

For deriving the quantum mechanical dynamical equations of motion, it is most convenient to work with the first order formulation. As we already know, since the Lagrangian is invariant under ^{local} gauge transformations, so will be the equations of motion for the potentials A_μ , hence they are not completely determined by the equations. That is, we must choose a particular gauge condition which gives ^{with gauge} the angles α and hence selects one A_μ from its gauge orbit - then the equations of motion determine A_μ 's time evolution uniquely.

Alternatively stated, when we quantize a theory we do so in terms of the ^{independent} dynamical degrees of freedom. That is we identify the independent variables and their canonically conjugate momenta of the system. The Hamiltonian is expressed in terms of these variables alone and describes their time evolution through the Heisenberg equation of motion. We can then represent the Green function as a path integral over the independent dynamical variables. Since the Lagrangian is gauge invariant not all of the

Euler-Lagrange equations of motion will be independent — they do not determine the arbitrary angles $w^a(x)$ — that is, what local gauge invariance means. Hence there will be a linear relation among equations of motion (this is the second Noether theorem which we will not dwell upon), this implies that not all the fields A_μ^a are independent. In fact, as we will see, A_0^a acts as a Lagrange multiplier imposing this fundamental constraint among the fields. Hence in order to describe the quantum mechanical time evolution of the system correctly we must eliminate the constrained fields (interms of the independent dynamical variables) so that we can write the Hamiltonian in terms of them explicitly. The non-independence of the potentials A_μ^a requires a relation between them, this is given by the gauge condition — choosing a gauge, since the dynamics is independent of the gauge choice we are free to choose it at our convenience. From QED we know that the Coulomb gauge condition allows us to isolate the transverse independent degrees of

freedom most easily, however, it does so in a non-manifestly Lorentz invariant way. The Lorentz gauge condition although manifestly Lorentz invariant does not allow this separation of the "coordinates" into independent and dependent without introducing unphysical, auxiliary, degrees of freedom. Hence we will derive the quantum mechanical equations of motion for the Hamiltonian in terms of the independent coordinate and momenta in the Coulomb gauge, and then show that the S-matrix is the same as if we worked in the Lorentz gauge, that is we will prove equivalence of the general functional (up to field redefinition) to the two gauges.

Hence to start consider the first order formulation Lagrangian

$$\mathcal{L}_{inv} \equiv +\frac{1}{4} F_{\nu}^a F^{\nu\mu} + \mathcal{L}(\psi, D\psi) - \frac{1}{2} F_{\nu}^a (\delta^{\mu\nu} A^{\alpha\beta} - \delta^{\mu\alpha} A^{\nu\beta} - \delta^{\mu\beta} A^{\nu\alpha}) A^{\nu\alpha}$$

The Euler-Lagrange equations are given by

$$1) \frac{\delta \mathcal{L}_{\text{inv}}}{\delta F_{\mu\nu}^a} = 0 \Rightarrow \boxed{F_{\mu\nu}^a = \partial_\mu A_\nu^a - \partial_\nu A_\mu^a - f_{abc} A_\mu^b A_\nu^c}$$

$$2) \frac{\delta \mathcal{L}_{\text{inv}}}{\delta A_\mu^a} - \partial_\nu \frac{\delta \mathcal{L}_{\text{inv}}}{\delta \partial_\nu A_\mu^a} = 0$$

$$\Rightarrow -\partial^\nu F_{\mu\nu}^a = f_{abc} F_{\mu\nu}^b A^{c\nu} + \frac{\delta \mathcal{L}(\phi, D_\mu \phi)}{\delta A^{a\mu}} = 0$$

But recall that $\frac{\delta \mathcal{L}(\phi, D_\mu \phi)}{\delta A^{a\mu}} = \frac{\delta \mathcal{L}}{\delta (D^\mu \phi)^\alpha} \frac{\delta (D^\mu \phi)^\alpha}{\delta A^{a\mu}}$

however

$$\frac{\delta (D^\mu \phi)^\alpha}{\delta A^{a\mu}} = ig^\mu{}_\nu (T^a)^\alpha{}_\beta \phi^\beta$$

So $\frac{\delta \mathcal{L}(\phi, D_\mu \phi)}{\delta (D^\mu \phi)^\alpha} \frac{\delta (D^\mu \phi)^\alpha}{\delta A^{a\mu}} = \frac{\delta \mathcal{L}(\phi, D_\mu \phi)}{\delta (D^\mu \phi)^\alpha} (T^a)^\alpha{}_\beta \phi^\beta$

$$= J_\mu^a(\phi, D_\mu \phi)$$

So we have

$$\left[\partial^\nu F_{\mu\nu}^a - f_{abc} A^{b\nu} F_{\mu\nu}^c \right] = J_\mu^a$$

Then of course we have the "matter" field equation

$$\partial_\mu \frac{\delta \mathcal{L}_{\text{inv}}}{\delta \phi^a} - \partial_\mu \frac{\delta \mathcal{L}_{\text{inv}}}{\delta \partial_\mu \phi^a} = 0$$

$$= \frac{\delta \mathcal{L}(\phi, \partial_\mu \phi)}{\delta \phi^a} - \partial_\mu \frac{\delta \mathcal{L}(\phi, \partial_\mu \phi)}{\delta \partial_\mu \phi^a} = 0$$

