

(1)

Assignment #4

1 (a) The Euler-Bernoulli equation in the absence of an external force is

$$YI \frac{\partial^4 w}{\partial x^4} + \mu \frac{\partial^2 w}{\partial t^2} = 0$$

If the boundary conditions are $w(0, t) = w(L, t) = 0$
then we propose that solutions are of the
form

$$w(x, t) = A \sin(k_n x) e^{i\omega_n t}.$$

In order to satisfy the boundary condition $w(L, t) = 0$
we must have

$$k_n L = n\pi.$$

Therefore, $k_n = \frac{n\pi}{L}$.

(b) We need to substitute the proposed solution into the differential equation.

$$\frac{\partial^4 w}{\partial x^4} = k_n^4 w(x, t) \quad \frac{\partial^2 w}{\partial t^2} = -\omega_n^2 w(x, t)$$

Therefore, $YI \frac{\partial^4 w}{\partial x^4} + \mu \frac{\partial^2 w}{\partial t^2} = (YI k_n^4 - \mu \omega_n^2) w = 0$

Hence, $\omega_n^2 = \frac{YI}{\mu} k_n^4 = \frac{YI}{\mu} \left(\frac{n\pi}{L}\right)^4$

$$\Rightarrow \omega_n = \pm \sqrt{\frac{YI}{\mu}} \left(\frac{n\pi}{L}\right)^2$$

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(c) Using the constants:

$$\begin{aligned}Y &= 69 \times 10^9 \text{ N} \cdot \text{m}^{-2} \\ \rho &= 2.7 \times 10^6 \text{ kg} \cdot \text{m}^{-3} \\ L &= 1 \text{ mm} = 10^{-3} \text{ m} \\ d &= 25 \mu\text{m} = 25 \times 10^{-6} \text{ m}\end{aligned}$$

The radius of the wire is $r = 12.5 \times 10^{-6} \text{ m}$.
The area moment of inertia is

$$I = \frac{1}{2}\pi r^4 = \frac{1}{2}(12.5 \times 10^{-6} \text{ m})^4 \times \pi = 3.835 \times 10^{-20} \text{ m}^4$$

The mass per unit length is

$$\begin{aligned}\mu &= \pi r^2 \rho = \pi (12.5 \times 10^{-6} \text{ m})^2 (2.7 \times 10^6 \text{ kg} \cdot \text{m}^{-3}) \\ &= 1.325 \times 10^{-3} \text{ kg/m}\end{aligned}$$

$$\begin{aligned}\text{Then } f_1 &= \frac{\omega_1}{2\pi} = \frac{1}{2\pi} \sqrt{\frac{Y I}{\mu}} \left(\frac{\pi}{L} \right)^2 \\ &= \frac{\pi}{2} \left(\frac{(69 \times 10^9 \text{ N} \cdot \text{m}^{-2})(3.835 \times 10^{-20} \text{ m}^4)}{1.325 \times 10^{-3} \text{ kg} \cdot \text{m}^{-1}} \right) \left(\frac{\pi}{10^{-3} \text{ m}} \right)^2 \\ &= 2220 \text{ s}^{-1} \\ &= 2.22 \text{ kHz}.\end{aligned}$$

2. This question asks for a solution to the initial value problem with boundary conditions $y(0,t) = y(L,t) = 0$ and initial conditions $y(x,0) = 0$, and

$$\dot{y}(x,0) = vx(L-x).$$

where v is just some constant with dimensions $\text{m}^{-1}\text{s}^{-1}$.

The general solution can be written

$$y(x,t) = \sum_n a_n \sin\left(\frac{n\pi x}{L}\right) \sin(\omega_n t)$$

$$\text{where } \omega_n = \frac{n\pi}{L} \sqrt{\frac{T}{\mu}}$$

The choice of $\sin(\omega_n t)$ ensures that $y(x,0) = 0$.

The time derivative of the general solution is

$$\dot{y}(x,t) = \sum_n a_n \omega_n \sin\left(\frac{n\pi x}{L}\right) \cos(\omega_n t)$$

$$\text{so at } t=0, \dot{y}(x,0) = \sum_n a_n \omega_n \sin\left(\frac{n\pi x}{L}\right).$$

We can calculate $a_n \omega_n$ from the integral

$$a_n \omega_n = \frac{2}{L} \int_0^L y(x,0) \sin\left(\frac{n\pi x}{L}\right) dx$$

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As we showed in class (Lecture 16) the even terms must vanish.

