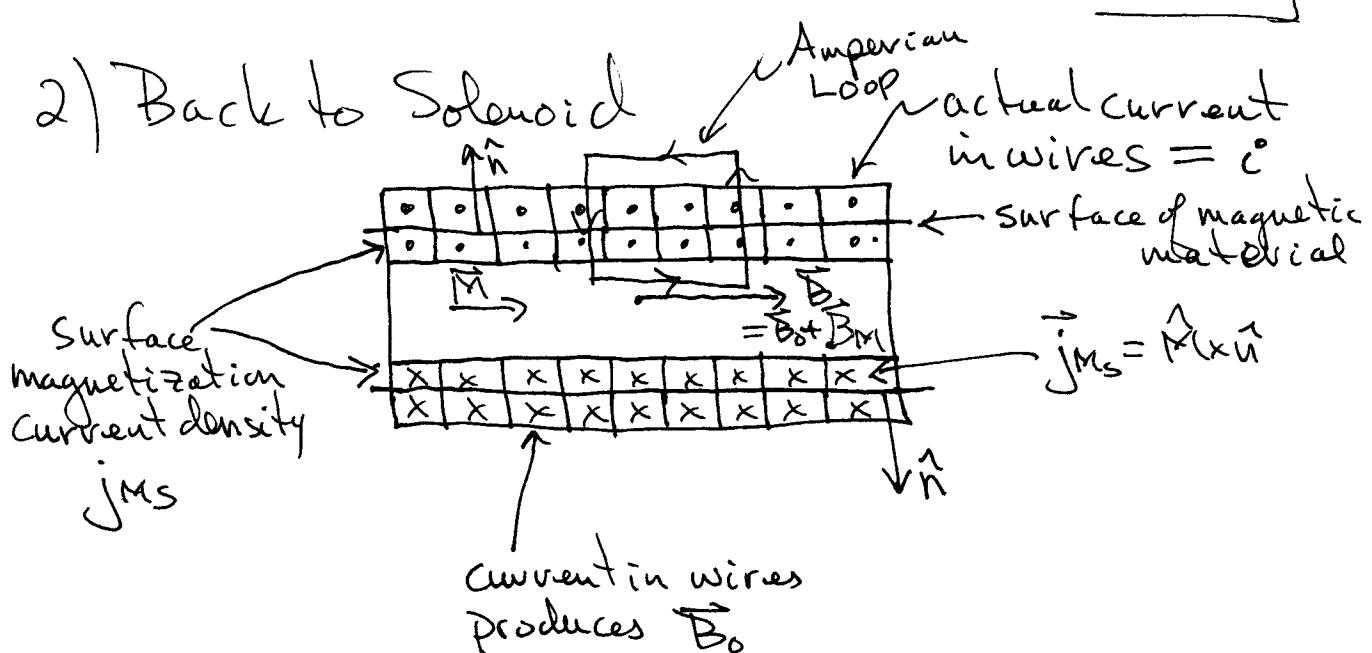
$$\text{But } \mu = iA = i\Delta y \Delta z = M\Delta V = M\Delta x \Delta y \Delta z$$

$$\Rightarrow M = \frac{i}{\Delta x} = j_{MS}$$

$$\Rightarrow \boxed{\vec{j}_{MS} = \vec{M} \times \hat{n}}$$

The magnetization
current
density

2) Back to Solenoid



- VII) E2) Ampere's Law: $\oint_C \vec{B} \cdot d\vec{s} = \mu_0 i_{\text{enclosed}}$

$$\begin{aligned} C &\parallel \\ B_h &= \mu_0 \left[\frac{Nh}{L} i + j_{MS} h \right] \\ &= \mu_0 \frac{Nh}{L} i + \mu_0 M_h \\ \Rightarrow \boxed{B = \underbrace{\mu_0 \frac{N}{L} i}_{=B_0} + \underbrace{\mu_0 M}_{=\vec{B}_M}} &\quad \text{i.e. } \vec{B}_M = \mu_0 \vec{M} \end{aligned}$$

So in general Ampere's law can be written

$$\oint_C \vec{B} \cdot d\vec{s} = \mu_0 i_{\text{free}} + \mu_0 \oint_C \vec{M} \cdot d\vec{s}$$

i_{free}
 conduction current $\int_C \vec{M} \cdot d\vec{s}$
 = i_m magnetization current

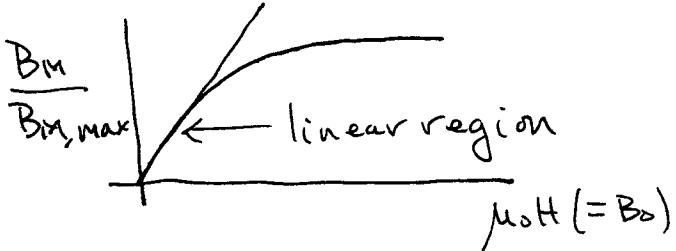
That is defining the magnetic intensity field

$$\vec{H} = \frac{1}{\mu_0} (\vec{B} - \mu_0 \vec{M}) \quad (= \frac{1}{\mu_0} \vec{B}_0)$$

Ampere's law can be written as

$$\boxed{\oint_C \vec{H} \cdot d\vec{s} = i_{\text{conduction (free)}}}$$

- VI) F) Constitutive Equation : For paramagnetic and diamagnetic materials that are isotropic and linear



$$\vec{M} = \chi_M \vec{H}$$

linear, isotropic magnetic material.

$\chi_M \equiv$ magnetic susceptibility

But

$$\vec{B} = \vec{B}_0 + \mu_0 \vec{M} = \mu_0 \vec{H} + \mu_0 \vec{M}$$

$$= \mu_0 (1 + \chi_M) \vec{H} = \boxed{\mu \vec{H} = \vec{B}}$$

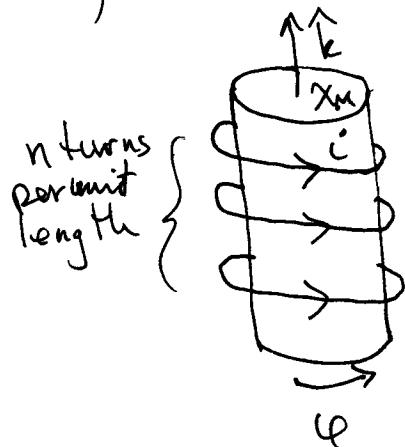
for linear, isotropic magnetic material.

$\mu = \mu_0 (1 + \chi_M)$ = permeability of material

(Other notation: $\chi_M = \mu_r = \frac{\mu}{\mu_0}$ = relative permeability)

VII G) Examples

1) Solenoid filled with magnetic material



Amperes law

$$\oint_C \vec{H} \cdot d\vec{s} = i_{\text{free}}$$

Diagram showing an Amperian loop C around a rectangular cross-section of the solenoid. Current i flows clockwise through the loop. Magnetic field \vec{H} points outwards from the top face and inwards from the bottom face.

$$\Rightarrow H L = i n L \Rightarrow \vec{H} = i n \hat{k}$$

$$\Rightarrow \boxed{\begin{aligned} \vec{B} &= \mu_0 (1 + \chi_m) \vec{H} \\ &= \mu_0 (1 + \chi_m) i n \hat{k} \end{aligned}}$$

a) If material is paramagnetic $\chi_m > 0 \Rightarrow B > B_0$.
if diamagnetic $\chi_m < 0 \Rightarrow B < B_0$.

b) The magnetization current density runs around cylinder's surface

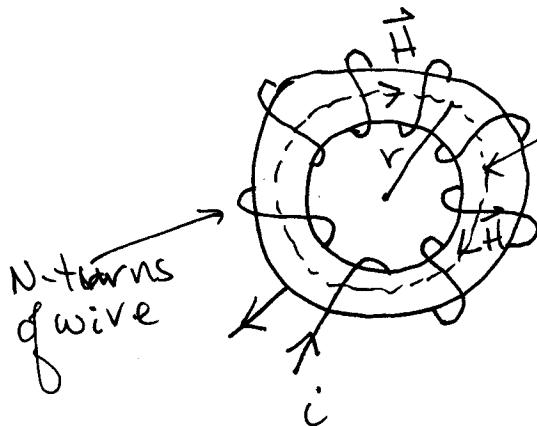
$$\vec{j}_{Ms} = \vec{M} \times \hat{n} = \chi_m \vec{H} \times \hat{n}$$

$$= \chi_m i n \hat{k} \times \hat{n} = \vec{i}$$

$$\boxed{\vec{j}_{Ms} = \chi_m i n \hat{i}}$$

\vec{j}_{Ms} is same direction as i
 $\chi_m > 0$
 $\chi_m < 0$ j_{Ms} opposite i

- III. G.) 2) Toroid with magnetic material



Amperian Loop

Amper's Law

$$\oint_C \vec{H} \cdot d\vec{s} = i_{\text{free}}$$

(Note: $H = 0 = B$
outside toroidal
Volume)

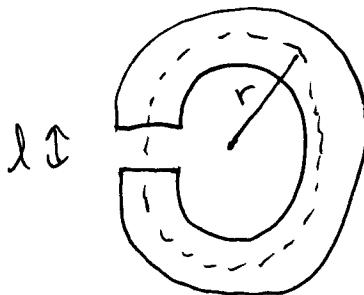
$$H \cdot 2\pi r = Ni$$

$$\Rightarrow H = \frac{Ni}{2\pi r}$$

But

$$\vec{B} = \mu \vec{H} \Rightarrow B = \frac{\mu Ni}{2\pi r} = (1 + \chi_m) \frac{\mu_0 Ni}{2\pi r}$$