Now since the Lagrangian is gauge invariant

$$\mathcal{L}_{\text{inv}}(A, F, \phi) = \mathcal{L}_{\text{inv}}(A^g, F^g, \phi^g)$$

where

$$A_\mu^g(x) \equiv U^g(x) A_\mu(x) U^g(x)$$

$$= U^g(x) \partial_\mu U^g(x) + U^g(x) A_\mu(x) U^g(x)$$

$$F^g_{\mu\nu} \equiv U^{-1}(g) F_{\mu\nu} U(g) \\ = U(g) F_{\mu\nu} U^{-1}(g)$$

and

$$\phi^g \equiv U^{-1}(g) \phi U(g) \\ = U(g) \phi$$

The field equations have the same form for $A^g_\mu, F^g_{\mu\nu}, \phi^g$; with $g(x)$ completely arbitrary. Thus there must be a relation among the equations for $A_\mu, F_{\mu\nu}$ since they are not uniquely determined. Defining the adjoint representation covariant derivative as

$$(\nabla_\mu)^{ab} \equiv \partial_\mu \delta^{ab} - f_{abc} A_\mu^c$$

the $F_{\mu\nu}$ field equation yields

$$(\nabla^\nu F_{\mu\nu})^a = J_\mu^a$$

Taking the covariant derivative again yields

$$\begin{aligned}\nabla^\mu \nabla^\nu F_{\mu\nu} &= \nabla^\mu J_\mu \\ &= \frac{1}{2} [\nabla^\mu, \nabla^\nu] F_{\mu\nu} \quad \text{since } F_{\mu\nu} = -F_{\nu\mu}\end{aligned}$$

but as before

$$[\nabla^\mu, \nabla^\nu] = i(T^a) F^a_{\mu\nu}$$

where $(T^a)_{bc} = -if_{abc}$ for the adjoint representation

Hence

$$\begin{aligned}[\nabla^\mu, \nabla^\nu] F_{\mu\nu}^b &= f_{cab} F^{c\mu\nu} F_{b\mu\nu} \\ &= 0.\end{aligned}$$

So

$$\boxed{\nabla^\mu \nabla^\nu F_{\mu\nu} = 0}$$

and, as can be checked from the ϕ field equations, consistent with this the current must be covariantly conserved

$$(\nabla^\mu J_\mu)^a = 0.$$

So since $\nabla^\mu \bar{J}_\mu = 0 \Rightarrow$

$$\nabla^\mu \nabla^\nu F_{\mu\nu} = 0. \text{ This implies not}$$

all the A_μ^a equations are independent

thus some of the equations are constraint equations for A_μ^a . We must have a relation between the fields to determine them uniquely. That is since $\nabla^\mu \nabla^\nu F_{\mu\nu} = 0$ we cannot invert $\nabla_\mu F^{\mu\nu} = -j^\nu$

The Euler-Lagrange equations do not determine A_μ^a ; they are gauge invariant and leave $g(x)$ completely free. Hence we must specify a relation among the fields A_μ^a in order to determine the true independent degrees of freedom from the ^{arbitrary angles} gauge dependent variables. Since the relations of motion are invariant we can choose any relation among the fields as long as it determines $g(x)$ uniquely and hence allows the A_μ^a to be determined. Of course the work then comes in

expressing the dependent degrees of freedom in terms of the true ^{independent} dynamical

degrees of freedom. This is easiest to accept: $\nabla \cdot \mathbf{A} = 0$ is the Coulomb gauge

$$\partial_i A_i^a = 0.$$

(Technical point: in QED the gauge transformation of the Coulomb condition $\Rightarrow \nabla^2 \omega = 0$ and hence for $\omega \xrightarrow{x \rightarrow \infty} 0$ the Poisson eq. $\Rightarrow \omega(x) = 0$, i.e. $\partial_i A_i^a = 0$ determined $\omega(x)$ uniquely. For non-abelian groups the gauge transformation \Rightarrow

$$\partial_i (\partial_i \omega^a + f_{abc} \omega^b A_i^c) = 0$$

or
$$[\nabla_{i,c}^2 - f_{abc} A_i^b \partial_i] \omega^c = 0$$

Now in perturbation theory i.e. small A_i^b this

operator is invertible and $\omega^c = 0$ but for large fields A_i^b it is possible that the operator has ~~non~~ zero eigenvalues and is not invertible - this is called the Gribov ambiguity - the Coulomb gauge condition does not uniquely fix the gauge angles for large ~~non~~-perturbative fields. We will ignore this problem since 1) it is known how to circumvent it 2) we could choose $A_0^a = 0$ gauge which

uniquely fixes ω^a even non-perturbatively.)

So let's look more closely at the Euler-Lagrange equations, some will involve time derivatives and hence represent true dynamical evolution others will not involve time derivatives and will represent constraints among the variables. We then must solve the constraints (along with our choice of gauge) in order to eliminate the non-independent degrees of freedom from the dynamical equations. We can then express the Hamiltonian and Lagrangian in terms of these variables and hence the functions and integral representations for the Green functions.

