

# Physics 42200 Waves & Oscillations

Lecture 22 – Review

Spring 2013 Semester

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#### **Midterm Exam:**

Date: Wednesday, March 6<sup>th</sup>

Time: 8:00 - 10:00 pm

Room: PHYS 203

Material: French, chapters 1-8

#### Review

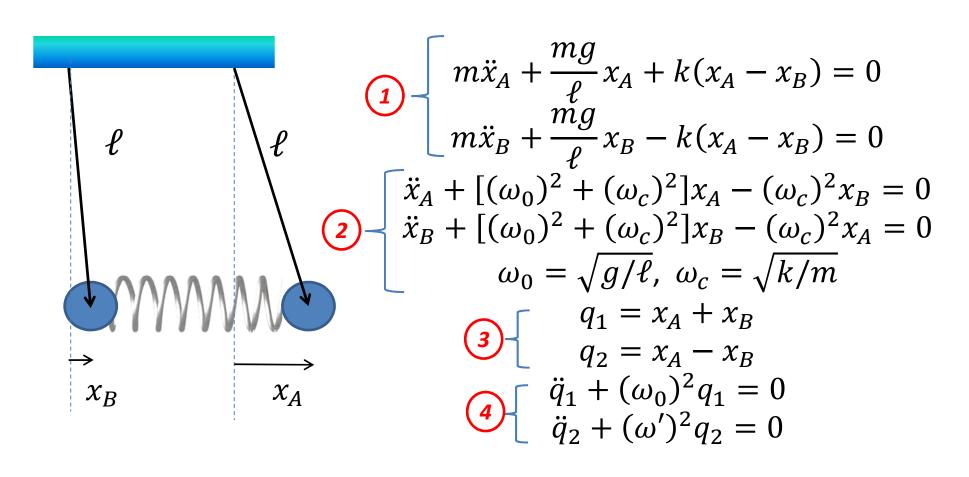
- 1. Simple harmonic motion (one degree of freedom)
  - mass/spring, pendulum, water in pipes, RLC circuits
  - damped harmonic motion
- 2. Forced harmonic oscillators
  - amplitude/phase of steady state oscillations
  - transient phenomena
- 3. Coupled harmonic oscillators
  - masses/springs, coupled pendula, RLC circuits
  - forced oscillations
- 4. Uniformly distributed discrete systems
  - masses on string fixed at both ends
  - lots of masses/springs

#### Review

- 5. Continuously distributed systems (standing waves)
  - string fixed at both ends
  - sound waves in pipes (open end/closed end)
  - transmission lines
  - Fourier analysis
- 6. Progressive waves in continuous systems
  - dispersion, phase velocity/group velocity
  - reflection/transmission coefficients
- 7. Waves in two and three dimensions
  - Laplacian operator
  - Rotationally symmetric solutions in 2d and 3d

## **Coupled Discrete Systems**

 The general method of calculating eigenvalues will always work, but for simple systems you should be able to decouple the equations by a change of variables.



#### **Forced Oscillations**

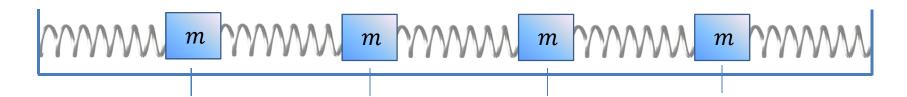
- We mainly considered the qualitative aspects
  - We did not analyze the behavior when damping forces were significant
- Main features:
  - Resonance occurs at each normal mode frequency
  - Phase difference is  $\delta = \pi/2$  at resonance
- Example:  $x_A$  driven by the force  $F(\omega) = F_0 \cos \omega t$ 
  - Calculate force term applied to normal coordinates

$$F_1(\omega) = F_2(\omega) = F_0 \cos \omega t$$

Reduced to two one-dimensional forced oscillators:

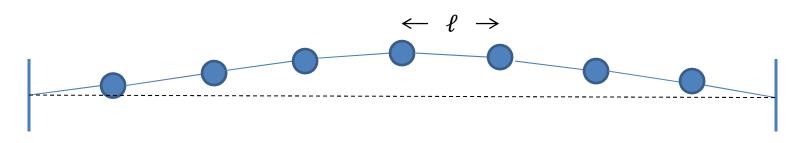
$$\ddot{q}_1 + (\omega_0)^2 q_1 = F_0/m \cos \omega t$$
  
$$\ddot{q}_2 + (\omega')^2 q_2 = F_0/m \cos \omega t$$

#### **Uniformly Distributed Discrete Systems**



Equations of motion for masses in the middle:

$$\ddot{x}_i + 2(\omega_0)^2 x_i - (\omega_0)^2 (x_{i-1} + x_{i+1}) = 0$$
$$(\omega_0)^2 = k/m$$



$$\ddot{y}_n + 2(\omega_0)^2 y_n - (\omega_0)^2 (y_{n+1} + y_{n-1}) = 0$$
$$(\omega_0)^2 = T/m\ell$$

## **Uniformly Distributed Discrete Masses**

Proposed solution:

$$\frac{x_n(t) = A_n \cos \omega t}{A_{n-1} + A_{n+1}} = \frac{-\omega^2 + 2(\omega_0)^2}{(\omega_0)^2}$$

We solved this to determine  $A_n$  and  $\omega_k$ :

his to determine 
$$A_n$$
 and  $\omega_k$ :
$$A_{n,k} = C \sin\left(\frac{nk\pi}{N+1}\right) \begin{array}{l} \text{Amplitude of mass } n \\ \text{Amplitude of mass } n \\ \text{Amplitude of mormal} \\ \text{Oscillating in normal} \\ \text{mode } k \\ \text{mode } k \\ \text{oscillating of normal} \\ \omega_k = 2\omega_0 \sin\left(\frac{k\pi}{2(N+1)}\right) \begin{array}{l} \text{Frequency of normal} \\ \text{Frequency of normal} \\ \text{mode } k \\ \text{mode } k \end{array}$$
 stion:

General solution:

$$x_n(t) = \sum_{k=1}^{N} a_k \sin\left(\frac{nk\pi}{N+1}\right) \cos(\omega_k t - \delta_k)$$

## **Vibrations of Continuous Systems**

Amplitude of mass n for normal mode k:

$$A_{n,k} = C \sin\left(\frac{nk\pi}{N+1}\right)$$

Frequency of normal mode k:

$$\omega_k = 2\omega_0 \sin\left(\frac{k\pi}{2(N+1)}\right)$$

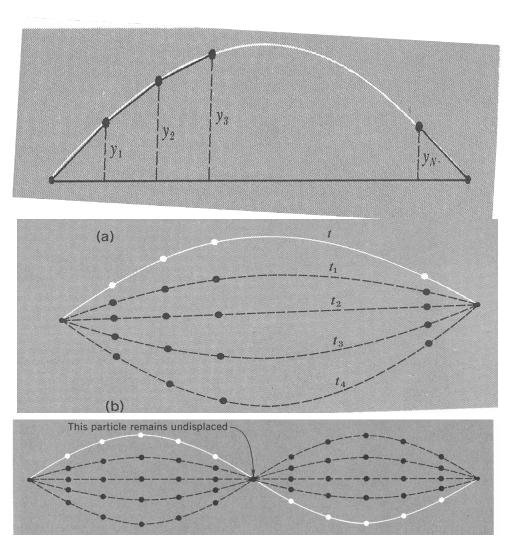
Solution for normal modes:

$$x_n(t) = A_{n,k} \cos \omega_k t$$

General solution:

$$x_n(t) = \sum_{k=1}^{N} a_k \sin\left(\frac{nk\pi}{N+1}\right) \cos(\omega_k t - \delta_k)$$