3) Torus with a gap



$$B_{\text{in}} = B_{\text{gap}}$$

$$\left(\oint_C \vec{B} \cdot d\vec{A} = 0 = B_{\text{in}} A - B_{\text{gap}} A \right)$$

Let $h \rightarrow 0$

$$\Rightarrow B_{\text{in}} = B_{\text{gap}}$$

$$\text{So } B_{\text{in}} = B_{\text{gap}} = B(r)$$

$$\text{But } H_{\text{inside}} = \frac{B}{\mu} ; \quad H_{\text{gap}} = \frac{B}{\mu_0}$$

Now apply Amper's law

$$\oint_C \vec{H} \cdot d\vec{s} = i_{\text{free}} = Ni$$

||

$$H_{\text{in}}(2\pi r - l) + H_{\text{gap}}l = \frac{B}{\mu}(2\pi r - l) + \frac{B}{\mu_0}l$$

$$- \text{VII.G) 3)} \Rightarrow \boxed{B = \frac{\mu \mu_0 Ni}{\mu l + \mu_0 (2\pi r - l)}}$$

for ferromagnetic materials $\mu l \gg 2\pi r$

$$(\mu = \mu(H))$$

$$B \approx \frac{\mu_0 Ni}{l} \gg \frac{\mu_0 Ni}{2\pi r}$$

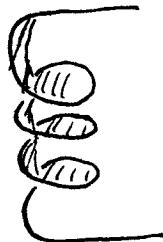
VII) Inductance :

A) Self inductance : Faraday's law $E_L = - \frac{d\phi_B}{dt} = - L \frac{di}{dt}$

$$L = \frac{d\phi_B}{di} = \frac{\phi_B}{i} \text{ for linear media.}$$

i) SI unit of inductance = Henry (H) $\equiv 1 \frac{\text{Volt} \cdot \text{sec.}}{\text{Ampere}}$

2) Solenoid : a) flux linkages = total flux thru solenoid.



$$\phi_B = nl \phi_{B\text{coil}} = nl B \pi r^2 = \mu_0 n^2 l A i$$

$$\Rightarrow L = \mu_0 n^2 l A$$

b) Voltage across each coil = E_{coil}

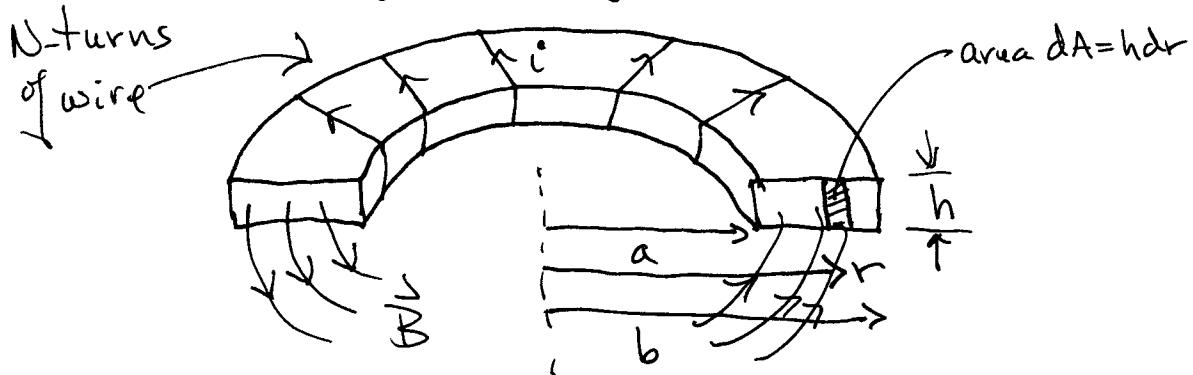


$$E_{\text{coil}} = - \frac{d\phi_{B\text{coil}}}{dt} = - \mu_0 n \pi r^2 \frac{di}{dt}$$

But there are nl -coils $\Rightarrow E_L = nl \cdot E_{\text{coil}}$

$$\Rightarrow L = \mu_0 n^2 l A$$

- VII.A) 3) Toroid of rectangular cross section:



Total flux through coil of wire $\phi_B = N \int_{coil} \vec{B} \cdot d\vec{A}$

$$\phi_B = N \int_{r=a}^b B(r) h dr$$

Use Ampere's law to find $B(r)$

$$\oint_C \vec{B} \cdot d\vec{s} = \mu_0 i_{enclosed} = \mu_0 Ni$$

$$B(r) 2\pi r \Rightarrow B(r) = \frac{\mu_0 Ni}{2\pi r}$$

$$\text{So } \phi_B = \frac{\mu_0 N^2 i h}{2\pi} \ln\left(\frac{b}{a}\right) i$$

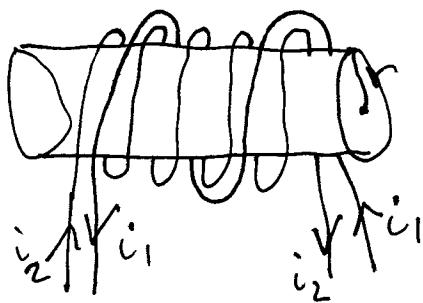
$$\Rightarrow L = \boxed{\frac{\mu_0 N^2 h}{2\pi} \ln\left(\frac{b}{a}\right)}$$

- 4) Fill inductors with magnetic material

$$\vec{B} = \frac{\mu}{\mu_0} \vec{B}_0 = (1 + X_M) \vec{B}_0 \leftarrow \begin{matrix} \vec{B}_{\text{without}} \\ \text{magnetic} \\ \text{material} \end{matrix}$$

- VII.A.4) \Rightarrow Solenoid: $L = \mu n^2 A l$
 Toroid: $L = \frac{\mu N^2 h}{2\pi} \ln\left(\frac{b}{a}\right)$

B) Mutual Inductance: Wrap 2 independent coils of wire around solenoid



$$\text{coil 1: } \Phi_{B_1} = \Phi_{B_{11}} + \Phi_{B_{12}}$$

$$\text{coil 2: } \Phi_{B_2} = \Phi_{B_{21}} + \Phi_{B_{22}}$$

$$\Phi_{B_{21}} = \text{flux thru coil 2 due to } B_1 = \mu_0 n_1 n_2 l A i_1$$

$$\Phi_{B_{12}} = \text{flux thru coil 1 due to } B_2 = \mu_0 n_1 n_2 l A i_2$$

$$\Phi_{B_{11}} = \text{self-linkages} = \mu_0 n_1^2 l A i_1$$

$$\Phi_{B_{22}} = \text{self-linkages} = \mu_0 n_2^2 l A i_2$$

So Faraday's law \Rightarrow

$$\mathcal{E}_1 = -L_1 \frac{di_1}{dt} - M \frac{di_2}{dt}$$

$$\mathcal{E}_2 = -L_2 \frac{di_2}{dt} - M \frac{di_1}{dt}$$

$$M = \sqrt{L_1 L_2} \left\{ \begin{array}{l} L_1 = \text{self-inductance of coil 1} = \frac{\Phi_{B_{11}}}{i_1} = \mu_0 n_1^2 l A \\ L_2 = \text{self-inductance of coil 2} = \frac{\Phi_{B_{22}}}{i_2} = \mu_0 n_2^2 l A \\ M = \text{mutual inductance} = \frac{\Phi_{B_{12}}}{i_2} = \frac{\Phi_{B_{21}}}{i_1} = \mu_0 n_1 n_2 l A \end{array} \right.$$

-III.C.) Magnetic Energy : Work required to move charge through inductor

$$dW = -\mathcal{E} dq = dq \frac{d\phi_B}{dt}$$

$$\text{But } dq = i dt \quad \& \quad \frac{d\phi_B}{dt} = \frac{d\phi_B}{di} \frac{di}{dt} = L \frac{di}{dt}.$$

Hence $dW = i dt L \frac{di}{dt} = L i di$

This is stored in the magnetic field of the inductor — it is the increase in Potential Energy stored in the magnetic field:

$$dU_B = dW = L i di$$

\Rightarrow

$$U_B = \frac{1}{2} L i^2 = \frac{1}{2} i \phi_B$$

i) Applied to a solenoid: $L = \mu_0 n^2 A l \Rightarrow$

$$U_B = \frac{1}{2} \mu_0 n^2 i^2 (A l) \quad \text{but } B = \mu_0 n i$$

\Rightarrow

$$U_B = \frac{1}{2} \mu_0 B^2 (A l) = \frac{1}{2} \mu_0 \int_{\text{All Space}} \vec{B} \cdot \vec{B} dV$$

2) Energy density stored in magnetic field

$$u_B = \frac{U_B}{A l} = \frac{1}{2} \vec{B} \cdot \vec{B}; U_B = \int_{\text{All Space}} u_B dV$$

-VII.C) 3) If a magnetic material is present

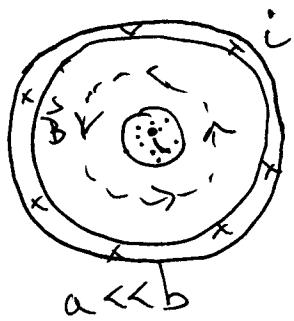
$$\boxed{U_B = \frac{1}{2} \int_{\text{All Space}} \vec{B} \cdot \vec{H} dV}$$

$$U_B = \frac{1}{2} \vec{B} \cdot \vec{H}$$

4) Example: Coaxial Cable: What is the energy stored for a length l of cable.