Since it is the gauge fields that present the difficulty we can wlog set $J_\mu = 0$ and just treat the pure Yang-Mills theory. for $J_\mu \neq 0$ we can follow the same reasoning we will present in the $J_\mu = 0$ case. ✓

The Euler-Lagrange equations are

$$a) F_{\mu\nu}^a = \partial_\mu A_\nu^a - \partial_\nu A_\mu^a - f_{abc} A_\mu^b A_\nu^c$$

and

$$b) \partial^\nu F_{\mu\nu}^a - f_{abc} A^{\nu b} F_{\mu\nu}^c = 0$$

The true dynamical equations involve time derivatives and are given by $\begin{matrix} a) \mu=0, \nu=i \\ b) \mu=i, \nu=0 \end{matrix}$

$$D1) \partial_0 A_i^a = F_{0i}^a + \partial_i A_0^a + f_{abc} A_0^b A_i^c$$

$$= F_{0i}^a + (\partial_i \delta^{ac} - f_{abc} A_i^b) A_0^c$$

$$\partial_0 A_i^a = F_{0i}^a + (\nabla_i)^{ab} A_0^b$$

dynamical equations

D2)

$$\partial_0 F_{0i}^a = [\partial_j \delta^{ac} - f_{abc} A_j^b] F_{ji}^c + f_{abc} A_0^b F_{0i}^c$$

The momentum canonically conjugate to

$$A_i^a \text{ is } \frac{\partial \mathcal{L}_{inv}}{\partial \dot{A}_i^a} = + F_{0i}^a$$

However the Lagrangian L_{inv} is independent of \dot{A}_0^a and, of course, \dot{F}_{ij}^a hence they are dependent variables. We must solve their constraint equations in terms of the independent variables and substitute this in the RHS of the dynamical equations. Further we know that the gauge invariance implies that not all the F_{0i}^a can be independent and hence not all the A_i^a are independent. We use the gauge invariance to pick a gauge relation among them at equal times and it will evolve according to D1) & D2).

So first let's consider the remaining Euler-Lagrange equations a) $\mu, \nu = i, j$ and b) $\mu = 0$ above to yield the constraint equations:

constraint equations

C1) $F_{ij}^a = \partial_i A_j^a - \partial_j A_i^a - f_{abc} A_i^b A_j^c$,

this defines F_{ij}^a in terms of A_i^a at equal times.

C2) $-(\partial_i \delta^{ac} - f_{abc} A_i^b) F_{0i}^c = 0$

or

$$\nabla_i F_{0i}^a = 0$$

So again not all the F_{0i}^a are independent since these equations are not independent ($\nabla_\mu \nabla_\nu F_{\mu\nu} = 0$) this is analogous all to $\nabla \cdot \vec{E} = 0$ in QED. and hence the A_i^a cannot be treated as independent. Thus we must impose a gauge condition to relate the A_i^a . We now choose the

Coulomb gauge

$$\partial_i A_i^a = 0$$

Since \mathcal{L} is gauge invariant we can always

do this. Hence as in QED A_i^a must
be transverse. Thus the longitudinal

Component of the momentum canonically
conjugate to A_i^a is not independent,

call it F_{0i}^{aL} . Hence F_{0i}^{aL} depends

upon the other degrees of freedom

through the constraint equation (C2)

to see this we can always write
any 3-vector in terms of its longitudinal
and transverse components as

$$F_{0i}^a = F_{0i}^{aT} + F_{0i}^{aL}$$

where $\partial_i F_{0i}^a = \partial_i F_{0i}^{aL}$ i.e. $\partial_i F_{0i}^{aT} = 0$

$$\text{and } \epsilon_{ijk} \partial_j F_{0k}^a = \epsilon_{ijk} \partial_j F_{0k}^{aT}$$

$$\text{i.e. } \epsilon_{ijk} \partial_j F_{0k}^{aL} = 0$$

(i.e. $\vec{E} = \vec{\nabla}\phi + \vec{\nabla} \times \vec{A}$ for any 3-vector)

Now we must express the dependent variables A_0^a and F_{0i}^{aL} in terms of the independent variables (well F_{ij}^a is straight forward) which are the transverse components of A_i^a and F_{0i}^a (Coulomb gauge $\Rightarrow A_i^L = 0$), towards this end we express F_{0i}^a as

$$F_{0i}^{aL} \equiv -\partial_i f^a; \quad F_{0i}^{aT} \equiv E_i^a; \quad \text{that is } \boxed{F_{0i}^a = E_i^a - \partial_i f^a}$$

with $\partial_i E_i^a = 0$, E_i^a is purely transverse

So that $\partial_i F_{0i}^a = -\nabla^2 f^a$

(i.e. the 3 dimensional projectors are

$$P_{ij}^T \equiv \delta_{ij} - \frac{\partial_i \partial_j}{\nabla^2}; \quad P_{ij}^L \equiv \frac{\partial_i \partial_j}{\nabla^2}$$

$$P^T P^T = P^T; \quad P^L P^L = P^L; \quad P^L P^T = 0 = P^T P^L$$

$$P^T + P^L = 1.$$

So any vector $V_i = P_{ij}^T V_j + P_{ij}^L V_j$

$$= \underbrace{V_i^T}_{V_i^T} + \partial_i \frac{\partial_j V_j}{\nabla^2}$$

$$= V_i^T + \partial_i V^L$$

Thus

$$F_{0i}^a = -\partial_i f^a + E_i^a$$

where

$$-f^a = \frac{1}{\nabla^2} \partial_j F_{0j}^a$$

$$E_i^a = \left(\delta_{ij} - \frac{\partial_i \partial_j}{\nabla^2} \right) F_{0j}^a$$

So then E_i^a and the transverse components of A_i^a are the independent variables and they are conjugate to each other. Hence we must find A_0^a and f^a in terms of A_i^a ; E_i^a . Turning to the constraint equation (C2)

$$0 = (\partial_i \delta^{ac} - f_{abc} A_i^b) F_{0i}^c$$

$$\Rightarrow \left(\nabla^2 \delta^{ac} - f_{abc} A_i^b \partial_i \right) f^c = - f_{abc} A_i^b E_i^c$$

Now we can formally solve this equation by introducing the Coulomb Green function $D_c(x, y; A_i^a)$ such that

$$(\nabla_x^2 \delta^{ac} - f_{abc} A_i^b \partial^x_i) \mathcal{D}_c^{cd}(\vec{x}, \vec{y}; A_i^a) = \delta^{ad} \int^3 (\vec{x} - \vec{y})$$

