

Physics 630

Classical electrodynamics

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Our goal this semester is to study the equations and phenomena of classical $E + M$, which follow from that tremendous synthesis into 4 vector equations, by James Clerk Maxwell.

In vacuum, written in SI units, Maxwell's eqns are:

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0} \quad (1)$$

$$\nabla \times \vec{B} - \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} = \mu_0 \vec{J} \quad (2)$$

$$\nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0 \quad (3)$$

$$\nabla \cdot \vec{B} = 0 \quad (4)$$

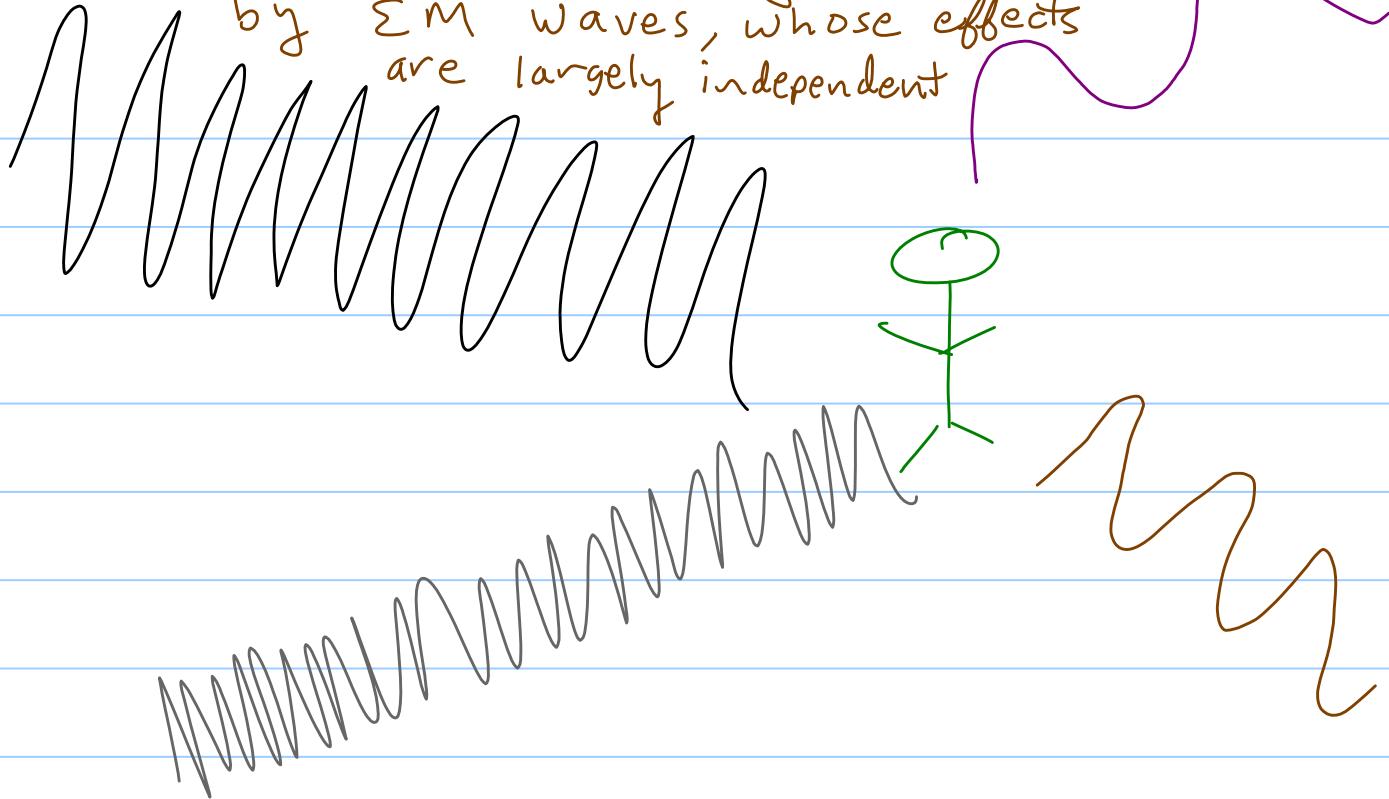
and these equations imply an auxiliary equation, derived by taking $\nabla \cdot (2)$ and plugging in (1):

$$\nabla \cdot \vec{J} + \frac{\partial \rho}{\partial t} = 0 \quad (5)$$

charge conservation law

IMPORTANT: Maxwell's equations are LINEAR,
First-order differential equations

We are constantly bombarded by EM waves, whose effects are largely independent



We also must describe the effects of \vec{E}, \vec{B} on the motion of a charged particle q .