inner conductor radius = a

outer conductor inner radius = b



Amperes Law

$$\oint_C \vec{B} \cdot d\vec{s} = \mu_0 i_{\text{enclosed}}$$

$$B 2\pi r = \mu_0 i$$

$$B(r) = \frac{\mu_0 i}{2\pi r}$$

So energy stored in magnetic field ($a \leq r \leq b$)

$$U_B = \frac{1}{2} \mu_0 B^2 = \frac{\mu_0 i^2}{8\pi^2 r^2}$$

Assume center conductor a small radius and outer conductor thin \Rightarrow

$$U_B = \frac{1}{2} \int_{r=a}^b \frac{1}{\mu_0} B^2 dV = \frac{\mu_0 i^2 l}{4\pi} \ln(b/a)$$

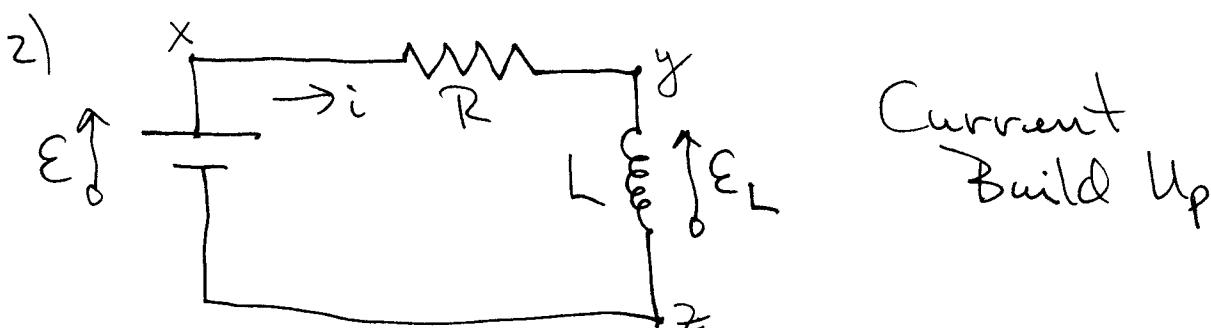
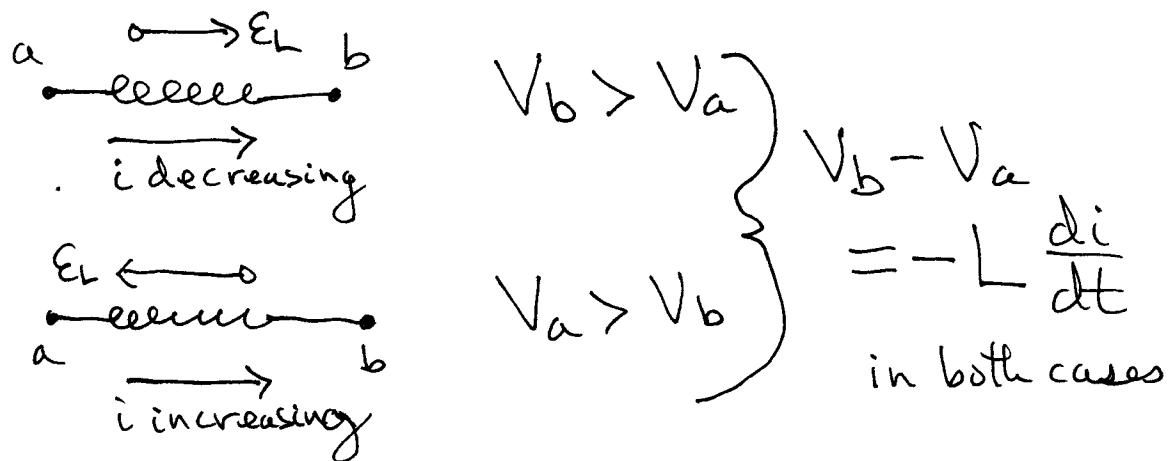
- VII.C.4) Recalling that $U_B = \frac{1}{2} L i^2$ we can determine the inductance of the cable from U_B above

$$L = \frac{\mu_0 l}{2\pi} \ln\left(\frac{b}{a}\right)$$

which agrees with $L = \frac{\Phi_B}{i}$

D) LR-Circuits

1) Potential Difference across inductor (Lenz' Law)



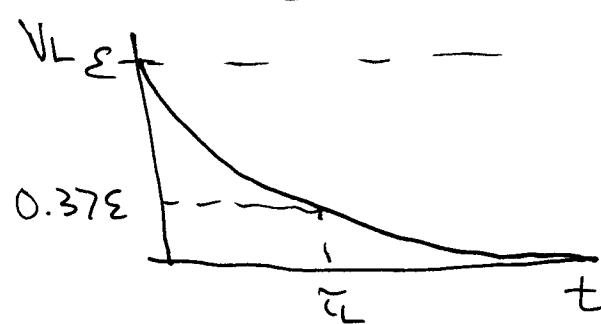
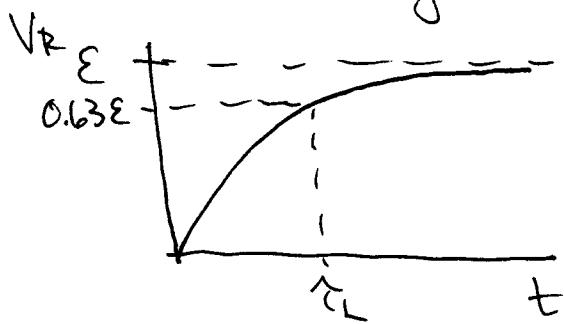
Loop Rule: $\epsilon = iR + L \frac{di}{dt}$

for i \Rightarrow $i(t) = \frac{\epsilon}{R} \left(1 - e^{-t/\tau_L}\right)$

-VII.D) 2) with $\tau_L = L/R$ = inductive time constant

$$\text{So } V_R = V_x - V_y = iR = \mathcal{E}(1 - e^{-t/\tau_L})$$

$$V_L = V_y - V_z = -\mathcal{E}_L = L \frac{di}{dt} = \mathcal{E} e^{-t/\tau_L}$$



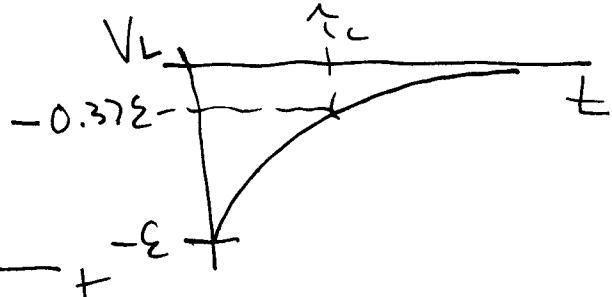
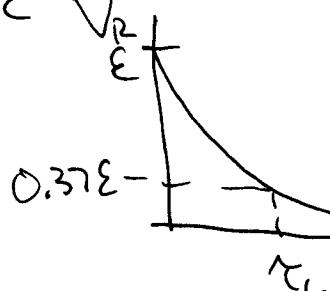
3) Current Decay



$$\text{Loop Rule: } L \frac{di}{dt} + iR = 0$$

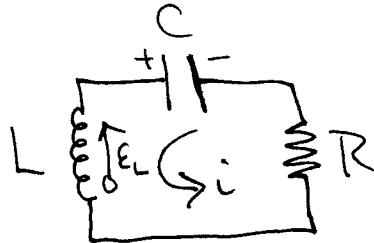
$$\Rightarrow i(t) = i_0 e^{-t/\tau_L}$$

$$\text{Let } i_0 = \mathcal{E}$$



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iii. E.) LCR-Circuit: Initially charged capacitor



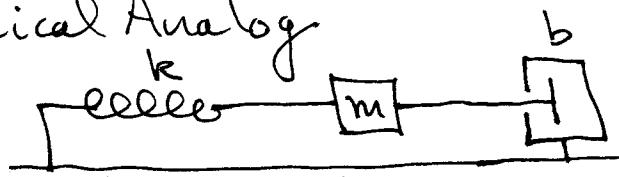
Loop Rule:

$$L \frac{d^2q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q = 0$$

with initial conditions $q(0) = q_m$

$$\frac{dq(0)}{dt} = 0.$$

(Mechanical Analog



$$F = -kx - bx$$

Newton's 2nd Law

$$\vec{F} = m\vec{a} \Rightarrow$$

with i.c. $x(0) = x_m$

$$\frac{dx(0)}{dt} = 0$$

$$m \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx = 0$$

$$-\frac{Rt}{2L}$$

For $4\frac{L}{C} > R^2$ $q(t) = q_0 e^{-\frac{Rt}{2L}} \cos(\omega' t + \phi)$

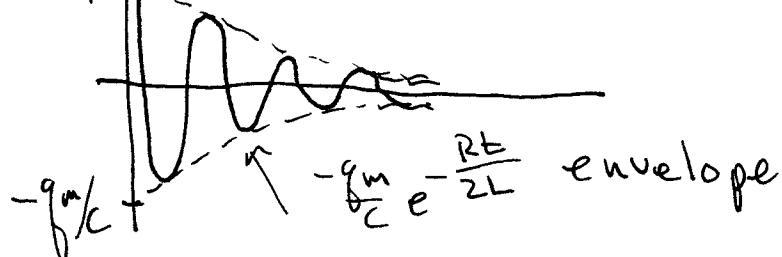
i.c. $\Rightarrow \tan \phi = \frac{-1}{\sqrt{\frac{4L}{R^2} - 1}}$; $q_0 = q_m \frac{1}{\sqrt{LC} \omega'}$