Then we have that

$$f^a(\vec{x}, t) = \int d^3 y \mathcal{D}_c^{ab}(\vec{x}, \vec{y}; A_i^a) f_{bcd}(A_i^c, E_i^d)(\vec{y}, t)$$

Perturbatively \mathcal{D}_c^{ab} can be found by expanding in powers of A_i^a that is

in lowest order $\mathcal{D}_c = \mathcal{D}_c^{(0)} + \mathcal{D}_c^{(1)} + \dots$
 and $\mathcal{D}_c^{(0)}$ is indep. of A_i^a
 with

$$\nabla^2 \mathcal{D}_c^{(0)} = \int^3 (\vec{x} - \vec{y})$$

$$\Rightarrow \mathcal{D}_c^{(0)ab}(\vec{x}, \vec{y}) = \frac{-\delta^{ab}}{4\pi |\vec{x} - \vec{y}|} \quad \text{as}$$

in Maxwell theory.

Then
$$\nabla_x^2 \delta^{ac} \mathcal{D}_c^{cd} - f_{abc} A_i^b \partial^x_i \mathcal{D}_c^{cd} = 0$$

$$\Rightarrow \mathcal{D}_c^{(1)ab}(\vec{x}, \vec{y}; A) = \int d^3 z \mathcal{D}_c^{(0)ac}(\vec{x}, \vec{z}) (f_{cde} A_i^d \partial^z_i) \mathcal{D}_c^{(0)db}(\vec{z}, \vec{y})$$

etc. Some have

$$\mathcal{D}_c^{ab}(\vec{x}, \vec{y}; A_i^a) = \frac{-\delta^{ab}}{4\pi|\vec{x}-\vec{y}|} + \int d^3z \frac{1}{4\pi|\vec{x}-\vec{z}|} f_{acb} A_i^c(\vec{z}) \partial_i \frac{1}{4\pi|\vec{z}-\vec{y}|}$$

Hence we have f^a in terms of the independent variables.

Next we need an equation for A_0 . Taking the divergence of (D1) we find

$$\partial_0 \partial_i A_i^a = \partial_i F_{0i}^a + (\delta^{ac} \nabla^2 - f_{abc} A_i^b) A_0^c$$

Now we use the Coulomb gauge condition

$$\partial_i A_i^a = 0$$

and the decomposition of F_{0i}^a ; $\partial_i F_{0i}^a = -\nabla^2 f^a$

to obtain

$$\nabla^2 f^a = (\nabla^2 \delta^{ac} + f_{abc} A_i^b \partial_i) A_0^c$$

Again we can solve this by using the Coulomb gauge Greenfunction \mathcal{D}_C ; yielding

$$A_0^a(\vec{x}, t) = \int d^3y \mathcal{D}_C^{ab}(\vec{x}, \vec{y}, A_i^a) \nabla_y^2 f^b(\vec{y}, t)$$

So considering \mathcal{D}_C an integral operator we can write these solutions in a short hand way as

$$\begin{aligned} f^a &= \mathcal{D}_C^{ab} (f_{bcd} A_i^c E_i^c) \\ A_0^a &= \mathcal{D}_C^{ab} (\nabla^2 f^b) \end{aligned}$$

Mission accomplished we have expressed the dependent variables in terms of the independent variables. We may now construct the Hamiltonian in terms of the independent variables alone, as well as the Lagrangian.

$$\text{Hence } \mathcal{H} = E_i^a \frac{\partial A_i^a}{\partial t} - \mathcal{L}_{\text{inv}}$$

with \mathcal{L}_{inv} now written in terms of E_i^a, A_i^a only.

That is using the Euler-Lagrange eq.'s

$$\mathcal{L}_{inv} = \frac{1}{4} F_{\mu\nu}^a F^{a\mu\nu} - \frac{1}{2} F_{\mu\nu}^a (\delta^{\mu\nu} A^a - \delta^{\nu\mu} A^a - f_{abc} A^b A^c)$$

$$= -\frac{1}{4} F_{\mu\nu}^a F^{a\mu\nu}$$

$$= +\frac{1}{2} F_{0i}^a F_{0i}^a - \frac{1}{4} F_{ij}^a F_{ij}^a$$

we have the second order formulation.
Now we use the constraints to write

$$\begin{aligned} F_{ij}^a &= \partial_i A_j^a - \partial_j A_i^a - f_{abc} A_i^b A_j^c \\ &\equiv \epsilon_{ijk} B_k^a \end{aligned}$$

Hence $F_{ij}^a F_{ij}^a = \epsilon_{ijk} \epsilon_{ijl} B_k^a B_l^a = 2 B_i^a B_i^a$

and

$$F_{0i}^a F_{0i}^a = (E_i^a - \partial_i f^a)(E_i^a - \partial_i f^a)$$

So

$$\mathcal{L}_{inv} = \frac{1}{2} (E_i^a - \partial_i f^a)(E_i^a - \partial_i f^a) - \frac{1}{2} B_i^a B_i^a$$

Where we have E_i^a is transverse

$B_i^a = B_i^a(A_j^b)$ is a function of transverse A_j^b

$$\text{and } f^a = \mathcal{D}_c^{ab} (f_{bcd} A_i^c E_i^c)$$

is a function of E_i^c and A_i^c also.

