

YOUR IMAGINATION™

Blue Book

EXAMINATION BOOK

Box No. _____

NAME _____

SUBJECT PHYS 422

CLASS _____

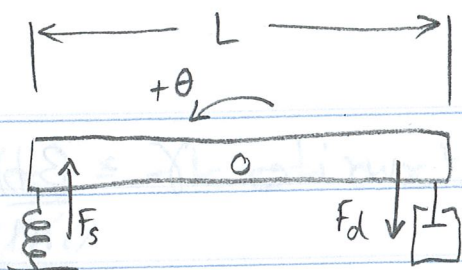
SECTION _____

INSTRUCTOR _____

DATE MARCH 10, 2016

8.5" x 7"

8 LEAVES 16 PAGES



$$F_s = \frac{kL\theta}{2}$$

$$F_d = \frac{bL\dot{\theta}}{2}$$

(directions as indicated on the free-body diagram)

Torques :

$$N_s = -\frac{kL^2\theta}{4}$$

$$N_d = -\frac{bL^2\dot{\theta}}{4}$$

Equation of motion :

$$I\ddot{\theta} = \sum N = -\frac{kL^2\theta}{4} - \frac{bL^2\dot{\theta}}{4}$$

or

$$\frac{ML^2}{12}\ddot{\theta} + \frac{bL^2}{4}\dot{\theta} + \frac{kL^2}{4}\theta = 0$$

$$\text{or } \ddot{\theta} + \frac{3b}{M}\dot{\theta} + \frac{3k}{M}\theta = 0$$

If we write $\gamma = \frac{3b}{M}$

$$\text{and } \omega_0^2 = \frac{3k}{M}$$

then the equation of motion is

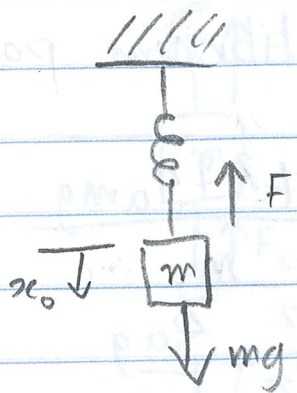
$$\ddot{\theta} + \gamma \dot{\theta} + \omega_0^2 \theta = 0$$

The frequency of free oscillations is

$$\omega = \sqrt{\omega_0^2 - \gamma^2/4}$$

$$= \sqrt{\frac{3k}{M} - \frac{9b^2}{4M^2}}$$

$$F(x) = -kx - ax^2$$



$$\uparrow F(x_0) \quad kx_0 + ax_0^2 = mg$$

$$ax_0^2 + kx_0 - mg = 0$$

$$x_0 = \frac{-k \pm \sqrt{k^2 + 4amg}}{2a}$$

$$= \frac{-k}{2a} + \sqrt{\frac{k^2}{4a^2} + \frac{mg}{a}}$$

we choose the positive root so that $x_0 > 0$.