In classical mechanics this is the

Lorentz force law,

$$\vec{F} = q \vec{E}(\vec{x}, t) + q \frac{d\vec{x}}{dt} \times \vec{B}(\vec{x}, t) \quad (6)$$

$\vec{E}(\vec{x}, t)$ = electric field at position \vec{x} , time t , or $(\frac{V}{m})$
 $\vec{B}(\vec{x}, t)$ = magnetic field " " " ", time t , (T)

$\rho(\vec{x}, t)$ = charge density, $(\frac{\text{Coulombs}}{\text{m}^3})$

$\vec{j}(\vec{x}, t)$ = current density, $(\frac{\text{Coulombs}}{\text{m}^2 \cdot \text{s}})$

And in a linear, homogeneous, dielectric medium, $\vec{D} = \epsilon \vec{E}$, $\vec{B} = \mu \vec{H}$

whereby (1) becomes $\nabla \cdot \vec{D} = \rho$ (1')

(2) becomes $\nabla \times \vec{H} - \frac{\partial \vec{D}}{\partial t} = \vec{J}$ (2')

c = vacuum light speed $\equiv 299792458 \frac{m}{s}$, EXACTLY

$$= \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

The first step in development of the subject of $\Sigma + M$ was the discovery of Coulomb's Law: For 2 point charges in a vacuum, the Coulomb force on q_1 due to q_2 is

$$\vec{F}_{1,2} = \frac{q_1 q_2}{4\pi \epsilon_0} \frac{\vec{x}_1 - \vec{x}_2}{|\vec{x}_1 - \vec{x}_2|^3}$$

Since the force on q_1 is proportional to q_1 , it is useful to define the electric field at \vec{x}_1 , independently of whether q_1 is actually there i.e. as

$$\vec{E}(\vec{x}_1) = \lim_{q_1 \rightarrow 0} \frac{\vec{F}_{1,2}}{q_1} = \frac{q_2}{4\pi \epsilon_0} \frac{\vec{x}_1 - \vec{x}_2}{|\vec{x}_1 - \vec{x}_2|^3}$$

If there are many charges, their net electric field at \vec{x} is the sum

$$\vec{E}(\vec{x}) = \sum_i \frac{q_i}{4\pi\epsilon_0} \frac{\vec{x} - \vec{x}_i}{|\vec{x} - \vec{x}_i|^3}$$

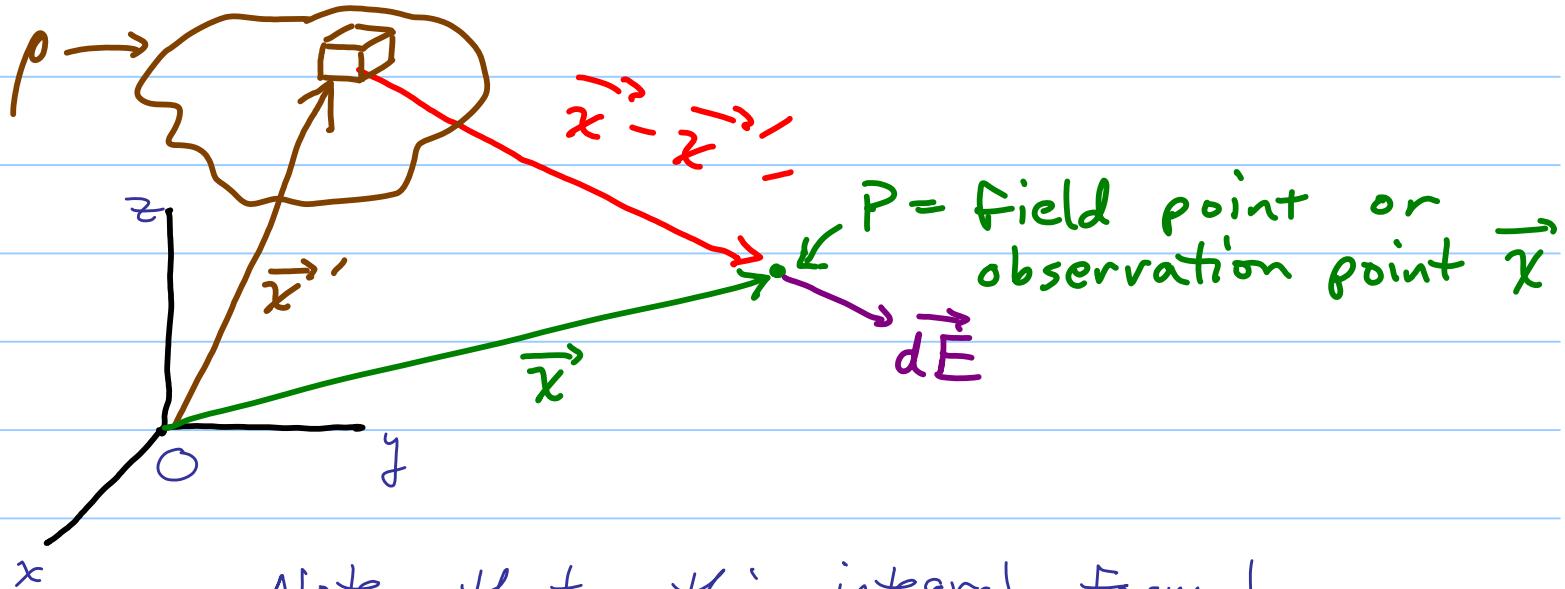
which generalizes for a continuous distribution of charges, through the substitutions