1) Energy Loss:

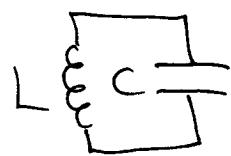
$$U = U_E + U_B = \frac{1}{2} \frac{q^2}{C} + \frac{1}{2} L i^2$$

$$\frac{dU}{dt} = -i^2 R \quad \text{Joule heating}$$

2) $V_C = \frac{q_m}{C} e^{-\frac{Rt}{2L}}$ envelope



VII. E. 3) $R \rightarrow 0$

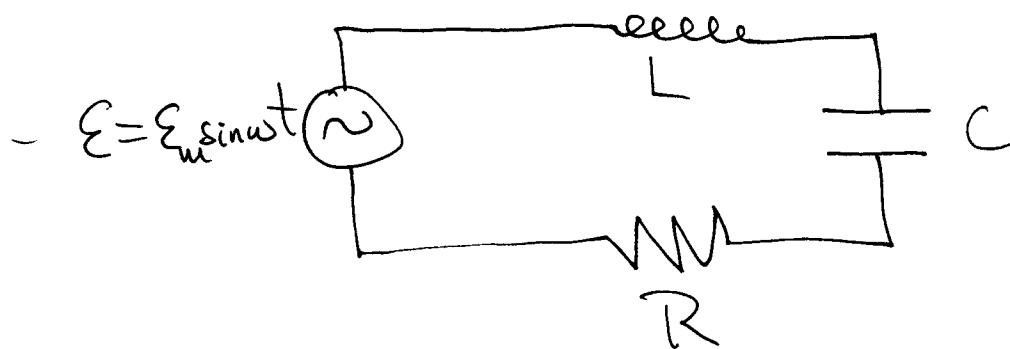


$$\frac{dU}{dt} = 0$$

$$U = \text{constant} = U_E + U_B$$

energy oscillates between
being stored in electric field
and the magnetic field as the current
oscillates sinusoidally CW then CCW in circuit.

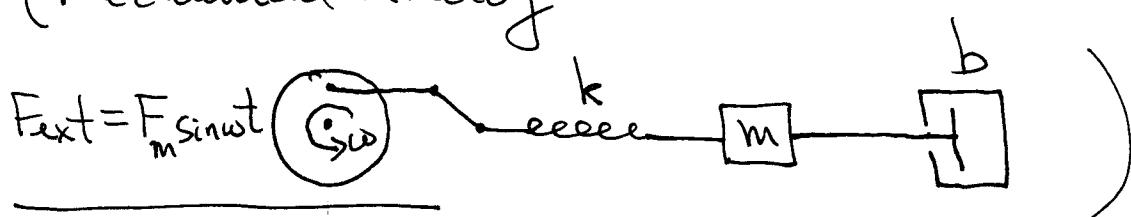
F.) Driven LCR-Circuit - Resonance



Loop Equation \Rightarrow

$$L \frac{d^2q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q = \epsilon_m \sin \omega t$$

(Mechanical Analog)



$$q(t) = q_c(t) + q_p(t)$$

Complementary
solution

particular solution = steady state
solution

transient solution above

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- VII. F) Ansatz: $\dot{q}_P(t) = \frac{i_m}{\omega} \sin(\omega t - \delta)$

Conventional $\delta = \phi + \frac{\pi}{2}$ so

$$i = \dot{q}_P(t) = i_m \sin(\omega t - \phi)$$

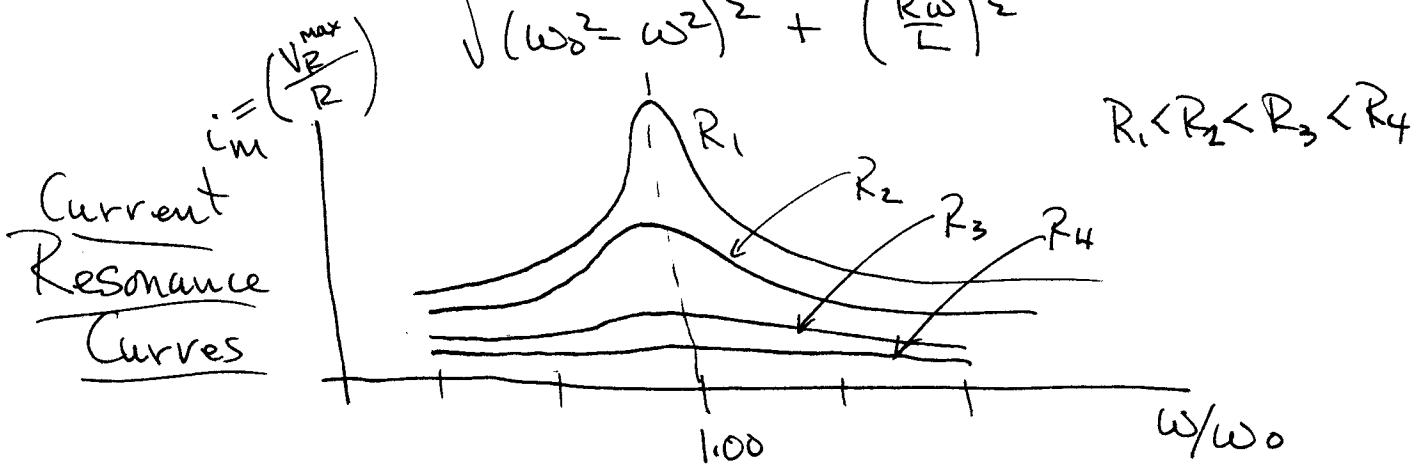
Loop equation $\Rightarrow \tan \delta = \frac{\frac{R}{L} \omega}{\omega_0^2 - \omega^2}$

or 1)
$$\tan \phi = \frac{\omega^2 - \omega_0^2}{\frac{R}{L} \omega}$$

where

$$\omega_0^2 = \frac{1}{LC} \quad (\text{natural frequency of L circuit})$$

2) $i_m = \frac{\epsilon_m}{R} \sec \phi$
 $= \frac{\omega \cdot \epsilon_m / L}{\sqrt{(\omega_0^2 - \omega^2)^2 + (\frac{R \omega}{L})^2}}$



$$\omega_R = \omega_0 = \frac{1}{\sqrt{LC}} \quad \left(\begin{array}{l} \text{Current } (V_R) \\ \text{Resonance} \end{array} \right)$$

VII. F.3) Voltage drop across capacitor = $V_c = \frac{q}{C}$

$V_{c\max} = \frac{i_m}{\omega C}$ has resonance at charge frequency: $\omega_{QR} = \sqrt{\omega_0^2 - \frac{1}{2}(\frac{R}{L})^2}$ f_P resonance at $< \omega_0$

4) Voltage drop across inductor = $V_L = L \frac{di}{dt}$

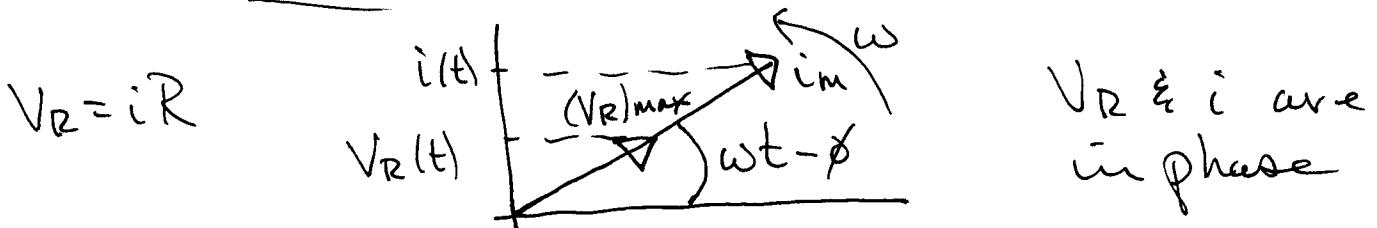
$V_{L\max} = L \omega i_m$ has resonance at

frequency:

$$\omega_{LR} = \frac{\omega_0}{\sqrt{1 - \frac{1}{2}(\frac{R^2 C}{L})}} > \omega_0$$