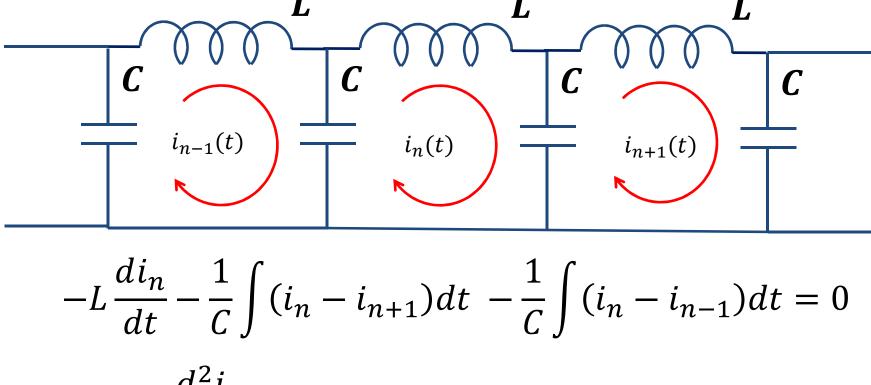
## Masses on a String



First normal mode

Second normal mode

## **Lumped LC Circuit**



$$\frac{d^2i_n}{dt^2} + 2\omega_0^2i_n - \omega_0^2(i_{n-1} + i_{n+1}) = 0$$

This is the exact same problem as the previous two examples.

## **Forced Coupled Oscillators**

- Qualitative features are the same:
  - Motion can be decoupled into a set of N independent oscillator equations (normal modes)
  - Amplitude of normal mode oscillations are large when driven with the frequency of the normal mode
  - Phase difference approaches  $\pi/2$  at resonance
- You should be able to anticipate the qualitative behavior when coupled oscillators are driven by a periodic force.

#### **Continuous Distributions**

Limit as  $N \to \infty$  and  $m/\ell \to \mu$ :

$$\frac{\partial^2 y}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 y}{\partial t^2}$$

Boundary conditions specified at x = 0 and x = L:

- Fixed ends: y(0) = y(L) = 0
- Maximal motion at ends:  $\dot{y}(0) = \dot{y}(L) = 0$
- Mixed boundary conditions

Normal modes will be of the form

$$y_n(x,t) = A_n \sin(k_n x) \cos(\omega_n t - \delta_n)$$

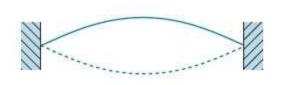
or 
$$y_n(x,t) = A_n \cos(k_n x) \cos(\omega_n t - \delta_n)$$

## **Properties of the Solutions**

$$y(L,t) \sim \sin k_n L = 0 \quad \Rightarrow \quad k_n L = n\pi$$

$$\Rightarrow$$

$$k_n L = n\pi$$



mode

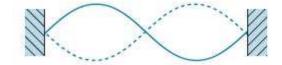
first

wavelength

frequency

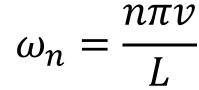
2L

$$\lambda_n = \frac{2L}{n}$$



second

L



third

$$f_n = \frac{nv}{2L}$$

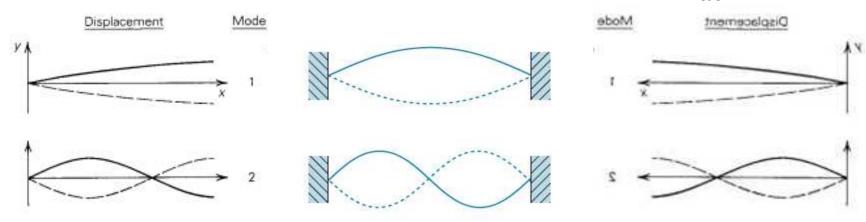
fourth

 $\frac{L}{2}$ 

## **Boundary Conditions**

#### Examples:

- String fixed at both ends: y(0) = y(L) = 0
- Organ pipe open at one end:  $\dot{y}(0) = \dot{y}(L) = 0$ 
  - Driving end has maximal pressure amplitude
- Organ pipe closed at one end:  $\dot{y}(0) = 0$ , y(L) = 0
- Transmission line open at one end: i(L) = 0
- Transmission line shorted at one end:  $v(L) \propto \frac{di(L)}{dt} = 0$