$$\vec{x}_i \rightarrow \vec{x}'$$

$$q_i \rightarrow dq' \equiv \rho(\vec{x}') d^3x'$$

giving the integral

$$\vec{E}(\vec{x}) = \frac{1}{4\pi\epsilon_0} \int d^3x' \rho(\vec{x}') \frac{\vec{x} - \vec{x}'}{|\vec{x} - \vec{x}'|^3}$$



Note that this integral formula can also be used for DISCRETE charges, provided we identify

$$\rho(\vec{x}') = \sum_i q_i \delta(\vec{x}' - \vec{x}_i)$$

Idealization Actually, all charges are discrete, so the most accurate picture would use sums only, but since there are often Avogadro's number of charges this is impractical. So approximating the sums by integrals is more practical and usually quite accurate.

Also, in classical E+M it is frequently stated that Gauss's Law implies that any net charge on a conductor in electrostatics must reside on its outermost surface, i.e. within an infinitesimally thin layer.

More realistic models including the quantum wavelike nature of the electrons shows (see Fig I.5) that the surface layer actually has a finite thickness of approximately $\Delta r \approx 2\text{ Å}$.

While this is not infinitely thin, it is thin enough so that for most applications it can be treated that way, i.e.

$$\rho(\vec{x}') = \sigma \delta(x' - R)$$

Math Review: Dirac delta functions

$$(1) \delta(x-a) = \begin{cases} 0, & x \neq a \\ " \infty ", & x = a \end{cases}$$

$$(2) \int_c^d \delta(x-a) dx = \begin{cases} 1, & c < a < d \\ -1, & c > a > d \\ 0, & \text{otherwise} \end{cases}$$

(Note: more careful consideration is needed)
if either $c=a$ or $d=a$.

explicit representations

$$\frac{1}{2} \frac{d^2}{dx^2} |x| = \delta(x)$$

$$\delta(x) = \pi^{-\frac{1}{2}} \lim_{\epsilon \rightarrow 0^+} e^{-\frac{1}{2\epsilon}} \exp(-x^2/\epsilon)$$

$$\delta(x) = \pi^{-1} \lim_{\epsilon \rightarrow 0^+} \frac{\epsilon}{x^2 + \epsilon^2}$$

$$\delta(x) = \pi^{-1} \lim_{N \rightarrow \infty} \frac{\sin Nx}{x}$$

$$\delta(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ikx} dk$$

$$(3) \int_{-\infty}^{\infty} dx f(x) \delta(x-a) dx = f(a), \quad a = \text{real}$$

$$\underline{\text{proof}} \quad \int_{-\infty}^{\infty} dx f(x) \left[\frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ik(x-a)} dk \right]$$

$$= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dk e^{-ika} \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dx f(x) e^{ikx} = f(a), \quad \text{QED}$$

since this is the inverse Fourier transform
of a Fourier transform.

$$(4) \int_{-\infty}^{\infty} f(x) \delta'(x-a) dx = f(x) \delta(x-a) \Big|_{-\infty}^{\infty} - \int_{-\infty}^{\infty} f'(x) \delta(x-a) dx \\ = -f'(a)$$