$$F(x_0 + \delta x) = F(x_0) + \left. \frac{dF}{dx} \right|_{x_0} \delta x$$

$$\left. \frac{dF}{dx} \right|_{x_0} = -k - 2ax_0$$

$$= -k + k - \sqrt{k^2 + 4amg}$$

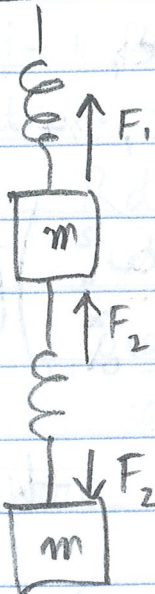
$$= -\sqrt{k^2 + 4amg}$$

Frequency of small oscillations about the equilibrium position

x_0 is

$$\omega_0^2 = \frac{k'}{m} = \frac{\sqrt{k^2 + 4amg}}{m}$$

$$= \sqrt{\frac{k^2}{m^2} + \frac{4ag}{m}}$$



$$F_1 = -kx_1$$

$$F_2 = -k(x_1 - x_2)$$

$$m\ddot{x}_1 + kx_1 + k(x_1 - x_2) = 0$$

$$\ddot{x}_1 + 2\omega_0^2 x_1 - \omega_0^2 x_2 = 0$$

$$m\ddot{x}_2 + k(x_2 - x_1) = 0$$

$$\ddot{x}_2 + \omega_0^2 x_2 - \omega_0^2 x_1 = 0$$

$$\ddot{x}_1 + 2\omega_0^2 x_1 - \omega_0^2 x_2 = 0$$

$$\ddot{x}_2 + \omega_0^2 x_2 - \omega_0^2 x_1 = 0$$

Assuming $x_1 = A \cos \omega t$

$$x_2 = B \cos \omega t$$

$$\ddot{x}_1 = -\omega^2 x_1$$

$$\ddot{x}_2 = -\omega^2 x_2$$

$$-\omega^2 x_1 + 2\omega_0^2 x_1 - \omega_0^2 x_2 = 0$$

$$-\omega^2 x_2 - \omega_0^2 x_1 + \omega_0^2 x_2 = 0$$

$$\begin{pmatrix} -\omega^2 + 2\omega_0^2 & -\omega_0^2 \\ -\omega_0^2 & -\omega^2 + \omega_0^2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

Let $\lambda = \omega^2$. then

$$(\omega_0^2 - \lambda)(2\omega_0^2 - \lambda) - \omega_0^4 = 0$$

$$\lambda^2 - 3\omega_0^2 \lambda + \omega_0^4 = 0$$

$$\lambda = \frac{3\omega_0^2}{2} \pm \frac{1}{2} \sqrt{9\omega_0^4 - 4\omega_0^4}$$

$$\omega^2 = \omega_0^2 \left(\frac{3}{2} \pm \frac{\sqrt{5}}{2} \right)$$

$$L \frac{di}{dt} + Ri + \frac{1}{C} \int i dt = V(\omega)$$

$$L \frac{d^2i}{dt^2} + R \frac{di}{dt} + \frac{i}{C} = -\omega V_0 \sin \omega t$$

$$\frac{d^2i}{dt^2} + \gamma \frac{di}{dt} + \omega_0^2 i = -\omega_0 V_0 \sin \omega t$$

where $\gamma = \frac{R}{L}$ $\omega_0^2 = \frac{1}{LC}$

Maximum power when $\omega = \omega_0 = \frac{1}{\sqrt{LC}}$

$$\text{FWHM} = \gamma = \frac{R}{L}$$

(a) With all holes closed the boundary conditions allow waves with $\lambda = 2L$.

$$\text{But } f = v/\lambda = \frac{v}{2L}$$



b) If there is a pressure node at $L/2$ then $\lambda = L$ and $f = \frac{v}{L}$.



c) If there is a pressure node at hole 1 then the lowest frequency would correspond to $\frac{\lambda}{2} = \frac{L}{4} \Rightarrow \lambda = \frac{L}{2}$

$$f = \frac{2v}{L}$$

$$y_k(t) = \sum_{n=1}^N a_n \sin\left(\frac{nkt\pi}{N+1}\right) \cos(\omega_n t)$$

$$y_k(0) = \sum_{n=1}^N a_n \sin\left(\frac{nkt\pi}{N+1}\right) = A \delta_{1k}$$

But,

$$\sum_{n=1}^N a_n \sin\left(\frac{nkt\pi}{N+1}\right) \sin\left(\frac{mkt\pi}{N+1}\right) = A \sum_k \delta_{1k} \sin\left(\frac{mkt\pi}{N+1}\right)$$

$$\sum_n a_n \delta_{nm} \cdot \frac{N}{2} = A \sin\left(\frac{m\pi}{N+1}\right)$$

$$a_m \cdot \frac{N}{2} = A \sin\left(\frac{m\pi}{N+1}\right)$$

$$a_m = \frac{2A}{N} \sin\left(\frac{m\pi}{N+1}\right)$$