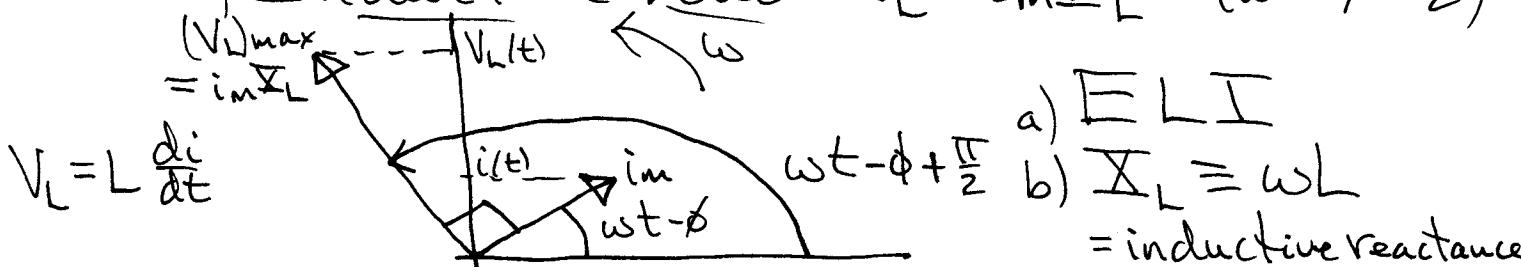
G) Phasor Diagrams: $i(t) = i_m \sin(\omega t - \phi)$
through circuit element

1) Resistive Load: $V_R = i_m R \sin(\omega t - \phi)$



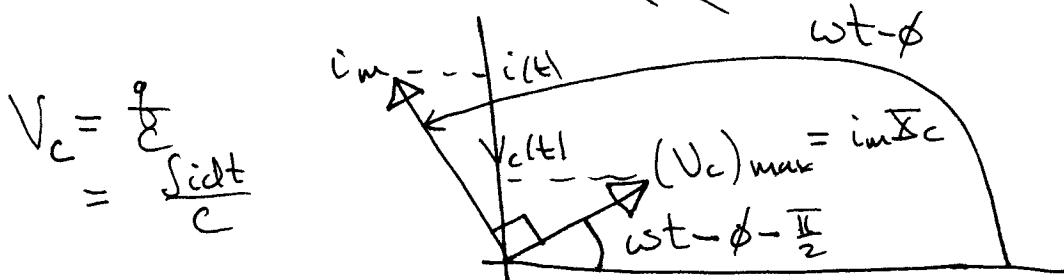
V_R & i are in phase

2) Inductive Load: $V_L = i_m X_L \sin(\omega t - \phi + \frac{\pi}{2})$



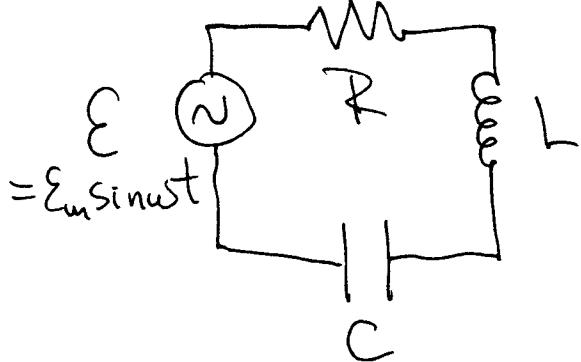
a) E LI
b) $X_L = \omega L$
 $=$ inductive reactance

- VII.G.) 3) Capacitive Load: $V_c = i_m \bar{X}_c \sin(\omega t - \phi - \frac{\pi}{2})$

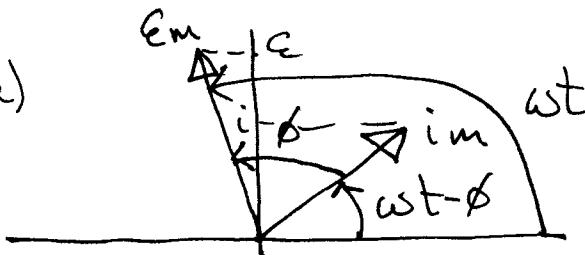


a) ICE
b) $\bar{X}_c = \frac{1}{\omega C}$
= capacitive reactance

4) LCR-Circuit:



$E = E_m \sin \omega t$
Ansatz: $i = i_m \sin(\omega t - \phi)$

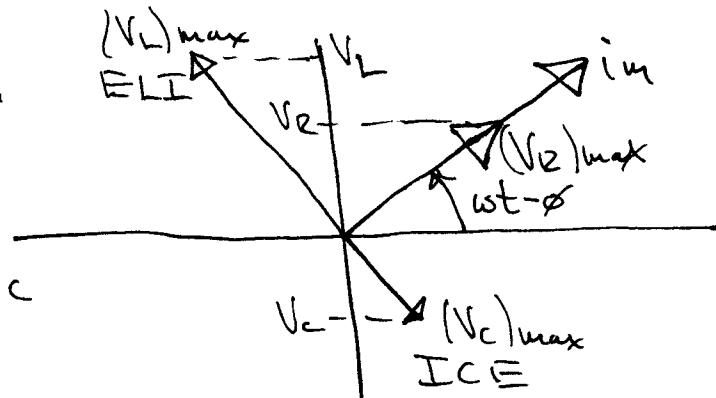


b) RLC Components:

loop rule:

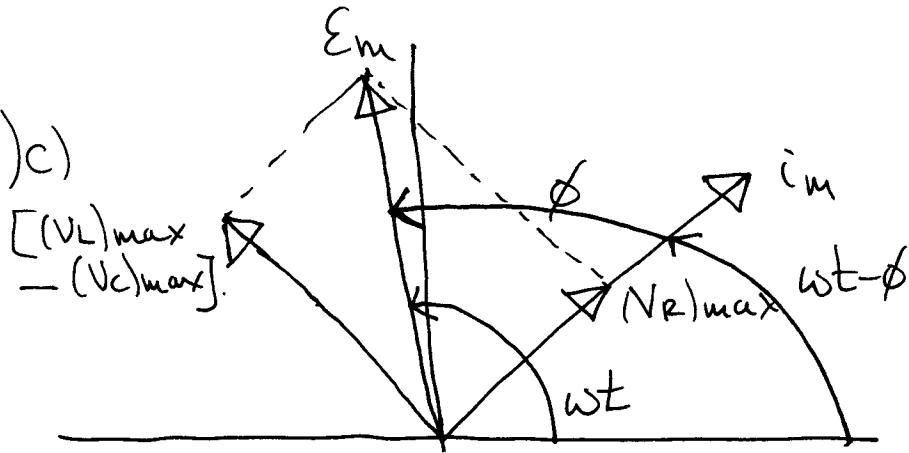
$$E = V_R + V_L + V_C$$

(scalar sum)



c) Vector sum of $(V_R)_{\text{max}}$, $(V_L)_{\text{max}}$, $(V_C)_{\text{max}}$ phasors equals $\underline{E_m}$ phasor

- VII. G4)c)



Since $V_{R,C,L}$ phasors are at right angles \Rightarrow

$$\begin{aligned} E_m &= \sqrt{[(V_R)_{\text{max}}]^2 + [(V_L)_{\text{max}} - (V_C)_{\text{max}}]^2} \\ &= i_m \sqrt{R^2 + (\Sigma_L - \Sigma_C)^2} \end{aligned}$$

\Rightarrow

$$i_m = E_m / Z$$

$$Z = \sqrt{R^2 + (\Sigma_L - \Sigma_C)^2} = \text{impedance}$$

$$\tan \phi = \frac{(V_L)_{\text{max}} - (V_C)_{\text{max}}}{(V_R)_{\text{max}}} =$$

$$= \frac{\Sigma_L - \Sigma_C}{R} = \tan \phi$$

i) Resonance for the current occurs at $\phi = 0$
 $\Rightarrow \Sigma_L = \Sigma_C \Rightarrow \omega = \omega_0 = \frac{1}{\sqrt{LC}}$,

So $(V_L)_{\text{max}}$ and $(V_C)_{\text{max}}$ are equal and
 opposite to give i_m in phase with E_m .

VII. H) Power in AC circuits:

1) Power dissipation in Resistor:

$$P = i^2 R = i_m^2 R \sin^2(\omega t - \phi)$$

Average power dissipation

$$\bar{P} = \frac{1}{N_e} \int_0^{N_e} P(t) dt$$

$$= \frac{1}{2} i_m^2 R = i_{rms}^2 R$$

with root mean square current

$$i_{rms} = \frac{i_m}{\sqrt{2}} = \sqrt{\langle i^2 \rangle}$$

2) Power supplied to circuit by source of emf

$$P = \frac{dW}{dt} = E_i i = E_m i_m \sin \omega t \sin(\omega t - \phi)$$

Average power supplied

$$\bar{P} = \frac{1}{2} E_m i_m \cos \phi$$

$$= E_{rms} i_{rms} \cos \phi$$

VII.H.2) $\cos\phi \equiv \text{power factor}$

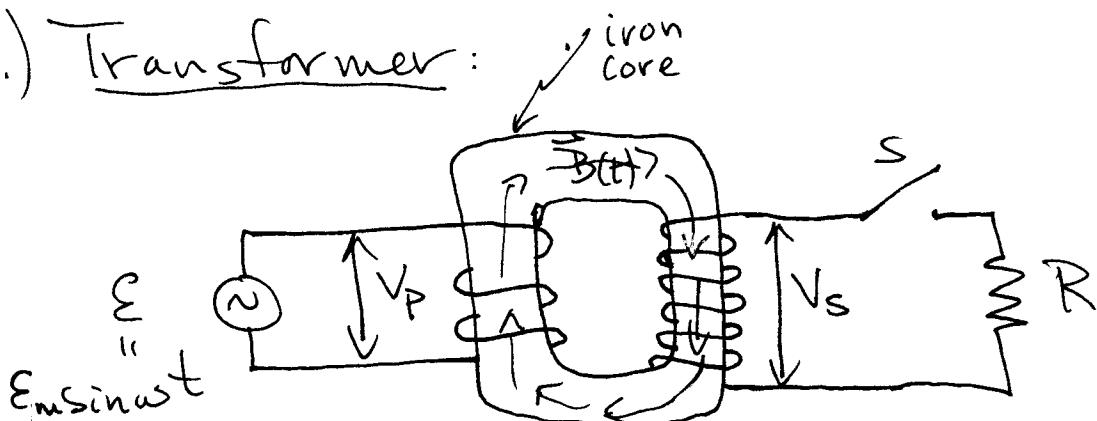
$$= \frac{R}{Z} = \frac{R}{\sqrt{R^2 + (\chi_L - \chi_C)^2}}$$