Hence L is written in terms of the independent variables

thus

$$L = E_i^a \frac{\partial A_i^a}{\partial t} - \frac{1}{2} (E_i^a - \partial_i f^a) (E_i^a - \partial_i f^a) + \frac{1}{2} B_i^a B_i^a$$

Now from the Euler-Lagrange eq. (D1)

$$\frac{\partial A_i^a}{\partial t} = \partial_0 A_i^a = \pi_{0i}^a + (\partial_i \delta^{ac} - f_{abc} A_i^b) A_0^c$$

using the definition π_{0i}^a and constraint equation for A_0^a

$$= E_i^a - \partial_i f^a + (\partial_i \delta^{ac} - f_{abc} A_i^b) \mathcal{D}_c^{cd} \nabla^2 f^d$$

$$\partial_0 A_i^a = E_i^a - \left[\partial_i \delta^{ad} - (\partial_i \delta^{ac} - f_{abc} A_i^b) \mathcal{D}_c^{cd} \nabla^2 \right] f^d$$

As a check since A_i^a is transverse and E_i^a is transverse the $[\]$ must be transverse.

$$\begin{aligned} & \partial_i [\partial_i \delta^{ad} - (\partial_i \delta^{ac} - f_{abc} A_i^b) \partial_c^{\text{cd}} \nabla^2] \\ &= [\nabla^2 \delta^{ad} - (\nabla^2 \delta^{ac} - f_{abc} A_i^b \partial_i) \partial_c^{\text{cd}} \nabla^2] \end{aligned}$$

but the Coulomb Green function is defined by

$$(\nabla^2 \delta^{ac} - f_{abc} A_i^b \partial_i) \partial_c^{\text{cd}} = \delta^{ad} \mathbb{1}$$

hence $\partial_i \{ \} = 0$ and is transverse.

So

$$\begin{aligned} \int d^3x E_i^a \partial_0 A_i^a &= \int d^3x [E_i^a E_i^a - E_i^a \partial_i f^a \\ &+ E_i^a \partial_i \partial_c^{\text{cd}} \nabla^2 f^d - f_{abc} E_i^a A_i^b \partial_c^{\text{cd}} \nabla^2 f^d] \end{aligned}$$

Now integrate by parts and throw away surface terms using the fact that E_i^a is transverse $\partial_i E_i^a = 0$ we have

$$\int d^3x E_i^a \partial_0 A_i^a = \int d^3x [E_i^a E_i^a - f_{abc} E_i^a A_i^b \partial_c^{\text{cd}} \nabla^2 f^d]$$

Now using the constraint eq. (C2)

$$(\nabla^2 \delta^{ac} - f_{abc} A_i^b \partial_i) f^c = f_{abc} A_i^b E_i^c$$

we have

$$\begin{aligned} & - f_{abc} E_i^a A_i^b \partial_c^{\text{cd}} \nabla^2 f^d \\ &= - (\nabla^2 \delta^{cf} - f_{cef} A_i^e \partial_i) f^f \partial_c^{\text{cd}} \nabla^2 f^d \\ &= - (\nabla^2 f^c) \partial_c^{\text{cd}} \nabla^2 f^d + f_{cef} A_i^e (\partial_i f^f) \partial_c^{\text{cd}} \nabla^2 f^d \end{aligned}$$

So integrate by parts using $\partial_i A_i^e = 0$

$$\begin{aligned} & - \int d^3x f_{abc} E_i^a A_i^b \partial_c^{\text{cd}} \nabla^2 f^d \\ &= \int d^3x - \left[f^c (\nabla^2 \partial_c^{\text{cd}}) \nabla^2 f^d + f^f (f_{cef} A_i^e \partial_i \partial_c^{\text{cd}} \nabla^2 f^d) \right] \end{aligned}$$

$$= \int d^3x - \left[f^a (\nabla^2 \delta^{ad} - f_{abc} A_i^b \partial_i) \partial_c^{\text{cd}} \right] \nabla^2 f^d$$

using the Coulomb Green function eq. \Rightarrow

$$= \int d^3x - (f^a \nabla^2 f^a) = + \int d^3x (\partial_i f^a) (\partial_i f^a)$$

Hence

$$\int d^3x E_i^a \delta A_i^a = \int d^3x [E_i^a E_i^a + (\delta_i f^a)(\delta_i f^a)]$$

So the Hamiltonian written in terms of the independent degrees of freedom, becomes after another integration by parts

$$H = \int d^3x \left[\frac{1}{2} E_i^a E_i^a + \frac{1}{2} B_i^a B_i^a + \frac{1}{2} (\delta_i f^a)(\delta_i f^a) \right]$$

This is similar to the Hamiltonian we found in Coulomb gauge QED where $\int d^3x \frac{1}{2} (\delta_i f^a)^2$ is like the instantaneous Coulomb interaction which occurred there.

Finally we would like to apply our path integral representation of the generating functional to this case. Since we have been treating A_i^a and E_i^a as independent fields in our 1st order formalism we must integrate over both of them with the usual exponential of the action in terms of them times i , we also include a source term for A_i^a (we could include a E_i^a source term but there is no

need to do so) thus

$$Z[j_i^a] = \int [dE_i^a][dA_i^a] e^{i \int d^4x [L_{inv} - j_i^a A_i^a]}$$

$$= \int [dE_i^a][dA_i^a] e^{i \int d^4x [\frac{1}{2} E_i^a E_i^a + \frac{1}{2} (\partial_i^a)^2 A_i^a$$

$$- \frac{1}{2} B_i^a B_i^a - j_i^a A_i^a]}$$

$$= \int [dE_i^a][dA_i^a] e^{i \int d^4x [E_i^a \partial_0 A_i^a - \frac{1}{2} E_i^a E_i^a$$

$$- \frac{1}{2} B_i^a B_i^a - \frac{1}{2} (\partial_i^a)^2 A_i^a]$$

$$- j_i^a A_i^a]}$$

$$Z[j_i^a] = \int [dE_i^a][dA_i^a] e^{i \int d^4x [E_i^a \partial_0 A_i^a - \frac{1}{2} E_i^a E_i^a - \frac{1}{2} B_i^a B_i^a - \frac{1}{2} (\partial_i^a)^2 A_i^a - j_i^a A_i^a]}$$

where we see that this is written in the form of the phase space path integral, this is an integral over the momenta and the conjugate coordinates of the exponential it times the Lagrangian. and since A_i^a is transverse so is j_i^a .