• Normal modes satisfying y(0) = y(L) = 0:

$$y_n(x,t) = A_n \sin\left(\frac{n\pi x}{L}\right) \cos(\omega_n t - \delta_n)$$

General solution:

$$y(x,t) = \sum_{n=1}^{\infty} A_n \sin\left(\frac{n\pi x}{L}\right) \cos(\omega_n t - \delta_n)$$

Initial conditions:

$$y(x,0) = \sum_{n=1}^{\infty} A_n \sin\left(\frac{n\pi x}{L}\right) \cos(\delta_n) = \sum_{n=1}^{\infty} B_n \sin\left(\frac{n\pi x}{L}\right)$$
$$\dot{y}(x,0) = \sum_{n=1}^{\infty} A_n \omega_n \sin\left(\frac{n\pi x}{L}\right) \sin(\delta_n) = \sum_{n=1}^{\infty} C_n \sin\left(\frac{n\pi x}{L}\right)$$

• Fourier sine transform:

$$u(x) = \sum_{n=1}^{\infty} B_n \sin\left(\frac{n\pi x}{L}\right)$$
$$B_n = \frac{2}{L} \int_0^L u(x) \sin\left(\frac{n\pi x}{L}\right) dx$$

Fourier cosine transform:

$$v(x) = \sum_{n=1}^{\infty} B_n \cos\left(\frac{n\pi x}{L}\right)$$
$$B_n = \frac{2}{L} \int_0^L v(x) \cos\left(\frac{n\pi x}{L}\right) dx$$

$$B_n = A_n \cos \delta_n$$

$$C_n = A_n \omega_n \sin \delta_n$$

Solve for amplitudes:

$$A_n = \sqrt{B_n^2 + \frac{C_n^2}{\omega_n^2}}$$

Solve for phase:

$$\tan \delta_n = \frac{C_n}{B_n \omega_n}$$

- Suggestion: don't simply rely on these formulas use your knowledge of the boundary conditions and initial conditions.
- Example:
  - If you are given  $\dot{y}(x,0) = 0$  and y(0) = y(L) = 0 then you know that solutions are of the form

$$y(x,t) = \sum A_n \sin\left(\frac{n\pi x}{L}\right) \cos \omega_n t$$

- If you are given  $\dot{y}(x,0) = 0$  and  $\dot{y}(0) = 0$ , y(L) = 0 then solutions are of the form

$$y(x,t) = \sum_{odd,n} A_n \cos\left(\frac{n\pi x}{L}\right) \cos\omega_n t$$

#### **Progressive Waves**

 Far from the boundaries, other descriptions are more transparent:

$$y(x,t) = f(x \pm vt)$$

The Fourier transform gives the frequency components:

$$A(k) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) \cos(kx) dx$$

$$B(k) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) \sin(kx) dx$$

$$g(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} A(k) \cos(kx) dk + \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} B(k) \sin(kx) dk$$

- Narrow pulse in space wide range of frequencies
- Pulse spread out in space narrow range of frequencies

## **Properties of Progressive Waves**

- Power carried by a wave:
  - String with tension T and mass per unit length  $\mu$

$$P = \frac{1}{2}\mu\omega^{2}A^{2}v = \frac{1}{2}Z\omega^{2}A^{2}$$

• Impedance of the medium:

$$Z = \mu v = T/v$$

- Important properties:
  - Impedance is a property of the medium, not the wave
  - Energy and power are proportional to the square of the amplitude

#### Reflections

- Wave energy is reflected by discontinuities in the impedance of a system
- Reflection and transmission coefficients:
  - The wave is incident and reflected in medium 1
  - The wave is transmitted into medium 2

$$ho = rac{Z_1 - Z_2}{Z_1 + Z_2} \ au = rac{2Z_1}{Z_1 + Z_2}$$

Important: when is this negative?

