

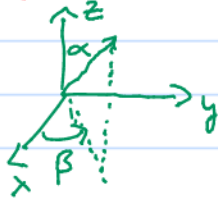
$$\langle \hat{S}_z \rangle = \mathcal{X}^\dagger \underline{S}_z \mathcal{X} = \begin{pmatrix} \cos(\frac{\alpha}{2}) & \sin(\frac{\alpha}{2})e^{-i\beta} \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \cos(\frac{\alpha}{2}) \\ \sin(\frac{\alpha}{2})e^{i\beta} \end{pmatrix}$$

$$= \cos^2(\frac{\alpha}{2}) - \sin^2(\frac{\alpha}{2}) = \cos(\alpha)$$

$$\langle \hat{S}_x \rangle = \begin{pmatrix} \cos(\frac{\alpha}{2}) & \sin(\frac{\alpha}{2})e^{-i\beta} \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \cos(\frac{\alpha}{2}) \\ \sin(\frac{\alpha}{2})e^{i\beta} \end{pmatrix}$$

$$= \cos(\frac{\alpha}{2})\sin(\frac{\alpha}{2})(e^{i\beta} + e^{-i\beta}) = \sin(\alpha)\cos(\beta)$$

$$\langle \hat{S}_y \rangle = \cos(\frac{\alpha}{2})\sin(\frac{\alpha}{2})(-ie^{i\beta} + ie^{-i\beta}) = \sin(\alpha)\sin(\beta)$$



Now add the time dependence

$$\mathcal{X}(t) = e^{i\gamma} \begin{pmatrix} \cos(\frac{\alpha}{2})e^{i\gamma B_0 t/2} \\ \sin(\frac{\alpha}{2})e^{i\beta}e^{-i\gamma B_0 t/2} \end{pmatrix} = e^{i(\gamma + \gamma B_0 t/2)} \begin{pmatrix} \cos(\frac{\alpha}{2}) \\ \sin(\frac{\alpha}{2})e^{i(\beta - \gamma B_0 t)} \end{pmatrix}$$

$$\langle S_z \rangle = \cos(\alpha) \quad \langle S_x \rangle = \sin(\alpha)\cos(\beta - \gamma B_0 t) \quad \langle S_y \rangle = \sin(\alpha)\sin(\beta - \gamma B_0 t)$$

Why doesn't $\langle S_z \rangle$ change? Why doesn't tilt change?
What does this motion look like?

Look at the book discussion of Stern Gerlach experiment.

How to write the state when there are 2 or more particles with spin?
Two particles S_1, S_2 will have joint states

$$|S_1 M_{S_1}, S_2 M_{S_2}\rangle = |S_1 M_{S_1}\rangle |S_2 M_{S_2}\rangle$$

These are rarely eigenstates of \hat{H}

One of the more common forms of interaction is proportional to $\vec{S}_1 \cdot \vec{S}_2$

$$\text{This can be written as } \vec{S}_1 \cdot \vec{S}_2 = \frac{1}{2} [(\vec{S}_1 + \vec{S}_2)^2 - \vec{S}_1^2 - \vec{S}_2^2]$$

Instead of using eigenstates of $\vec{S}_1^2, S_{1z}, \vec{S}_2^2, S_{2z}$ use the eigenstates of $\vec{S}_1^2, \vec{S}_2^2, \vec{S}^2, S_z$

$$\vec{S} \equiv \vec{S}_1 + \vec{S}_2 \quad S_z = S_{1z} + S_{2z}$$

In classical mechanics, the \vec{S}_1 and \vec{S}_2 can be in any direction. The $\max |\vec{S}_1 + \vec{S}_2| = |\vec{S}_1| + |\vec{S}_2|$ and the $\min |\vec{S}_1 + \vec{S}_2| = ||\vec{S}_1| - |\vec{S}_2||$

In Q.M. the allowed eigenvalues of \vec{S}^2 are $\hbar^2 S(S+1)$ with $S_1 + S_2, S_1 + S_2 - 1, \dots, |S_1 - S_2|$