$$\partial_i j_i^a = 0.$$

(Aside: Recall for scalar field theory)

$$Z[J] = \int [d\phi] e^{i \int d^4x [\mathcal{L}(\phi, \partial\mu\phi) + \mathcal{J}\phi]}$$

Now if \mathcal{L} is quadratic in $\partial\mu\phi$ i.e. $\mathcal{L} = \frac{1}{2} \partial_\mu\phi \partial^\mu\phi - V(\phi)$ then we can introduce a gaussian integral over the momentum π i.e.

$$\int [d\pi] e^{i \int d^4x [\pi \dot{\phi} - \frac{1}{2} \pi^2]} = e^{+\frac{i}{2} \int d^4x \dot{\phi} \ddot{\phi}}$$

So $e^{i \int d^4x [\mathcal{L} + \mathcal{J}\phi]} = e^{i \int d^4x [\frac{1}{2} \dot{\phi}^2 - \frac{1}{2} \vec{\nabla}\phi \cdot \vec{\nabla}\phi - V(\phi) + \mathcal{J}\phi]}$

$$= \int [d\pi] e^{i \int d^4x [\pi \dot{\phi} - \frac{1}{2} \pi^2 - \frac{1}{2} \vec{\nabla}\phi \cdot \vec{\nabla}\phi - V(\phi) + \mathcal{J}\phi]}$$

$$= \int [d\pi] e^{i \int d^4x [\pi \dot{\phi} - \mathcal{H}(\pi, \phi) + \mathcal{J}\phi]}$$

hence

$$Z[J] = \int [d\pi] [d\phi] e^{i \int d^4x [\pi \dot{\phi} - \mathcal{H}(\pi, \phi) + \mathcal{J}\phi]}$$

This can be derived from first principles directly and is the most general form for the path integral quantization of a theory i.e. this

is true for all Hamiltonians written in terms of the independent dynamical degrees of freedom and their conjugate momenta.

Now we would like to re-express the integral in various ways; ~~by doing this~~ let it be made explicit that A_i^a and E_i^a are transverse by putting a superscript T rather than S .

$$Z[j_i^a] = \int [dE_i^{at}] [dA_i^{at}] \times$$

$$\times e^{i \int d^4x [E_i^{at} \cdot \partial_0 A_i^{at} - \mathcal{H}(E_i^{at}, A_i^{at}) - j_i^a A_i^a]}$$

where it is understood that B_i^a and f_i^a depend on A_i^{at} and E_i^{at} through their constraint equations.

It is difficult to integrate over the transversely constrained fields, so we will relax the constraint by integrating over all fields and put a δ functional for the transverse condition.

Then we introduce the dummy variable E^{aL}

$$\int [dE_i^{aT}] = \int [dE_i^{aT}] [dE^{aL}] \delta[E^{aL}]$$

where we introduce 3 independent components of the field E_i^a by

$$E_i^a \equiv \left(\delta_{ij} - \frac{\partial_i \partial_j}{\nabla^2} \right) E_j^{aT} + \frac{\partial_i}{\nabla^2} E^{aL}$$

Then

$$\partial_i E_i^a = E^{aL}$$

the longitudinal part of E_i^a

So

$$\int [dE_i^{aT}] = \int [dE_i^a] \delta[\partial_i E_i^a] J$$

where J is the jacobian in going from an integral over the three variables

$\{E_i^{aT}, E^{aL}\}$ to the three independent variables $\{E_i^a\}$. So we have that

$$\begin{aligned}
 [dE_i^a] &= \left| \frac{\delta E_i^a}{\delta(E_j^{bT}, E_j^{bL})} \right| [dE_i^{aT}] [dE_i^{aL}] \\
 &= \det \left(\frac{\vec{\nabla}}{\nabla^2} \right) [dE_i^{aT}] [dE_i^{aL}]
 \end{aligned}$$

Since $\det \left(\frac{\vec{\nabla}}{\nabla^2} \right)$ is just a ∞ constant independent of the fields, it cancels from our normalized factors and can be ignored. We can do the same for A_i^{aT} hence

$$\begin{aligned}
 Z[j_i^a] &= \int [dE_i^a] [dA_i^a] \delta[\partial_i E_i^a] \delta[\partial_i A_i^a] \times \\
 &\times e^{i \int d^4x \left[E_i^a \partial_0 A_i^a - \frac{1}{2} E_i^a E_i^a - \frac{1}{2} B_i^a B_i^a \right.} \\
 &\quad \left. - \frac{1}{2} (\partial_i f^a)(\partial_i f^a) - j_i^a A_i^a \right]
 \end{aligned}$$

Thus we have obtained the generating functional for the Yang-Mills theory in the Coulomb gauge. We could

use this formula to develop a perturbation expansion in the strength of A_i^a i.e. rescale A_i^a & E_i^a by g , the gauge coupling constant, then we could expand in g . Of course the Green functions will not be Lorentz covariant and hence the Lorentz invariance of the S-matrix will not be obvious (manifest) until all contributions to a particular order in perturbation theory are summed up. These Coulomb gauge Feynman rules are not a useful set of rules in which to calculate. Their use is in the fact that we have rigorously derived the functional integral representation for $Z[J_i^a]$ from first principles in the Coulomb gauge. Since the S-matrix is gauge invariant and Lorentz invariant we should be able to find a more Lorentz invariant form for the generating functional.