If resistive load $\chi_L = \chi_C \Rightarrow \cos\phi = 1$

power delivered to circuit is maximum

$P = \text{Ermsirms}$ ($Z=R$ resistive load)

I.) Transformer:



N_p turns N_s turns
Primary Winding Secondary Winding

$$1) \left(\frac{d\phi_B}{dt} \right)_{\text{primary per turn}} = \left(\frac{d\phi_B}{dt} \right)_{\text{secondary per turn}}$$

$$\Rightarrow \frac{V_p}{N_p} = \frac{V_s}{N_s}$$

$$\Rightarrow V_s = V_p \left(\frac{N_s}{N_p} \right)$$

$$2) \text{Energy Conservation: } i_p V_p = i_s V_s \quad (\text{Resistive load})$$

$$\Rightarrow i_s = i_p \left(\frac{N_p}{N_s} \right)$$

VIII.) Maxwell's Equations

A) Amperes Law as modified by Maxwell to be consistent with charge conservation

$$\frac{1}{\mu_0} \oint_C \vec{B} \cdot d\vec{s} = i + i_D = i + \epsilon_0 \frac{d\phi_E}{dt}$$

i_D = displacement current

$$\equiv \epsilon_0 \frac{d}{dt} \int_S \vec{E} \cdot d\vec{A} = \epsilon_0 \frac{d\phi_E}{dt}$$

$\phi_E = \int_S \vec{E} \cdot d\vec{A}$ = electric flux through ^{open} surface S bounded by C.

1) Time varying \vec{E} -field produces a \vec{B} -field

2) Charging capacitor: Gauss' law $q = \epsilon_0 E A$

$$\Rightarrow \text{Conduction current} = i = \frac{dq}{dt} = \epsilon_0 \frac{d(EA)}{dt}$$

$$= \epsilon_0 \frac{d\phi_E}{dt} = i_D = \text{displacement current}$$

So appears as current is continuous

\Rightarrow

displacement current density
 $= \vec{j}_D = \epsilon_0 \frac{d\vec{E}}{dt}$

VIII) A3) Magnetic and Dielectric material present
Amperes law

$$\frac{1}{\mu_0} \oint_C \vec{B} \cdot d\vec{s} = i + i_D + i_M$$

with

$$i_M = \oint_C \vec{M} \cdot d\vec{s}$$

and Gauss' law

$$\oint_S (\epsilon_0 \vec{E} + \vec{P}) \cdot d\vec{A} = q_{\text{free}}$$

$\underbrace{\qquad\qquad}_{= \vec{D}}$
 $\equiv \phi_D = \oint_S \vec{D} \cdot d\vec{A}$

Hence Maxwell's modification becomes

$$i_D = \frac{d}{dt} \phi_D = \frac{d}{dt} \int_S \vec{D} \cdot d\vec{A}$$

Recalling $\vec{H} = \frac{1}{\mu_0} (\vec{B} - \mu_0 \vec{M})$

yields Amperes law

$$\oint_C \vec{H} \cdot d\vec{s} = i + \frac{d}{dt} \int_S \vec{D} \cdot d\vec{A}$$

i = conduction current or free current
or transport current

III.) A4) When using Faraday's law in the past we ignored the displacement current in Ampere's law — estimate error — Apply an alternating E-field to a conductor

$$\vec{E} = \vec{E}_0 \cos \omega t$$

Ohm's law $\Rightarrow \vec{j} = \sigma \vec{E} = \sigma \vec{E}_0 \cos \omega t$, with $\epsilon = 1$

$$\Rightarrow \frac{d\vec{D}}{dt} = -\omega \epsilon_0 \vec{E} \sin \omega t$$

Thus

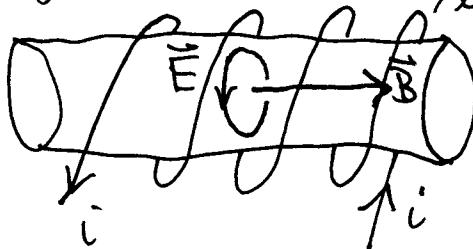
$$\frac{|\vec{j}|}{|\vec{j}_0|} = \frac{|\sigma \vec{E}|}{\left| \frac{d\vec{D}}{dt} \right|} = \frac{\sigma}{\omega \epsilon_0}$$

$$\text{For Cu } \frac{\sigma}{\epsilon_0} \approx 10^{19} \text{ and } \frac{|\vec{j}|}{|\vec{j}_0|} \approx \frac{10^{19}}{\omega}$$

This justifies quasi-static regime

\vec{j}_0 is negligible compared to \vec{j} .

- 5) Displacement current produces a magnetic field in inductor — what is estimate of error in neglecting this relative to the magnetic field produced by conduction current?



\vec{E} has direction given by Lenz' law ex. $\vec{B} \downarrow$, \vec{E} causes $i \uparrow$

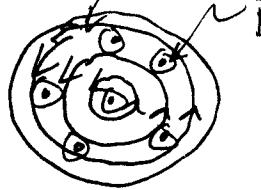
let $i = i_m \sin \omega t$

VIII.A)4) Ampere's law without displacement current

$\vec{B} \approx \mu_0 n i = \mu_0 n i \sin \omega t$

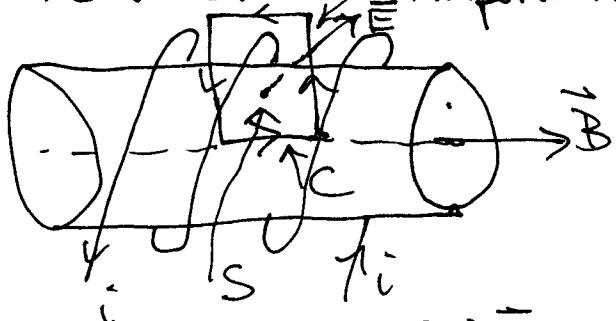
induces \vec{E} -field by Faraday's law

$$\oint \vec{E} \cdot d\vec{s} = - \frac{d}{dt} \Phi_B$$

$$\Rightarrow E = -(\frac{1}{2} \omega \mu_0 n i \sin \omega t) / r$$


So with $D = \epsilon_0 E$ (vacuum) $\Rightarrow D = -\frac{1}{2} \omega \epsilon_0 \mu_0 n i r \cos \omega t$

Ampere's law re-visited



$$\oint_C \vec{B} \cdot d\vec{s} = n l i + \int_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{A}$$

$$\text{Error} = \frac{\left| \int_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{A} \right|}{n l i} = \frac{1}{4} \omega^2 \epsilon_0 \mu_0 R^2$$

For $\frac{\omega}{2\pi} = 1 \text{ MHz}$, $R = 10 \text{ cm} \Rightarrow \text{Error} \approx 10^{-6}$.

VII.) B) Maxwell's Equations (integral form in vacuum)

$$\oint_S \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} q : \text{Gauss' Law}$$

$$\oint_S \vec{B} \cdot d\vec{A} = 0 : \text{No Magnetic Charge}$$

$$\oint_C \vec{E} \cdot d\vec{s} = - \frac{d}{dt} \oint_S \vec{B} \cdot d\vec{A} : \text{Faraday's Law}$$

$$\oint_C \vec{B} \cdot d\vec{s} = \mu_0 i + \epsilon_0 \mu_0 \frac{d}{dt} \oint_S \vec{E} \cdot d\vec{A} : \text{Ampere's Law as modified by Maxwell for charge conservation}$$

1) Charge particles interact with the electromagnetic field according to the Lorentz force law

$$\vec{F} = q (\vec{E} + \vec{v} \times \vec{B})$$

and their trajectories are determined by Newton's 2nd Law $\vec{F} = \frac{d\vec{p}}{dt}$.

2) All classical, macroscopic electromagnetic phenomena described by these laws.