This result is sometimes written as

$$f(x) \frac{d}{dx} \delta(x-a) = -\delta(x-a) \frac{d}{dx} f(x)$$

$$(5) \quad \delta(ax) = \frac{1}{|a|} \delta(x)$$

corollary $\delta[f(x)] = \sum_i \frac{\delta(x-x_i)}{|f'(x_i)|}$

provided $f(x)$ has only simple zeroes at x_i .

$$\text{e.g. } \delta[(x-a)(x-b)] = \frac{1}{|a-b|} (\delta(x-a) + \delta(x-b))$$

(6) δ -functions in multiple dimensions

$$\delta(\vec{x} - \vec{x}') = \delta(x_1 - x'_1) \delta(x_2 - x'_2) \delta(x_3 - x'_3)$$

(in Cartesian coordinates)

This vanishes except at the point $\vec{x} = \vec{x}'$

i.e. $\int_V \delta(\vec{x} - \vec{x}') d^3x' = \begin{cases} 1 & \text{if } \vec{x} \text{ is in } V \\ 0 & \text{otherwise} \end{cases}$

3-dimensional representation

$$\delta(\vec{x} - \vec{x}') = (2\pi)^{-3} \int d^3k e^{i\vec{k} \cdot (\vec{x} - \vec{x}')}}$$

If we consider general orthogonal, curvilinear coordinates, g_1, g_2, g_3 with differential arc length,

$$ds^2 = h_1^2 dg_1^2 + h_2^2 dg_2^2 + h_3^2 dg_3^2$$

and volume element $d^3x = h_1 h_2 h_3 dg_1 dg_2 dg_3$,

then $\delta(\vec{x} - \vec{x}') = \frac{1}{h_1 h_2 h_3} \delta(g_1 - g'_1) \delta(g_2 - g'_2) \delta(g_3 - g'_3)$

e.g. in spherical coordinates,

$$\begin{aligned} \delta(\vec{x} - \vec{x}') &= \frac{1}{r^2 \sin \theta} \delta(r - r') \delta(\theta - \theta') \delta(\phi - \phi') \\ &= \frac{1}{r^2} \delta(r - r') \delta(\cos \theta - \cos \theta') \delta(\phi - \phi') \end{aligned}$$