Towards this end we now would like to introduce as dummy variables the fields we eliminated by their constraint equations.

First in the above integral we have that

$$f^a = -D_c^{ab} (f^{bcd} A_i^c E_i^c)$$

So we can introduce the dummy variable f^a by the integral

$$I = \int [df^a] \delta [f^a + D_c^{ab} f^{bcd} A_i^c E_i^c]$$

Alternatively we can use the constraint equation f^a obeys p.-535-

$$[\nabla^2 \delta^{ac} - f^{abc} A_i^b \partial_i] f^c = f^{abc} A_i^b E_i^c$$

and the Green function equation

$$[\nabla^2 \delta^{ac} - f^{abc} A_i^b \partial_i] D_c^{ed} = \delta^{ad}$$

to write the δ -functional as

$$\begin{aligned} & \delta [(\nabla^2 \delta^{ac} - f^{abc} A_i^b \partial_i) f^c + f^{abc} A_i^b E_i^c] \\ &= \delta [(\nabla^2 \delta^{ac} - f^{abc} A_i^b \partial_i) [f^c + D_c^{cd} f^{def} A_i^e E_i^f]] \\ &= \frac{1}{\det[\nabla^2 \delta^{ac} - f^{abc} A_i^b \partial_i]} \delta [f^a + D_c^{ab} f^{bcd} A_i^c E_i^d] \end{aligned}$$

Thus

$$1 = \int [d f^a] (\det M_c) \delta \left[(\nabla^2 \delta^{ac} - f_{abc} A_i^b \partial_i) f^c + f_{abc} A_i^b E_i^c \right]$$

where

$$M_c^{ac}(x, y) \equiv (\nabla^2 \delta^{ac} - f_{abc} A_i^b \partial_i) \delta^4(x-y)$$

Hence we have

$$Z[j_i^a] = \int [d E_i^a] [d A_i^a] [d f^a] (\det M_c) \times$$

$$\begin{aligned} & \times \delta \left[\partial_i E_i^a \right] \delta \left[\partial_i A_i^a \right] \delta \left[(\nabla^2 \delta^{ac} - f_{abc} A_i^b \partial_i) f^c + f_{abc} A_i^b E_i^c \right] \\ & \times e^{\int d^4 x \left[E_i^a \partial_0 A_i^a - \frac{1}{2} (E_i^a E_i^a + B_i^a B_i^a + (\partial_i f^a)(\partial_i f^a)) \right.} \\ & \quad \left. - j_i^a A_i^a \right] \end{aligned}$$

We next would like to change variables from E_i^a to F_{0i}^a So define

$$F_{0i}^a \equiv E_i^a - \partial_i f^a$$

Then

$$[dE_i^a] [df^a] \delta[\partial_i E_i^a] \delta[(\nabla^2 \delta^{ac} - f_{abc} A_i^b \partial_i) f^c + f_{abc} A_i^b E_i^c]$$

$$= [dF_{0i}^a] [df^a] \delta[\partial_i F_{0i}^a + \nabla^2 f^a] \times$$

$$\times \delta[\nabla^2 f^a + \underbrace{f_{abc} A_i^b (E_i^c - \partial_i f^c)}_{F_{0i}^c}]$$

$$= [dF_{0i}^a] [df^a] \delta[\partial_i F_{0i}^a + \nabla^2 f^a] \delta[\nabla^2 f^a + f_{abc} A_i^b F_{0i}^c]$$

$$= [dF_{0i}^a] [df^a] \delta[\partial_i F_{0i}^a - f_{abc} A_i^b F_{0i}^c] \times$$

$$\times \delta[\nabla^2 f^a + f_{abc} A_i^b F_{0i}^c]$$

in addition the exponent of the integral becomes

$$\int d^4x [E_i^a \partial_0 A_i^a - \frac{1}{2} (E_i^a E_i^a + B_i^a B_i^a + (\partial_i f^a)(\partial_i f^a))]$$

$$= \int d^4x [F_{0i}^a \partial_0 A_i^a + \partial_i f^a \partial_0 A_i^a - \frac{1}{2} B_i^a B_i^a$$

$$- \frac{1}{2} (F_{0i}^a F_{0i}^a) + \partial_i f^a E_i^a]$$

also using the definition of B_i^a p. -539- we have

$$\frac{1}{2} B_i^a B_i^a = \frac{1}{4} (\partial_i A_j^a - \partial_j A_i^a + f_{abc} A_i^b A_j^c)^2$$

The integral becomes

$$\begin{aligned} Z[j_i^a] &= \int [dF_{0i}^a] [dA_i^a] [df^a] \delta[\nabla^2 f^a + f_{abc} A_i^b F_{0i}^c] \\ &\times (\det M_c) \times \delta[\partial_i F_{0i}^a - f_{abc} A_i^b F_{0i}^c] \delta[\partial_i A_i^a] \\ &\int dx^4 \left[F_{0i}^a \partial_0 A_i^a - \frac{1}{2} (F_{0i}^a F_{0i}^a) - \frac{1}{4} (\partial_i A_j^a - \partial_j A_i^a + f_{abc} A_i^b A_j^c) \right. \\ &\left. - j_i^a A_i^a \right] \end{aligned}$$

where we used integration by parts and transversality of F_i^a, A_i^a , i.e. the δ -functionals $\Rightarrow \partial_i F_i^a = 0 = \partial_i A_i^a$!