Example: Spin $\frac{5}{2}$ and spin $\frac{3}{2}$ Count states

Total number of $\frac{5}{2}$ states $2 \cdot \frac{5}{2} + 1 = 6$

" " " $\frac{3}{2}$ " $2 \cdot \frac{3}{2} + 1 = 4$

" " " states = $6 \cdot 4 = 24$

Total number of $\frac{5}{2} + \frac{3}{2} = 4$ states $2 \cdot 4 + 1 = 9$

" " " $\frac{5}{2} + \frac{3}{2} - 1 = 3$ " $2 \cdot 3 + 1 = 7$

" " " $\frac{5}{2} + \frac{3}{2} - 2 = 2$ " $2 \cdot 2 + 1 = 5$

" " " $\frac{5}{2} - \frac{3}{2} = 1$ " $2 \cdot 1 + 1 = 3$

sum = 24 states

Strategy for finding all of the eigenstates of \vec{S}^2 and S_z

① The state with $m_{s_1} = s_1$ and $m_{s_2} = s_2$ must be $S = S_1 + S_2, M_s = S$

② Act on that state with $\hat{S}_- / (\hbar A_{s_1 m_1})$. This must be $S = S_1 + S_2, M_s = S - 1$

③ Do $\hat{S}_- / (\hbar A_{s_1 m_1})$ This must be $S = S_1 + S_2, M_s = S - 2$

etc until you've got $S = S_1 + S_2, M_s = -S$

④ The $S = S_1 + S_2 - 1, M_s = S_1 + S_2 - 1$ state must be the state orthogonal to the $S = S_1 + S_2, M_s = S_1 + S_2 - 1$ state

⑤ Apply the $\hat{S}_- / (\hbar A_{s_1 m_1})$ to this state to get $S = S_1 + S_2 - 1, M_s = S_1 + S_2 - 2$

etc

⑥ The $S = S_1 + S_2 - 2, M_s = S_1 + S_2 - 2$ must be orthogonal to the states $S = S_1 + S_2, M_s = S_1 + S_2 - 2$ and $S = S_1 + S_2 - 1, M_s = S_1 + S_2 - 2$ states.

etc

Example: Spin 1 and spin $\frac{1}{2}$

$$|\frac{3}{2}, \frac{3}{2}\rangle = |1, 1\rangle |\frac{1}{2}, \frac{1}{2}\rangle$$

$$|\frac{3}{2}, \frac{1}{2}\rangle = \frac{1}{\sqrt{2}}(S_{1-} + S_{2-}) |1, 1\rangle |\frac{1}{2}, \frac{1}{2}\rangle / \sqrt{(\frac{15}{4} - \frac{3}{4})} = \sqrt{\frac{2}{3}} |1, 0\rangle |\frac{1}{2}, \frac{1}{2}\rangle + \sqrt{\frac{1}{3}} |1, 1\rangle |\frac{1}{2}, -\frac{1}{2}\rangle$$

⋮

$$|\frac{1}{2}, \frac{1}{2}\rangle = \sqrt{\frac{1}{3}} |1, 0\rangle |\frac{1}{2}, \frac{1}{2}\rangle + \sqrt{\frac{2}{3}} |1, 1\rangle |\frac{1}{2}, -\frac{1}{2}\rangle$$

You can look up these coefficients

$$|S, M_S\rangle = \sum_{M_1, M_2, S} |S_1, M_{1S}\rangle |S_2, M_{2S}\rangle \langle S_1, M_{1S}, S_2, M_{2S} | S, M_S\rangle \quad M_{1S} + M_{2S} = M_S$$

The $\langle j_1, m_1, j_2, m_2 | j, m\rangle$ are Clebsch Gordon coefficients

Book notation $C_{m_1, m_2, m}^{S_1, S_2, S} = \langle S_1, m_1, S_2, m_2 | S, m\rangle$