(7) another identity: $\nabla^2 \frac{1}{r} = -4\pi \delta(\vec{r})$

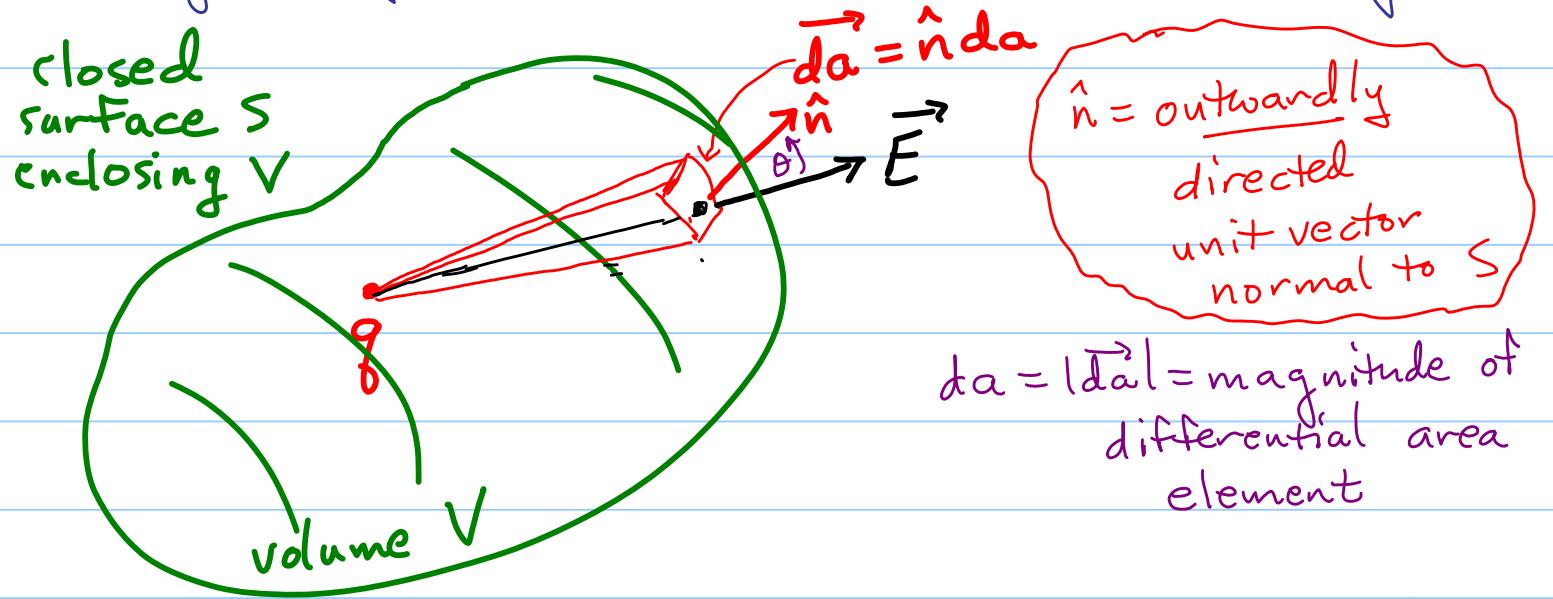
whereby we see that

$$\frac{1}{r} = \left[4\pi (2\pi)^{-3} \right] \int d^3k e^{\frac{i\vec{k} \cdot \vec{r}}{k^2}}$$

$\frac{1}{(2\pi^2)^{-1}}$

Gauss's Law - This is often more convenient than evaluating a 3-dimensional Coulomb's Law integral. It also exemplifies the intuitive power and beauty of geometrically reinterpreting a math formula.

To demonstrate this, consider a point charge q at a point in space, and draw an imaginary closed surface S surrounding it:



$$\text{Now observe that } \vec{E} \cdot \vec{da} = \frac{q}{4\pi\epsilon_0} \left(\frac{\cos\theta}{r^2} da \right)$$

$$\text{But } d\Omega = \cos\theta \frac{da}{r^2}, \quad \leftarrow$$

where $d\Omega$ = differential solid angle subtended by da from charge q .

So we can write

$$\oint_S \vec{E} \cdot \vec{da} = \oint_S \frac{q}{4\pi\epsilon_0} d\Omega = \begin{cases} q/\epsilon_0, & \text{if } q \text{ is in } V \\ 0, & \text{if } q \text{ is outside } V \end{cases}$$

Of course, this argument generalizes if there are many charges, i.e. by superposition which is permitted by the linearity of the equations, giving the key result:

$$\oint_S \vec{E} \cdot d\vec{a} = \frac{q_{\text{enclosed}}}{\epsilon_0} = \frac{1}{\epsilon_0} \int_V d^3x' \rho(\vec{x}')$$

where V = volume enclosed by S

Next, apply the divergence theorem:

$$\oint_S \vec{E} \cdot d\vec{a} = \int_V \nabla \cdot \vec{E} d^3x = \frac{1}{\epsilon_0} \int_V d^3x \rho(\vec{x})$$

and since the second equality holds for an ARBITRARY surface & volume, the integrands must themselves be equal everywhere, i.e.

$$\nabla \cdot \vec{E} = \rho / \epsilon_0$$

is equivalent to $\oint_S \vec{E} \cdot d\vec{a} = \frac{q_{\text{enclosed}}}{\epsilon_0}$

= Gauss's Law in differential and integral form

Electrostatic Potential

Consider

$$\nabla_x \frac{1}{|\vec{x} - \vec{x}'|} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \left[(x-x')^2 + (y-y')^2 + (z-z')^2 \right]^{-1/2}$$

$$= \frac{\hat{x} (-\frac{1}{2})(z)(x-x') + \hat{y} (-\frac{1}{2})(z)(y-y') + \hat{z} (-\frac{1}{2})(z)(z-z')}{[(x-x')^2 + (y-y')^2 + (z-z')^2]^{3/2}}$$

$$= -\frac{(\vec{x} - \vec{x}')}{|\vec{x} - \vec{x}'|^3} \quad \left(\begin{array}{l} \text{Aside: sometimes we} \\ \text{will abbreviate } \nabla_x \equiv \nabla \\ \nabla_{x'} \equiv \nabla' \end{array} \right)$$

Then Coulomb's Law
can be rewritten as:

$$\vec{E}(\vec{x}) = \int d^3x' \frac{\rho(\vec{x}')}{4\pi\epsilon_0} \frac{\vec{x} - \vec{x}'}{|\vec{x} - \vec{x}'|^3} = - \int d^3x' \frac{\rho(\vec{x}')}{4\pi\epsilon_0} \nabla \frac{1}{|\vec{x} - \vec{x}'|}$$

or we can write

$$\boxed{\vec{E} = -\nabla \Phi(\vec{x})}$$

where

$$\boxed{\Phi(\vec{x}) = \int d^3x' \frac{\rho(\vec{x}')}{4\pi\epsilon_0 |\vec{x} - \vec{x}'|} \equiv \text{Electrostatic Potential}}$$

Comments ① since $\nabla \times \nabla F = 0$ always $\Rightarrow \nabla \times \vec{E} = 0$ in electrostatics, always!