VIII. c) Maxwell's Equations (integral form when dielectric and magnetic material is present)

$$\oint_S \vec{D} \cdot d\vec{A} = q_{\text{free}} : \text{Gauss' Law}$$

$$\oint_S \vec{B} \cdot d\vec{A} = 0 : \text{No Magnetic Charges}$$

$$\oint_C \vec{E} \cdot d\vec{s} = - \frac{d}{dt} \int_S \vec{B} \cdot d\vec{A} : \text{Faraday's Law}$$

$$\oint_C \vec{H} \cdot d\vec{s} = i_{\text{conduction}} + \frac{d}{dt} \int_S \vec{D} \cdot d\vec{A} : \text{Ampere's Law as modified by Maxwell}$$

In addition we require the constitutive equations

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P} \quad \text{with } \vec{P} = \vec{P}(\vec{E})$$

$$\vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M} \quad \text{with } \vec{M} = \vec{M}(\vec{H}),$$

where for linear, isotropic materials

$$\vec{D} = \chi_e \epsilon_0 \vec{E} = \epsilon \vec{E}$$

$$\vec{B} = \mu \vec{H}$$

That is

$$\vec{P} = \chi_e \epsilon_0 \vec{E}$$

$$\vec{M} = \chi_m \vec{H}$$

VII.C) In general we also consider Ohmic materials

$$\vec{j} = \sigma \vec{E} \quad : \text{Ohm's Law}$$

$$1) \text{ For Vacuum } \vec{D} = \epsilon_0 \vec{E}, \quad \vec{B} = \mu_0 \vec{H}.$$

D) Maxwell's Equations (Differential form)

$$\text{with } q_{\text{free}} = \int_V \rho dV; \quad i_{\text{conduction}} = \int_S \vec{j} \cdot d\vec{A}$$

$$1) \quad \nabla \cdot \vec{D} = \rho \quad : \text{Gauss' Law}$$

$$\nabla \cdot \vec{B} = 0 \quad : \text{No Magnetic Charges}$$

$$\nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \quad : \text{Faraday's Law}$$

$$\nabla \times \vec{H} = \vec{j} + \frac{\partial \vec{B}}{\partial t} \quad : \text{Amperie's Law}$$

$$2) \text{ In vacuum } \vec{D} = \epsilon_0 \vec{E}, \quad \vec{B} = \mu_0 \vec{H} \Rightarrow$$

$$\nabla \cdot \vec{D} = \frac{1}{\epsilon_0} \rho \quad : \text{Gauss' Law}$$

$$\nabla \cdot \vec{B} = 0 \quad : \text{No Magnetic Charges}$$

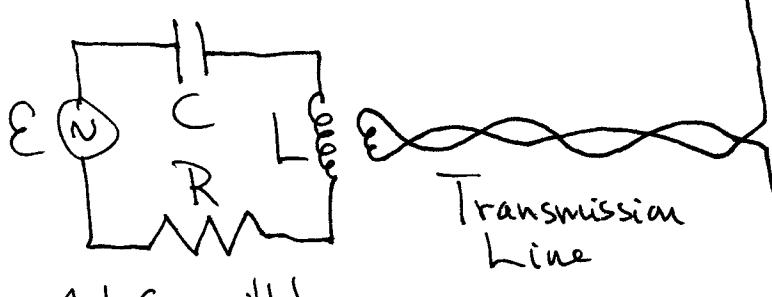
$$\nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \quad : \text{Faraday's Law}$$

$$\nabla \times \vec{B} = \mu_0 \vec{j} + \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t} \quad : \text{Amperie's Law}$$

IX) Electromagnetic Radiation: Charges at rest or moving at constant velocity do not radiate.

Accelerated charges radiate

A)



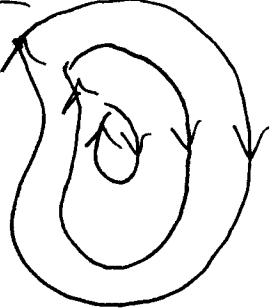
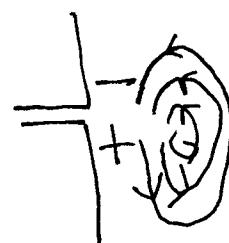
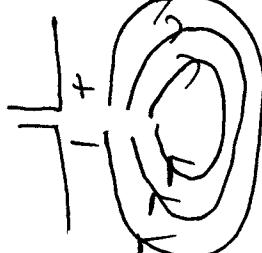
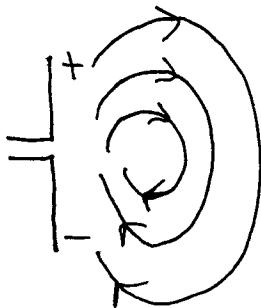
Transmission
line

→ Electromagnetic
Traveling
Wave

Electric
Dipole
Antenna

B) Antenna acts like oscillating electric dipole moment

(\vec{E} -field
shown
only)



$t=0$

$$\begin{aligned} q &= q_0 \cos \omega t \\ p &= qd \\ i &= \dot{q} = \frac{\dot{p}}{d} \end{aligned}$$

$t=t_1 > 0$



$t=t_2 > t_1$

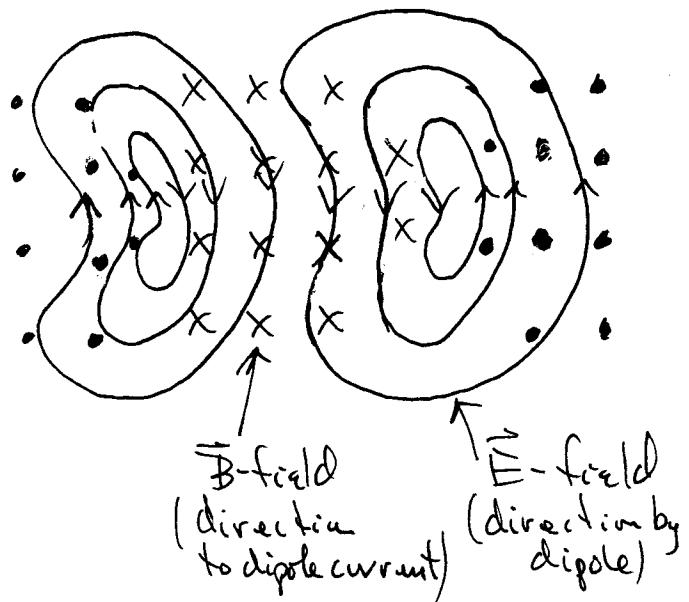
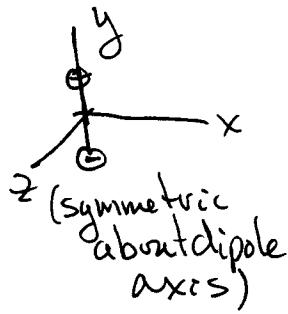
Electromagnetic
wave becomes
detached from
the charges

near field

$t=t_3 > t_2$

radiation
zone

IX) C) Closer look at wave:



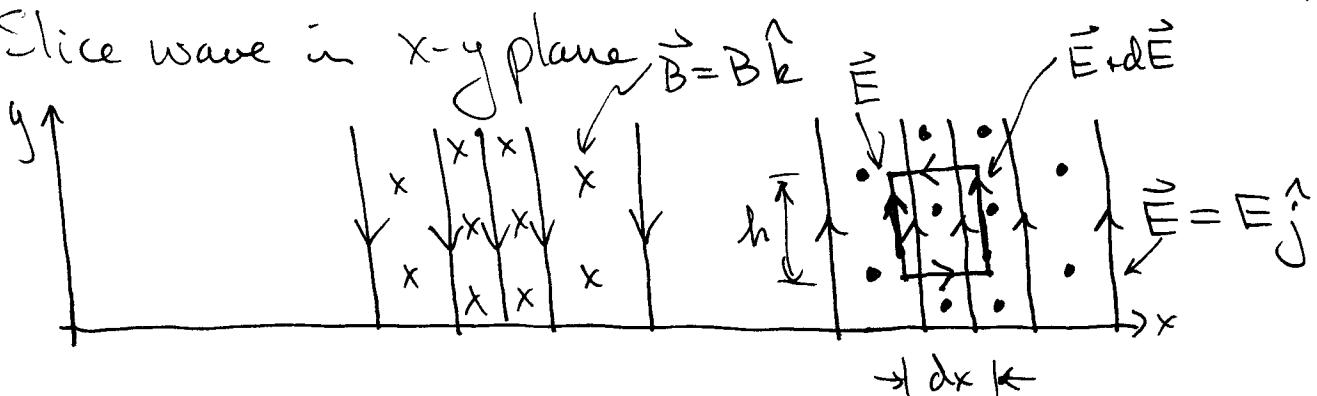
D) Maxwell's Equations applied to wave in Rad. zone

$$\oint \vec{E} \cdot d\vec{s} = - \int_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{A} : \text{Faraday's law}$$

$$\oint \vec{B} \cdot d\vec{s} = \epsilon_0 \mu_0 \int_S \frac{\partial \vec{E}}{\partial t} \cdot d\vec{A} : \text{Ampere's law}$$

(far from dipole in
Radiation zone)

i) Slice wave in x-y plane $\vec{B} = B \hat{k}$



Faraday's Law

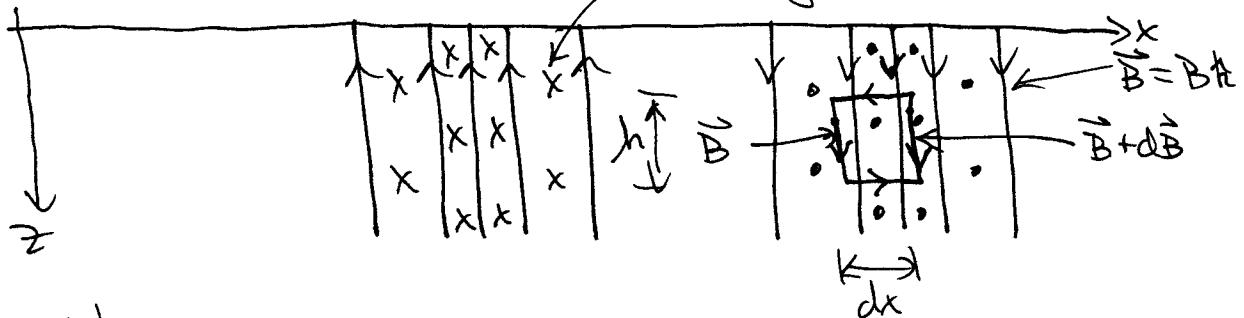
$$\oint \vec{E} \cdot d\vec{s} = (E + dE)h - Eh = dEh$$

$$= - \frac{\partial B}{\partial t} (h dx)$$

$\nabla \cdot D \Rightarrow$

$$\frac{\partial E}{\partial x} = -\frac{\partial B}{\partial t}$$

2) Slice wave in $x-z$ plane $\vec{E} = E_j \hat{j}$



Ampere's Law:

$$\oint_C \vec{B} \cdot d\vec{s} = -(B + dB)h + Bh = -h dB$$

$$= \epsilon_0 \mu_0 \frac{\partial E}{\partial t} (h dx)$$

\Rightarrow

$$\frac{\partial B}{\partial x} = -\epsilon_0 \mu_0 \frac{\partial E}{\partial t}$$