Show how to read the C.G. table

Example: $S_1 = \frac{3}{2}$ $S_2 = 1$

$$|\frac{5}{2}, \frac{5}{2}\rangle = |\frac{3}{2}, \frac{3}{2}\rangle |1, 1\rangle$$

$$|\frac{5}{2}, \frac{3}{2}\rangle = \sqrt{\frac{2}{5}} |\frac{3}{2}, \frac{3}{2}\rangle |1, 0\rangle + \sqrt{\frac{3}{5}} |\frac{3}{2}, \frac{1}{2}\rangle |1, 1\rangle$$

$$|\frac{3}{2}, \frac{3}{2}\rangle = \sqrt{\frac{3}{5}} |\frac{3}{2}, \frac{3}{2}\rangle |1, 0\rangle - \sqrt{\frac{2}{5}} |\frac{3}{2}, \frac{1}{2}\rangle |1, 1\rangle$$

$$|\frac{5}{2}, \frac{1}{2}\rangle = \sqrt{\frac{1}{10}} |\frac{3}{2}, \frac{3}{2}\rangle |1, -1\rangle + \sqrt{\frac{6}{10}} |\frac{3}{2}, \frac{1}{2}\rangle |1, 0\rangle + \sqrt{\frac{3}{10}} |\frac{3}{2}, -\frac{1}{2}\rangle |1, 1\rangle$$

$$|\frac{3}{2}, \frac{1}{2}\rangle = \sqrt{\frac{6}{15}} |\frac{3}{2}, \frac{3}{2}\rangle |1, -1\rangle + \sqrt{\frac{1}{15}} |\frac{3}{2}, \frac{1}{2}\rangle |1, 0\rangle - \sqrt{\frac{8}{15}} |\frac{3}{2}, -\frac{1}{2}\rangle |1, 1\rangle$$

$$|\frac{1}{2}, \frac{1}{2}\rangle = \sqrt{\frac{3}{6}} |\frac{3}{2}, \frac{3}{2}\rangle |1, -1\rangle - \sqrt{\frac{2}{6}} |\frac{3}{2}, \frac{1}{2}\rangle |1, 0\rangle + \sqrt{\frac{1}{6}} |\frac{3}{2}, -\frac{1}{2}\rangle |1, 1\rangle$$

Schematic of fine structure and hyperfine structure in H

$$2s \text{ --- } \begin{matrix} \text{--- } F=1 \\ \text{--- } F=0 \end{matrix} \quad 2p \text{ --- } \begin{matrix} \text{--- } J=\frac{3}{2} & \text{--- } F=\frac{2}{2} \\ \text{--- } J=\frac{1}{2} & \text{--- } F=\frac{1}{2} \end{matrix} \quad \begin{matrix} \vec{J} = \vec{L} + \vec{S}_e \\ \vec{F} = \vec{J} + \vec{S}_p \end{matrix} \quad \begin{matrix} \text{Fine} \\ \text{Hyperfine} \end{matrix}$$

$$1s \text{ --- } \begin{matrix} \text{--- } F=1 \\ \text{--- } F=0 \end{matrix} \quad \boxed{1420 \text{ MHz}} \rightarrow 21 \text{ cm line} \\ \text{astrophysics}$$

Example: Energy splittings when $\hat{H} = \epsilon_0 \vec{S}_1 \cdot \vec{S}_2 / \hbar^2$

$$\vec{S}_1 \cdot \vec{S}_2 = \frac{1}{2} (\vec{S}^2 - \vec{S}_1^2 - \vec{S}_2^2)$$

$$E_s = \frac{\epsilon_0}{2} [S(S+1) - s_1(s_1+1) - s_2(s_2+1)]$$

$$S = |s_1 - s_2|, |s_1 - s_2| + 1, \dots \\ \dots, s_1 + s_2 - 1, s_1 + s_2$$

For H ground state $S=1$ and 0

$$E_1 - E_0 = (\epsilon_0/2) [1 \cdot 2 - \frac{3}{4} - \frac{3}{4}] - (\epsilon_0/2) [0 \cdot 1 - \frac{3}{4} - \frac{3}{4}] = \epsilon_0 = h \cdot 1420 \text{ MHz}$$

34. CLEBSCH-GORDAN COEFFICIENTS, SPHERICAL HARMONICS, AND d FUNCTIONS

Note: A square-root sign is to be understood over every coefficient, e.g., for $-8/15$ read $-\sqrt{8/15}$.