② This integral expression for Φ is not the most general, since it has implicitly assumed the B.C. that $\Phi(\vec{x}) \rightarrow 0$ as $r \rightarrow \infty$, whenever ρ has a finite extent.

③ If $\Phi(\vec{x})$ is one solution, then an equally good solution is $\Phi(\vec{x}) + \text{constant}$, since both give the same $\vec{E}(\vec{x})$

④ Don't forget that you need BOTH

$$\nabla \cdot \vec{E} = \rho / \epsilon_0$$

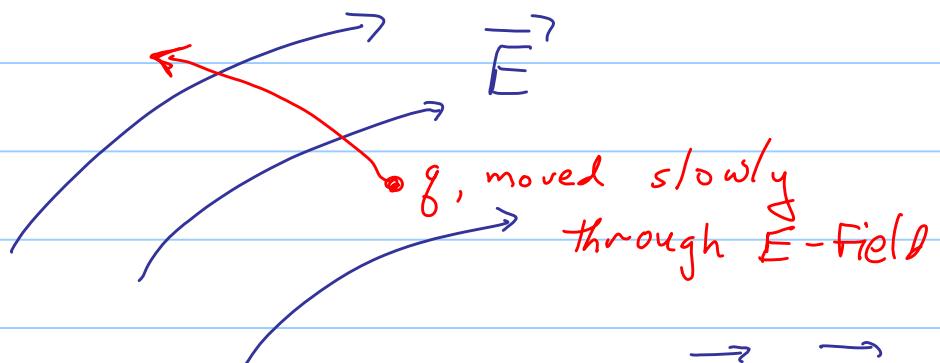
AND

$$\nabla \times \vec{E} = 0$$

to specify \vec{E} completely, i.e. to within the gradient of a scalar function f that obeys Laplace's equation, $\nabla^2 f = 0$.

Relationship to energy

Let's try to discuss this carefully, since it is easy to make sign errors when discussing work and potential energy.



The electric force on a charge g is $\vec{F} = g \vec{E}$
so the force WE apply to hold g fixed, or to move it very slowly, is $\vec{F}_{\text{us}} = -g \vec{E}$

Thus the work that WE do in slowly moving q from \vec{x}_1 to \vec{x}_2 along some path P is

$$W_2 - W_1 = \int_{\vec{x}_1}^{\vec{x}_2} \vec{F}_{us} \cdot d\vec{l} = - \int_{\vec{x}_1}^{\vec{x}_2} \vec{F} \cdot d\vec{l}$$

$$\text{or } W_2 - W_1 = -q \int_{\vec{x}_1}^{\vec{x}_2} \vec{E} \cdot d\vec{l} = +q \int_{\vec{x}_1}^{\vec{x}_2} \nabla \Phi \cdot d\vec{l}$$

$$= q \int_{\vec{x}_1}^{\vec{x}_2} d\Phi = q \Phi(\vec{x}_2) - q \Phi(\vec{x}_1)$$

Thus we can interpret $q \Phi(\vec{x})$ as the
ELECTRIC POTENTIAL ENERGY

i.e. if we do positive work, the potential energy must increase if kinetic energy = constant

Observations

① The work done is path-independent

$$-q \int_{\vec{x}_1}^{\vec{x}_2} \vec{E} \cdot d\vec{l} = q \Phi(\vec{x}_2) - q \Phi(\vec{x}_1)$$

② $\int_{\vec{x}_1}^{\vec{x}_1} \vec{E}(\vec{x}) \cdot d\vec{l} = \oint_C \vec{E}(\vec{x}) \cdot d\vec{l} = 0$

for ANY closed loop

③ $\oint_C \vec{E} \cdot d\vec{l} = \int_S \nabla \times \vec{E} \cdot d\vec{a} = 0$ is consistent with $\nabla \times \vec{E} = 0$