E) Wave Equation: uncouple the above by differentiating again \Rightarrow

$$\left[\epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial x^2} \right] E(x, t) = 0$$

$$\left[\epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial x^2} \right] B(x, t) = 0$$

-IX. E) General Solution to wave equation

$$\Rightarrow \boxed{E(x,t) = E(x-vt) \\ B(x,t) = B(x-vt) \\ v = \frac{1}{\sqrt{\epsilon_0 \mu_0}} = c}$$

All electromagnetic waves travel at speed c !

and $\left[\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial x^2} \right] E \text{ or } B = 0$

F) Plane Waves: Simplest Solution

$$E(x,t) = E_m \sin(kx - \omega t)$$

$$B(x,t) = B_m \sin(kx - \omega t)$$

Wave Equation $\Rightarrow \frac{\omega}{k} = c$

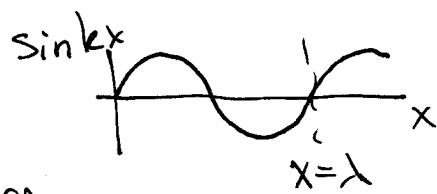
k = wave number

$kx = 2\pi$ gives zeroes of $\sin kx$

λ is called wave length $k\lambda = 2\pi$

$$\Rightarrow k = \frac{2\pi}{\lambda}$$

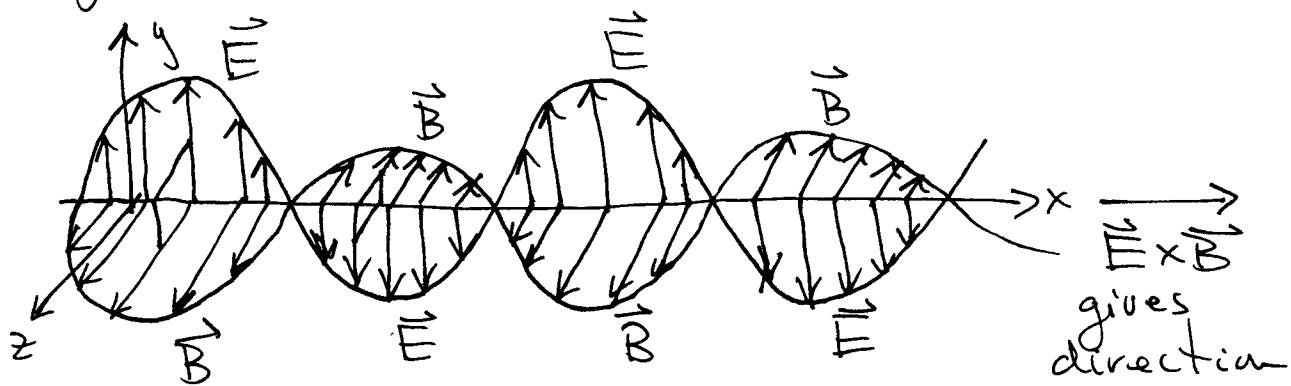
So $\frac{\omega}{k} = c = \frac{\omega}{2\pi} \frac{2\pi}{\lambda} = \omega \lambda$



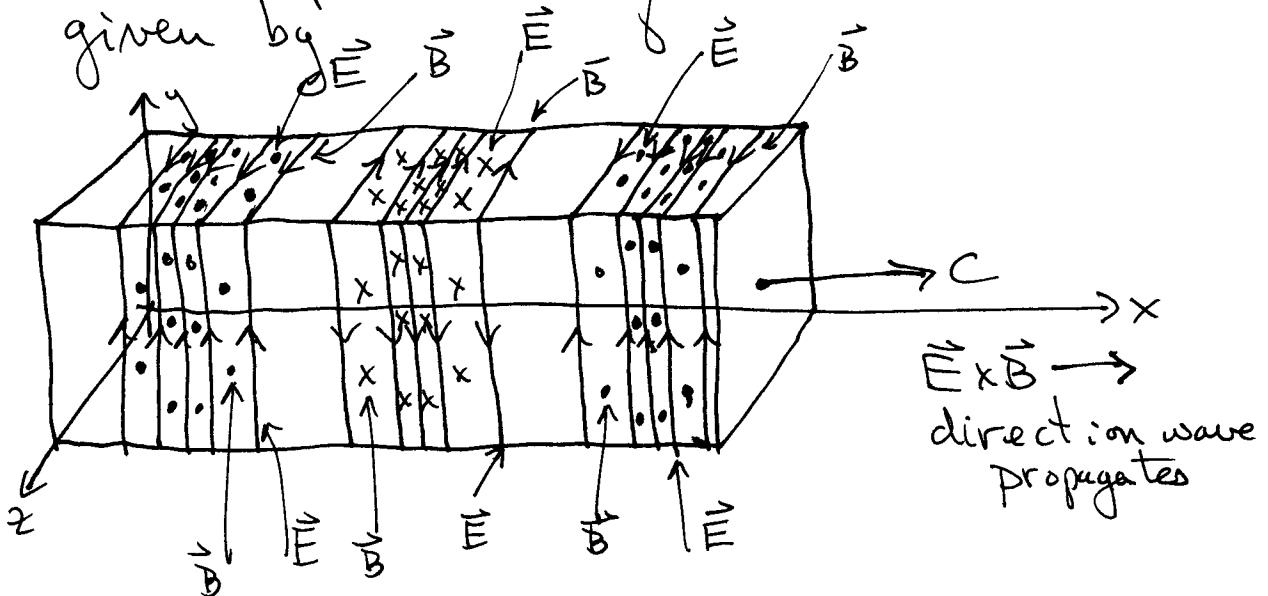
-IX. G) Linearly Polarized : $\vec{E} = E \hat{i}$
 $\vec{B} = B \hat{k}$

\vec{E} oscillates along one direction only, as does \vec{B} .

For fixed t this looks like



Another representation of the wave is given by



IX. H) Maxwell's Equations: $\frac{\partial E}{\partial x} = -\frac{\partial B}{\partial t}$: Faraday's Law
 $\frac{\partial B}{\partial x} = -\frac{1}{c^2} \frac{\partial E}{\partial t}$: Ampere's Law

\Rightarrow 1) E & B must be in phase

2)

$$E = cB$$

I) Energy Transport: The Poynting Vector

$$\vec{S} = \vec{E} \times \vec{H}$$

$$= \frac{1}{\mu_0} \vec{E} \times \vec{B} \quad \text{in vacuum}$$

\vec{S} = rate of energy flow per unit area in
 the direction of \vec{S}
 = electromagnetic power per unit area.

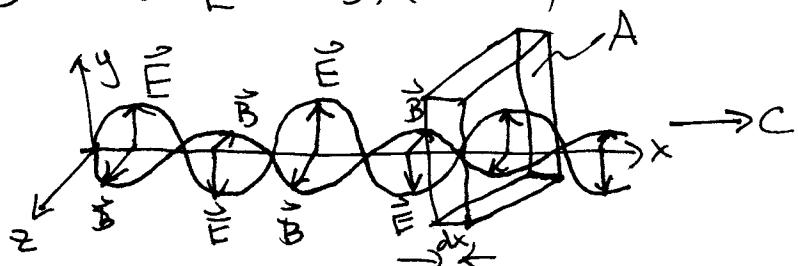
1) For above plane wave $\vec{S} = \frac{1}{\mu_0} EB \hat{i} = S \hat{i}$

↑ gives
 direction of propagation

$$2) dU = dU_E + dU_B = (u_E + u_B)(Adx)$$

$$u_E = \frac{1}{2} \epsilon_0 E^2$$

$$u_B = \frac{1}{2\mu_0} B^2$$



$$\text{IX.I.2) } dU = \frac{EBA}{\mu_0} \frac{dx}{c} \quad \text{but } dt = \frac{dx}{c}$$

This is amount of energy that passes through the box in time dt , the energy flow per unit time thru area A : $\frac{dU}{dt} = \frac{1}{\mu_0} EBA = S \cdot A$

So $S = \frac{dU}{dt A} = \frac{1}{\mu_0} EB$ is the energy flow per unit time per unit area.

3) Intensity $I = \bar{S} = \text{time average of } S$

$$I = \bar{S} = \frac{1}{2\mu_0} E_m B_m$$

$$= \frac{1}{\mu_0} E_{rms} B_{rms}$$