The odd terms are symmetric about $x = L/2$ so we just need to calculate

$$\begin{aligned} a_n w_n &= \frac{4U}{L} \int_0^{L/2} x(L-x) \sin\left(\frac{n\pi x}{L}\right) dx \\ &= 4U \int_0^{L/2} x \sin\left(\frac{n\pi x}{L}\right) dx \\ &\quad - \frac{4U}{L} \int_0^{L/2} x^2 \sin\left(\frac{n\pi x}{L}\right) dx \end{aligned}$$

The first integral can be evaluated using

$$\begin{aligned} \int x \sin(ax) dx &= -\frac{x}{a} \cos(ax) + \frac{1}{a^2} \sin(ax) \\ \int_0^{L/2} x \sin\left(\frac{n\pi x}{L}\right) dx &= -\left(\frac{L}{2}\right)\left(\frac{L}{n\pi}\right) \cos\left(\frac{n\pi}{2}\right) + \left(\frac{L}{n\pi}\right)^2 \sin\left(\frac{n\pi}{2}\right) \end{aligned}$$

But we only care about odd n , so

$$4U \int_0^{L/2} x \sin\left(\frac{n\pi x}{L}\right) dx = \pm 4U \left(\frac{L}{n\pi}\right)^2$$

The second integral can be evaluated using

$$\int x^2 \sin(ax) dx = \frac{2-a^2x^2}{a^3} \cos(ax) + \frac{2x}{a^2} \sin(ax)$$

$$\text{So } -\frac{4U}{L} \int_0^{L/2} x^2 \sin\left(\frac{n\pi x}{L}\right) dx = \mp \left(\frac{4U}{L}\right) L \cdot \left(\frac{L}{n\pi}\right)^2 + \frac{4U}{L} \cdot 2 \left(\frac{L}{n\pi}\right)^3$$

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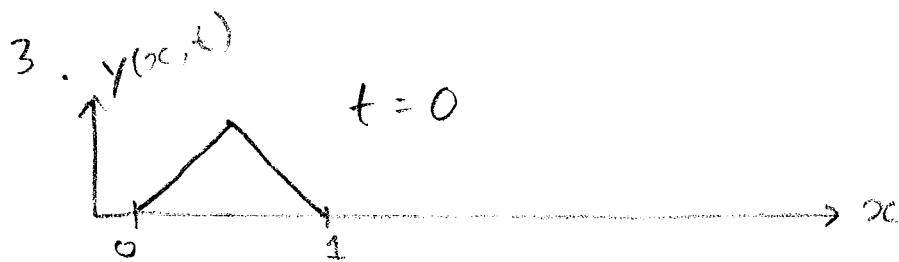
The first terms from each integral cancel so we are left with

$$a_n \omega_n = \frac{8vL^2}{(n\pi)^3} \quad \text{for } n=1, 3, 5, 7, \dots$$

Therefore, $a_n = 0$ when $n=2, 4, 6, \dots$

$$\begin{aligned} \text{and } a_n &= \frac{8vL^2}{(n\pi)^3} \cdot \frac{1}{(n\pi)} \sqrt{\frac{u}{T}} \quad \text{when } n=1, 3, 5, \dots \\ &= \frac{8vL^3}{(n\pi)^4} \sqrt{\frac{u}{T}} \end{aligned}$$

(6)



If the static pulse is described by the function $f(x)$ as shown, then the time dependent description of the pulse is

$$y(x, t) = f(x - vt)$$

The transverse velocity is

$$\dot{y}(x, t) = \frac{dy}{dt} = \frac{df}{dx} \frac{dx}{dt} = -v f'(x - vt)$$

$$\text{Since } f'(x) = \frac{0.4 \text{ m}}{0.5 \text{ m}} = 0.8 \quad \text{for } 0 < x < \frac{1}{2} \text{ m}$$

$$\text{and } f'(x) = -0.8 \quad \text{for } \frac{1}{2} < x < 1 \text{ m}.$$

The derivative will have the value of

$$(24 \text{ m/s})(0.8) \quad \text{for } 0 < t < \frac{0.5 \text{ m}}{24 \text{ m/s}}$$

$$\text{and } -(24 \text{ m/s})(0.8) \quad \text{for } \frac{0.5 \text{ m}}{24 \text{ m/s}} < t < \frac{1 \text{ m}}{24 \text{ m/s}}.$$