Now f^a appears only in the δ -functional

hence we can do the f^a integral to obtain simply $\frac{1}{\det \nabla^2}$. As usual this is

a field independent (or) constant that cancels in the normalization; hence we ignore it.

So we have

$$Z[j_i^a] = \int [dF_{0i}^a] [dA_i^a] (\det M_c) \delta[\partial_i A_i^a] \times$$

$$\times \delta[\partial_i F_{0i}^a - f_{abc} A_i^b F_{0i}^c] \times$$

$$\times e^{i \int d^4x [F_{0i}^a \partial_0 A_i^a - \frac{1}{2} (F_{0i}^a)^2 - \frac{1}{4} (\partial_i A_j^a - \partial_j A_i^a - f_{abc} A_i^b A_j^c)^2 - j_i^a A_i^a]}$$

finally we can represent the ^{second} functional δ by means of a Functional Fourier transform with integration variable A_0^a

$$\delta[\partial_i F_{0i}^a + f_{abc} A_i^b F_{0i}^c] = \int [dA_0^a] e^{i \int d^4x [A_0^a (\partial_i F_{0i}^a - f_{abc} A_i^b F_{0i}^c)]}$$

integrating by parts this becomes

$$= \int [dA_0^a] e^{i \int d^4x F_{0i}^a (-\partial_i A_0^a - f_{abc} A_0^b A_i^c)}$$

in addition we can write the B_i^a term in terms of a Gaussian integral over dummy variable F_{ij}^a

$$\int [dF_{ij}^a] e^{i \int d^4x \left[\frac{1}{4} F_{ij}^a F_{ij}^a - \frac{1}{2} F_{ij}^a (\partial_i A_j^a - \partial_j A_i^a - f_{abc} A_i^b A_j^c) \right]}$$

$$= e^{i \int d^4x \left[-\frac{1}{4} (\partial_i A_j^a - \partial_j A_i^a - f_{abc} A_i^b A_j^c)^2 \right]}$$

Putting this altogether we obtain

$$Z[j_i^a] = \int [dF_{0i}^a] [dF_{ij}^a] [dA_i^a] [dA_0^a] (\det M_c) \delta[\partial_i A_i^a] \times$$

$$\times e^{i \int d^4x \left[-\frac{1}{2} F_{0i}^a F_{0i}^a + \frac{1}{4} F_{ij}^a F_{ij}^a - \frac{1}{2} F_{ij}^a (\partial_i A_j^a - \partial_j A_i^a - f_{abc} A_i^b A_j^c) \right.}$$

$$\left. + F_{0i}^a (\partial_0 A_i^a - \partial_i A_0^a - f_{abc} A_0^b A_i^c) - j_i^a A_i^a \right]}$$

Grouping terms this becomes

$$Z[j_i^a] = \int [dF_{\mu\nu}^a] [dA_\mu^a] (\det M_c) \delta[\partial_i A_i^a] \times$$

$$\times e^{i \int d^4x \left[+\frac{1}{4} F_{\mu\nu}^a F^{\mu\nu a} - \frac{1}{2} F_{\mu\nu}^a (\partial_\mu A_\nu^a - \partial_\nu A_\mu^a - f_{abc} A_\mu^b A_\nu^c) \right.}$$

$$\left. - j_i^a A_i^a \right]}$$

Now this is just the exponent of the action with the additional $\delta \text{ad det}$. With the understanding that $j_0^a = 0$ we can write this as

$$Z[j_\mu^a] = \int [dA_\mu^a] [dF_{\mu\nu}^a] (\det M_c) \delta[D_i A_i^a] \times e^{i \int d^4x [\mathcal{L}_{\text{inv}}(A, F) + j_\mu^a A^{a\mu}]}$$

Since M_c is independent of F and $\mathcal{L}_{\text{inv}}(A, F)$ is Gaussian in F we can perform the F integral to obtain the second order formulated Lagrangian in the exponent

$$Z[j_\mu^a] = \int [dA_\mu^a] (\det M_c) \delta[D_i A_i^a] \times e^{i \int d^4x [\mathcal{L}_{\text{inv}}(A) + j_\mu^a A^{a\mu}]}$$

where

$$\mathcal{L}_{\text{inv}}(A) = -\frac{1}{4} F_{\mu\nu}^a F^{a\mu\nu}$$

with $F_{\mu\nu}^a = \partial_\mu A_\nu^a - \partial_\nu A_\mu^a - f_{abc} A_\mu^b A_\nu^c$

Thus we have derived the Faddeev-Popov form of the functional integral representation of the generating functional in the Coulomb gauge.

Note that the gauge variator of the Coulomb gauge condition is

$$\begin{aligned} \delta_Q(\omega) \partial_i A_i^a &= \partial_i (\partial_i \omega^a + f_{abc} \omega^b A_i^c) \\ &= (\nabla^2 \delta^{ac} - f_{abc} A_i^b) \omega^c \\ &= \int d^4y M_c^{ac}(x,y;A) \omega^c(y) \end{aligned}$$

This is just the operator necessary to guarantee that only one A_μ^a from each gauge orbit is chosen by the Coulomb gauge condition. Hence we have obtained the same integral representation for Z as we did in our intuitive approach.