Wave amplitudes:

$$A_r = \rho A_i$$
$$A_t = \tau A_i$$

#### Reflected and Transmitted Power

- Power is proportional to the square of the amplitude.
  - Reflected power:  $P_r = \rho^2 P_i$
  - Transmitted power:  $P_t = \tau^2 P_i$
- You should be able to demonstrate that energy is conserved:

ie, show that 
$$P_i = P_r + P_t$$

## Dispersion

- Wave speed is sometimes a function of frequency.
- Phase velocity:  $v = \lambda f = \frac{\omega}{k}$  (constant)
- Group velocity:  $v_g = \frac{d\omega}{dk}$  (function of frequency)
- Energy that is carried by a pulse propagates with the group velocity
- In optics, v = c/n(k) and

$$v_g = v \left( 1 - \frac{k}{n} \frac{dn}{dk} \right)$$

(evaluated at the average wavenumber of the pulse)

#### Waves in Two and Three Dimensions

Wave equation:

$$\nabla^2 \psi = \frac{1}{v^2} \frac{\partial^2 \psi}{\partial t^2}$$

 When the function only depends on the radius, (eg,  $\partial \psi/d\theta = 0$ ) then this can be written:

$$\nabla^2 \psi = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial \psi}{\partial r} \right) = \frac{1}{v^2} \frac{\partial^2 \psi}{\partial t^2} \qquad \text{Polar coordinates (2d)}$$

$$\nabla^2 \psi = \frac{1}{r} \frac{\partial^2}{\partial r^2} (r\psi) = \frac{1}{v^2} \frac{\partial^2 \psi}{\partial t^2}$$
 Spherical coordinates (3d)

#### Waves in Two Dimensions

Wave equation in polar coordinates:

tion in polar coordinates: 
$$\nabla^2 \psi = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial \psi}{\partial r} \right) = \frac{1}{v^2} \frac{\partial^2 \psi}{\partial t^2} \qquad \text{But only when } 0!$$
 uation:

Bessel's equation:

$$\frac{\partial^2 \psi}{\partial r^2} + \frac{1}{r} \frac{\partial \psi}{\partial r} + \frac{\omega^2}{v^2} \psi = 0$$

Let 
$$z = kr$$
  
where  $k = \omega/v$  
$$\frac{\partial^2 \psi}{\partial z^2} + \frac{1}{z} \frac{\partial \psi}{\partial z} + \psi(z) = 0$$

• Solutions: 
$$J_0(z) \sim \sqrt{\frac{2}{\pi}} \frac{\cos(z-\pi/4)}{\sqrt{z}}$$
 and  $Y_0(z) \sim \sqrt{\frac{2}{\pi}} \frac{\sin(z-\pi/4)}{\sqrt{z}}$ 

#### Waves in Three Dimensions

Wave equation in spherical coordinates:

ation in spherical coordinates: 
$$\nabla^2 \psi = \frac{1}{r} \frac{\partial^2}{\partial r^2} (r \psi) = \frac{1}{v^2} \frac{\partial^2 \psi}{\partial t^2}$$

• When  $\frac{\partial^2 \psi}{\partial t^2} = -\omega^2 \psi$  this is

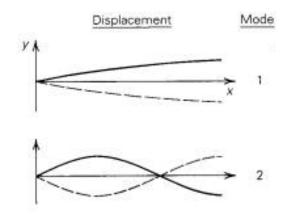
$$\frac{1}{r}\frac{\partial^2}{\partial r^2}(r\psi) + \frac{\omega^2}{v^2}\psi = 0$$

Solutions are of the form:

$$\psi(r,t) = A \frac{e^{ikr}}{r} \cos \omega t$$

## Boundary Conditions in Two and Three Dimensions

- When a boundary condition imposes the restriction that  $\psi(R,t)=0$  then the function must have a node at r=R.
- Analogous to the 1-dimensional case:



This imposes the requirement that kR is a root of the equation f(kR) = 0 which implies that  $k_n = \frac{\omega_n}{v} = z_n/R$  where  $z_n$  are roots of f(z) = 0.

#### That's all for now...

- Study these topics make sure you understand the examples and assignment questions.
- Send e-mail if you would like specific examples discussed before the exam next Wednesday.

Next topics: waves applied to optics.