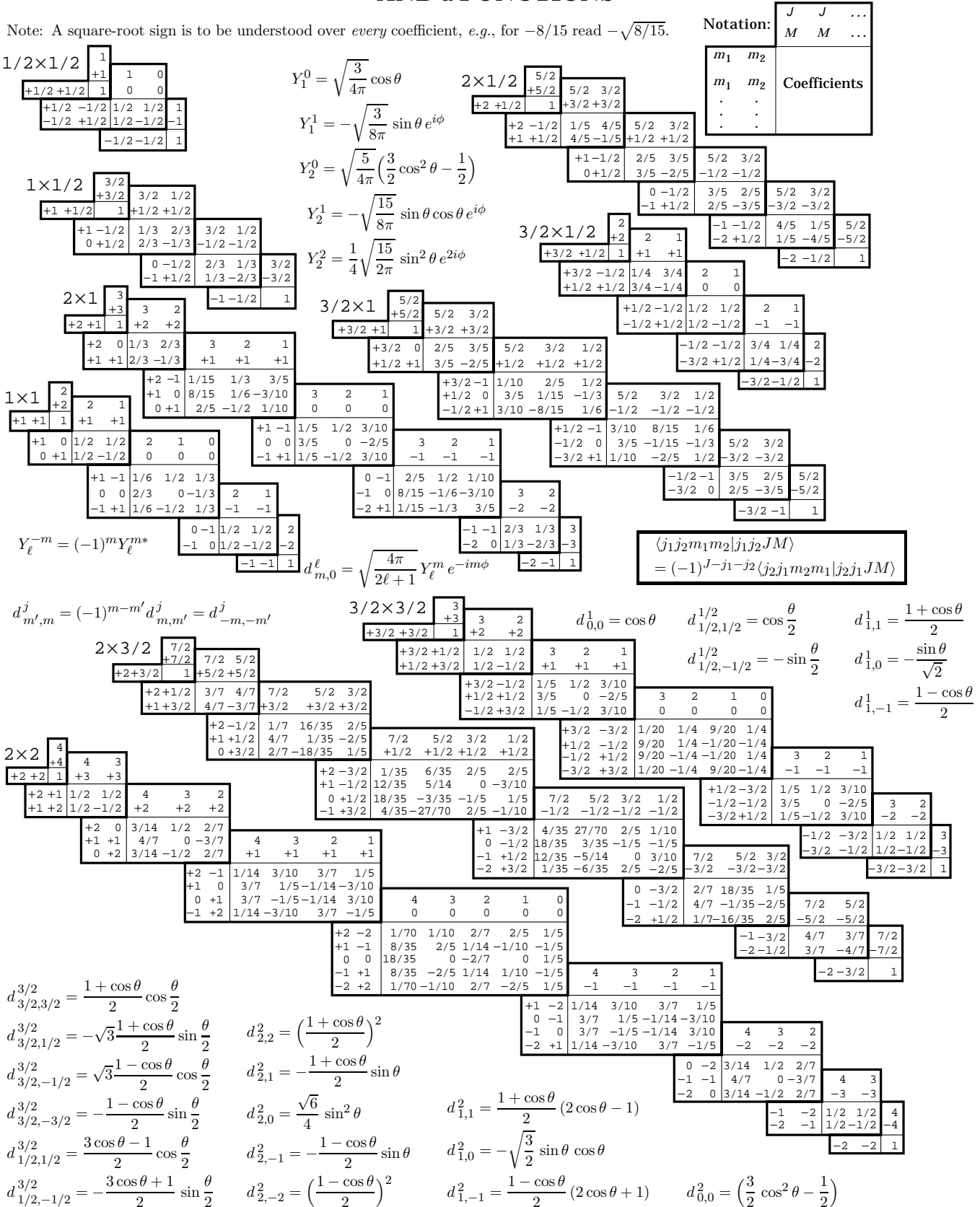


Figure 34.1: The sign convention is that of Wigner (*Group Theory*, Academic Press, New York, 1959), also used by Condon and Shortley (*The Theory of Atomic Spectra*, Cambridge Univ. Press, New York, 1953), Rose (*Elementary Theory of Angular Momentum*, Wiley, New York, 1957), and Cohen (*Tables of the Clebsch-Gordan Coefficients*, North American Rockwell Science Center, Thousand Oaks, Calif., 1974). The coefficients here have been calculated using computer programs written independently by Cohen and at LBNL.